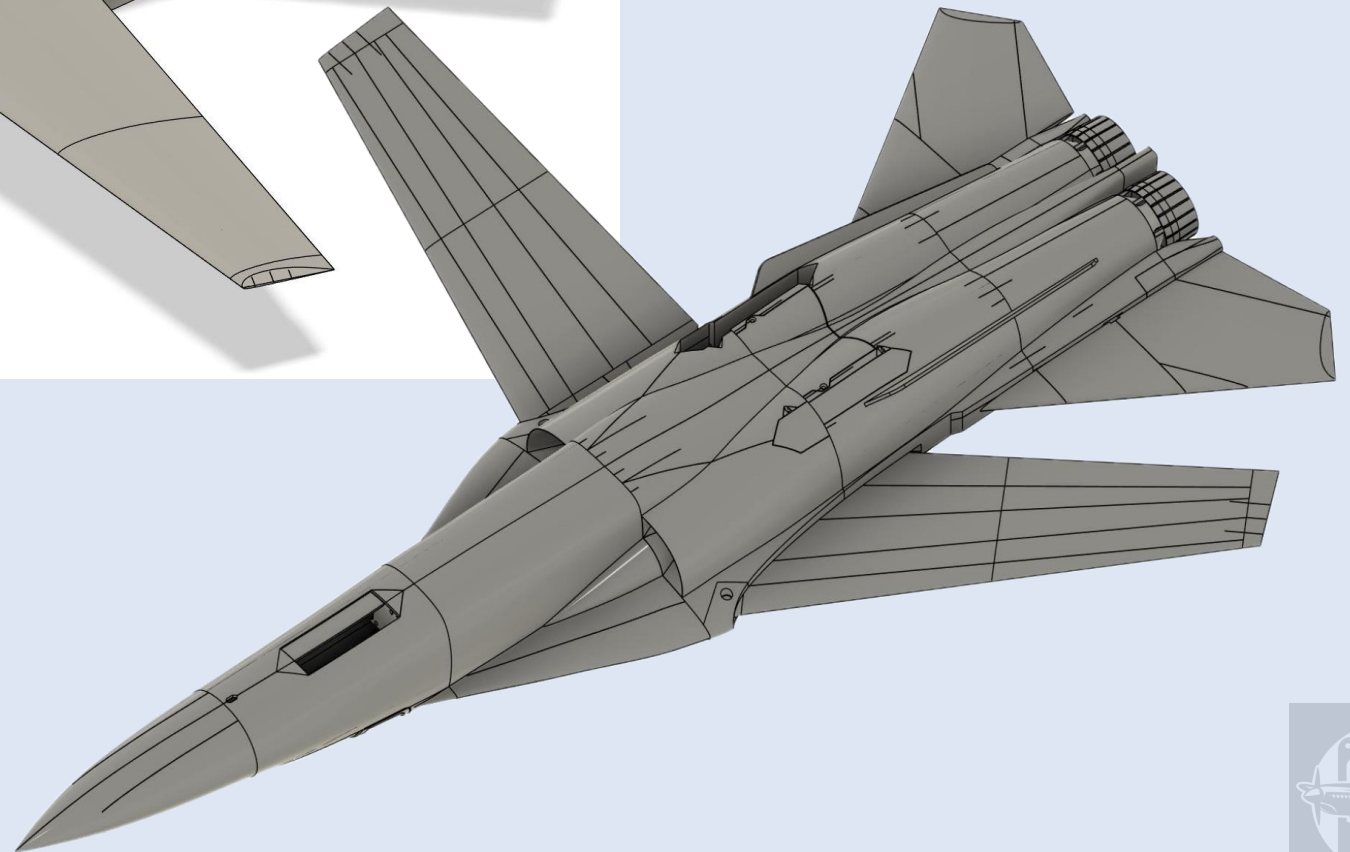


# **F-111 Aardvark**

## **3D Printed RC EDF Model**

### **Build Manual**



# SPECS



- 1200mm span (47in)
- 1350mm length
- 64mm EDF unit
- Servo driven Swing-Wing mechanism
- Elevon control w/ optional Rudder
- 2 Versions included
  - No undercarriage : ~1kg AUW
  - With Undercarriage : ~1.7kg AUW
- LW-PLA for most of model, PLA+ for select
- Optimised for Spiral / Vase print mode

## Notes

- Suits 3D Printer with minimum Bed size of approx; 220mm square or 300mm round (Check *SmallerBed* folder for possible alternate STLs)
- This model is not recommended for a first-time builder. This manual assumes you already have basic modelling skills and are familiar with printing, assembling, fitting-out and flying 3D Printed model aircraft.
- Check hosting sites (like CULTS3D.com) and RCGROUPS.com/3D Printed Planes for news and updates ([LINK](#))
- And please share your masterpieces photos and flight videos with the community. I only started making 3D printed models because of what I saw others doing ...
- While I enjoyed spending many 100's of hours designing this model, I'm selling the files for a very small amount, so please don't distribute copies of the files



# PARTS

## Electric Ducted Fans – 64mm

1 off either;

- FMS 3S or 4S 11 blade
  - 3900 or 3150KV
- QX-Motor 3S-6S 12 Blade
  - 2200 or 2400KV
- ESC to suit (typically 50-80amp)
- Motor lead extensions ~400mm
- With no undercarriage - recommend 3S-4S
- With undercarriage – recommend 4S-6S

## Battery – Typical

- 1400mAh to 2600mAh
- Approx. 200 grams to 340 grams
- Shorter/fat drone batteries will also fit

## Fittings – Typical

- Spring Wire for various : 1.6-1.8mm dia. – approx. 200mm
- Spring Wire for Undercarriage / 3mm typical
- 2x E/Z Connectors or similar for Elevon Horns
- 4x Dubro type hinges for Nose Gear Doors
- 4mm wooden dowel

## Carbon

10mm Tube

- Swing Pivots: 10 x 8 x 32mm (2)

8mm Tube

- Wings: 8 x 6 x 465mm (2)
- Idle Gear: 8 x 6 x 26mm (1)

6mm Rod/Tube

- Elevons: 6 x 120mm (2)

4mm Rod

- Wings: 4 x 120mm (2) optional

## Servos

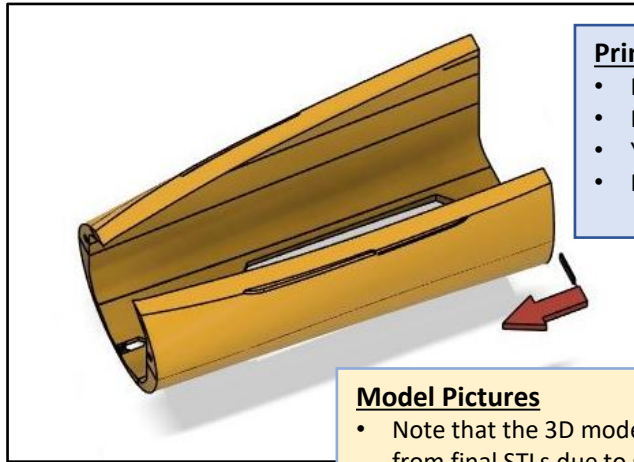
- 1x Hitec HS645MG (Swing Wing)
  - Optional Travel Expander/Tuner
- 2x Towerpro MG91 (Elevons)
  - 2x ~500mm extension leads
- Optional : 1 or 3 micros servos for Retract Doors

## Electric Retracts

- 1x set of 25 gram retracts with steerable nose gear
  - Often found at AliExpress
- Wheels - 2x 52mmx14mm (max) / 2x 35mmx9mm
  - 3mm Spring Wire



# Typical Arrangements

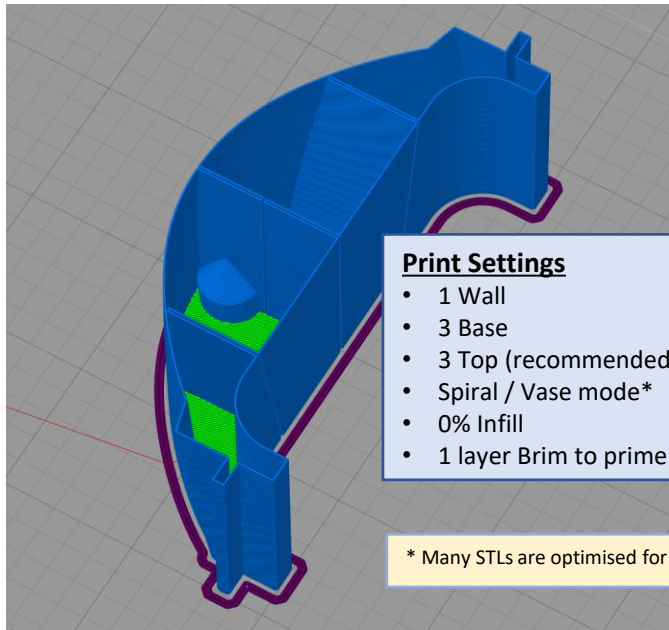


## Printing Orientation

- Red Arrow BASE = Print Bed
- Red Arrow Direction = Z Axis UP
- Yellow indicates component focus
- No Arrow = Pick simplest print arrangement

## Model Pictures

- Note that the 3D model pictures may vary slightly from final STLs due to subsequent improvements



## Print Settings

- 1 Wall
- 3 Base
- 3 Top (recommended. 0 may work)
- Spiral / Vase mode\*
- 0% Infill
- 1 layer Brim to prime nozzle

\* Many STLs are optimised for Spiral / Vase mode

## Notes

\* Many STLs are optimised for Spiral / Vase mode.  
While most main body STLs recommend 3 TOP LAYERS for strength reasons, in most cases this could be reduced to 0/zero.

## Typical Print Settings

### >>LW-PLA

- 0.4 nozzle / 0.4 width
- 0.2 layer height
- 0.6 Extrusion Multiplier
- 250°C nozzle / 60°C bed
- First Layer: 200% height & Width
- No Retraction, No Cooling

### >>LW-PLA-HT

- 0.4 nozzle / 0.4 width
- 0.25 layer height
- 0.65 Extrusion Multiplier
- 230°C nozzle / 60°C bed
- First Layer: 200% height & Width
- No Retraction, 33% Cooling

## Coloured Guides

Do Not Glue

Glue

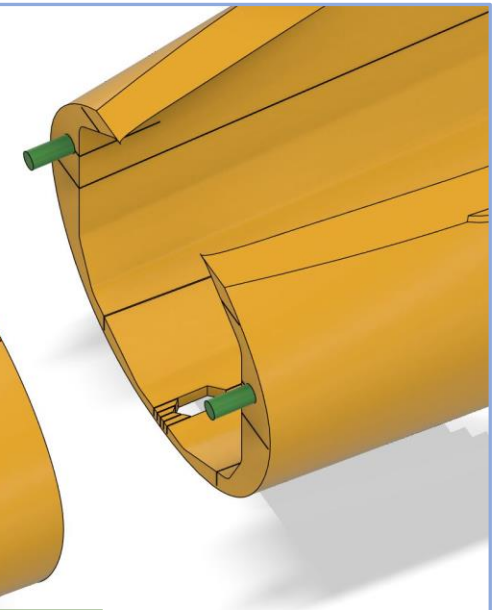
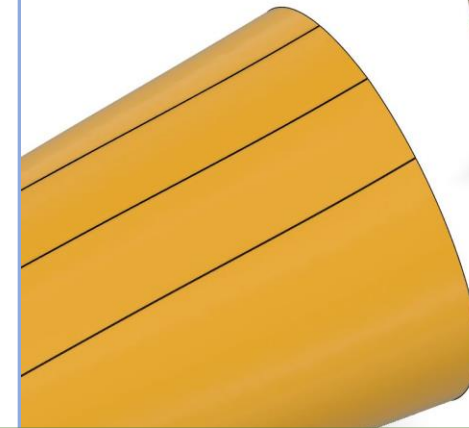
- Print Parameters

STL file name

INFO

## Doweling

- 4mm dowels are used to align large pieces
- Typical length : ~18mm
- Wood dowel is adequate
- If not firm fitting, glue dowel in 1 side first



## Fuselage Gluing

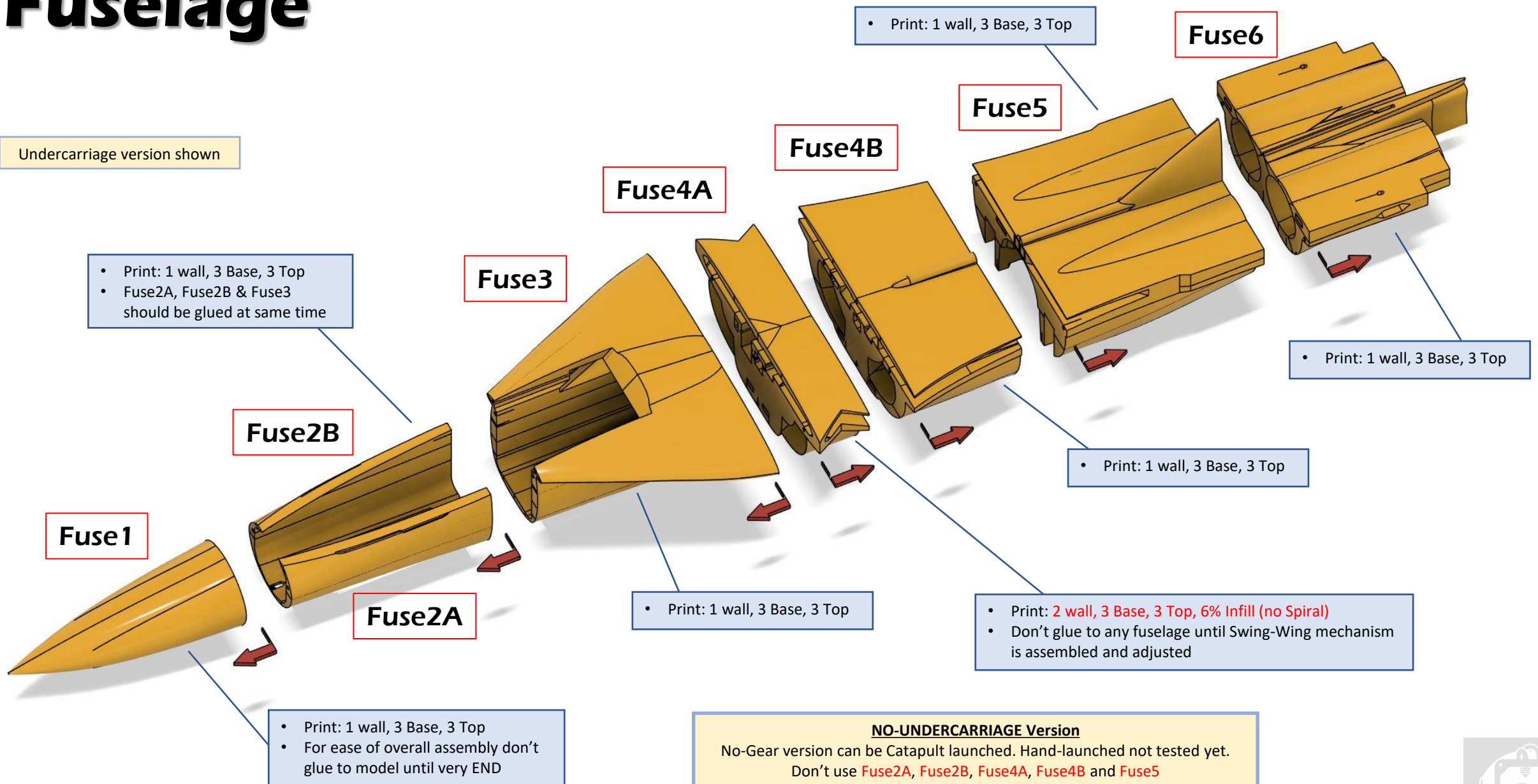
- Sand TOP level/flat
- Apply CA to only where faces touch
- Use dowels to align
- Apply firm pressure
- Use Accelerator if preferred





# Fuselage

Undercarriage version shown



## NO-UNDERCARRIAGE Version

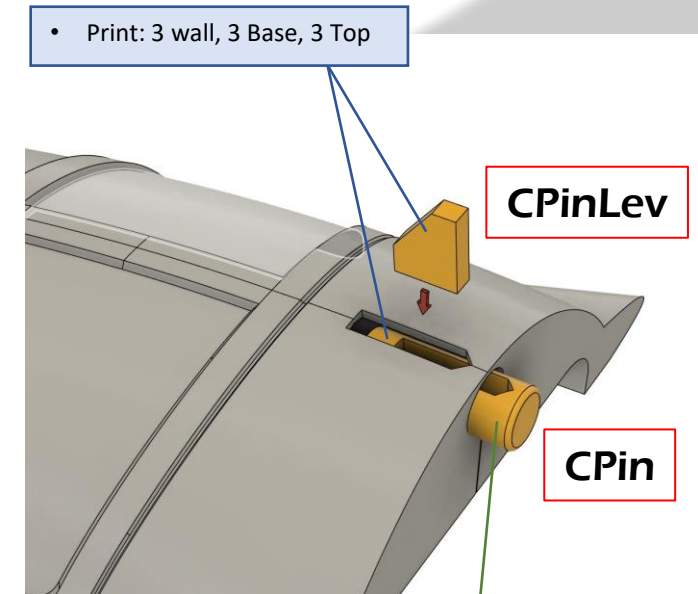
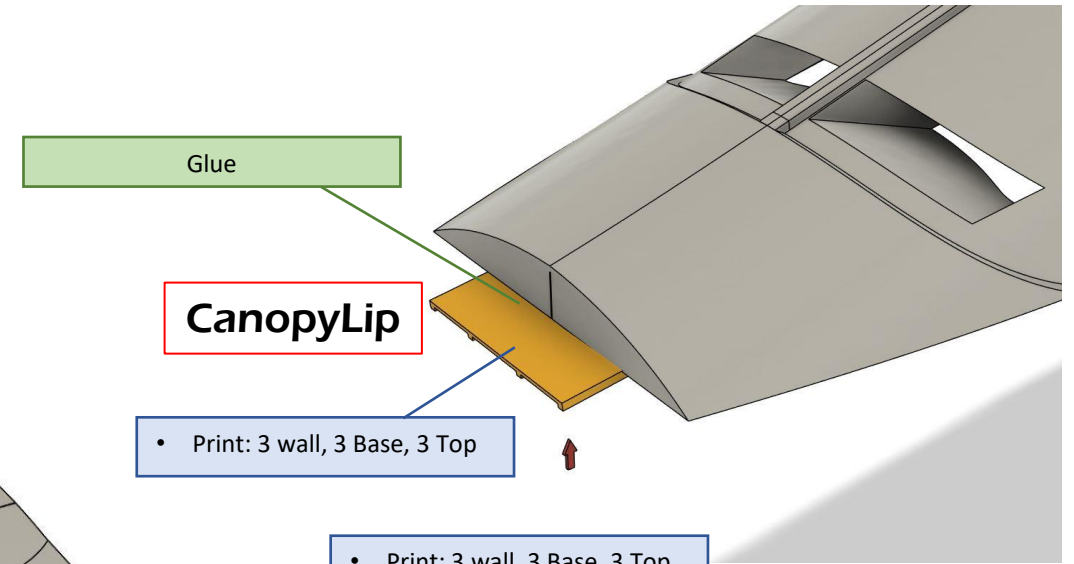
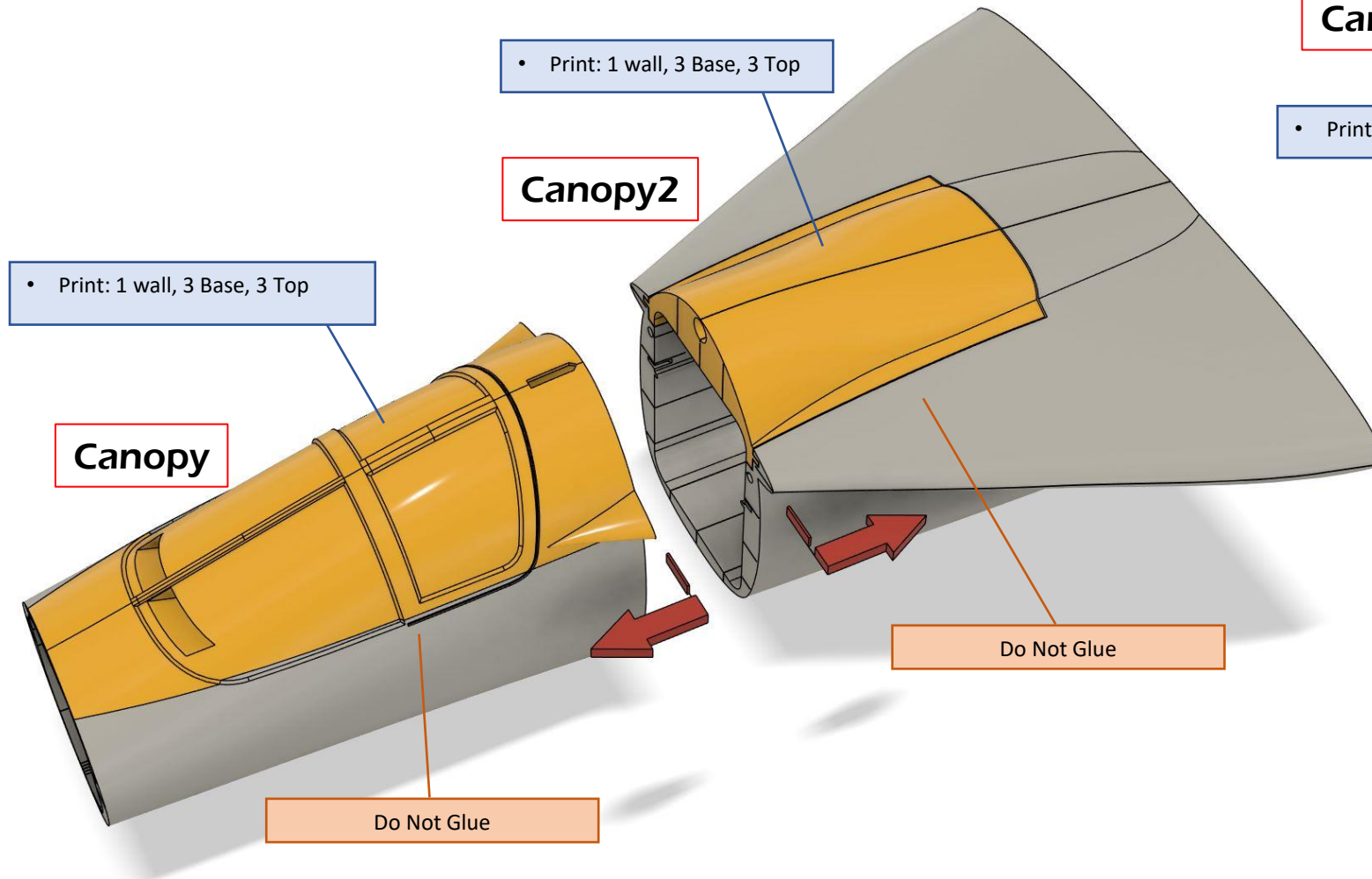
No-Gear version can be Catapult launched. Hand-launched not tested yet.

Don't use **Fuse2A**, **Fuse2B**, **Fuse4A**, **Fuse4B** and **Fuse5**

Instead use **Fuse2**, **Fuse4**, and **Fuse5** found in "NoGear" folder.

**TowHook** can be printed with PLA+. Add wire to make a small hook.

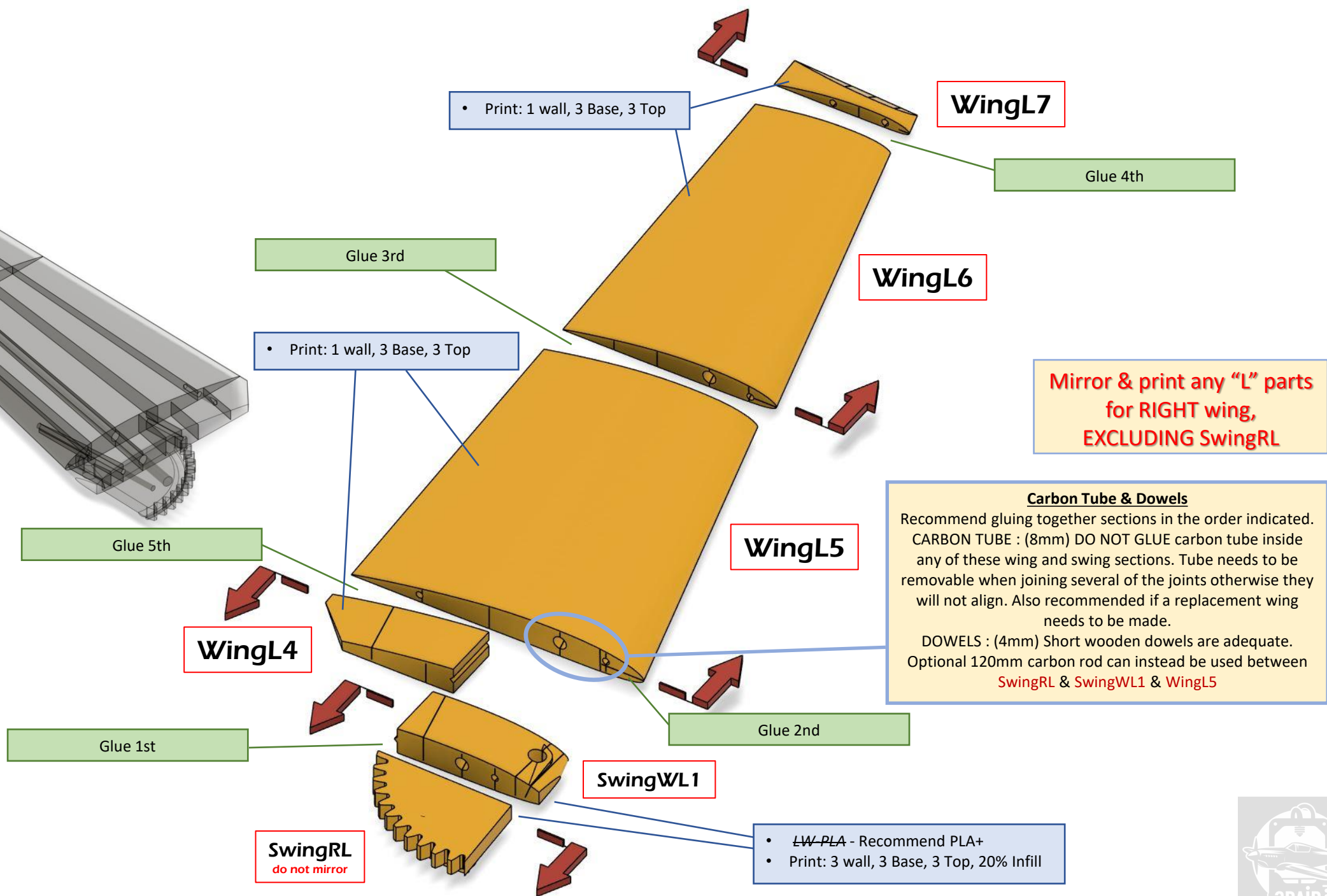
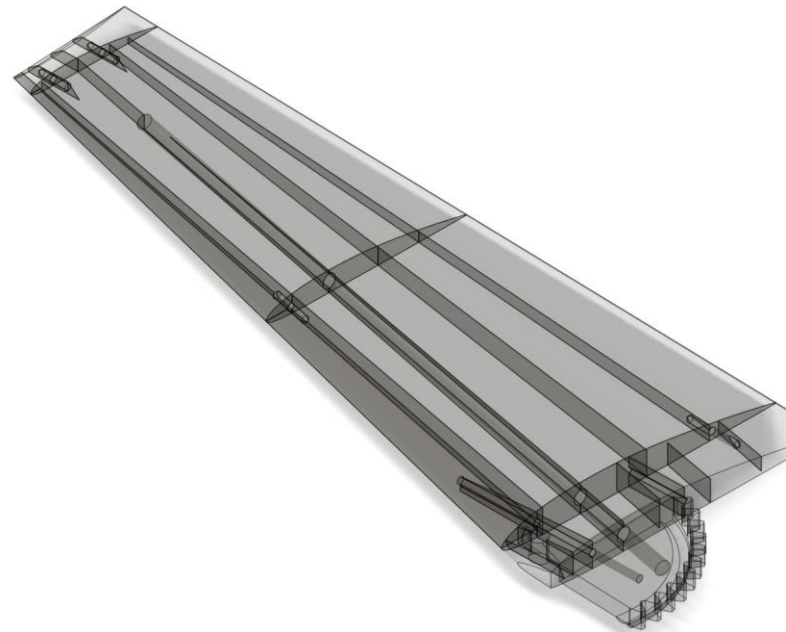
# Canopy



**Canopy Slide Lock**  
With **CPin** inside Canopy, only  
Glue **CPinLev** into **CPin**



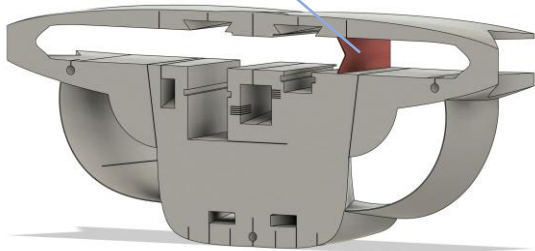
# Wings



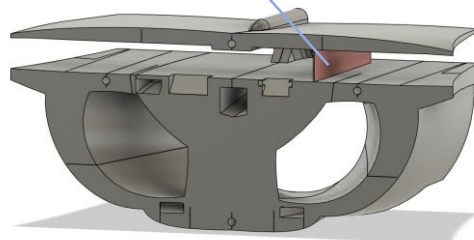


# Fuse4A Arrangements

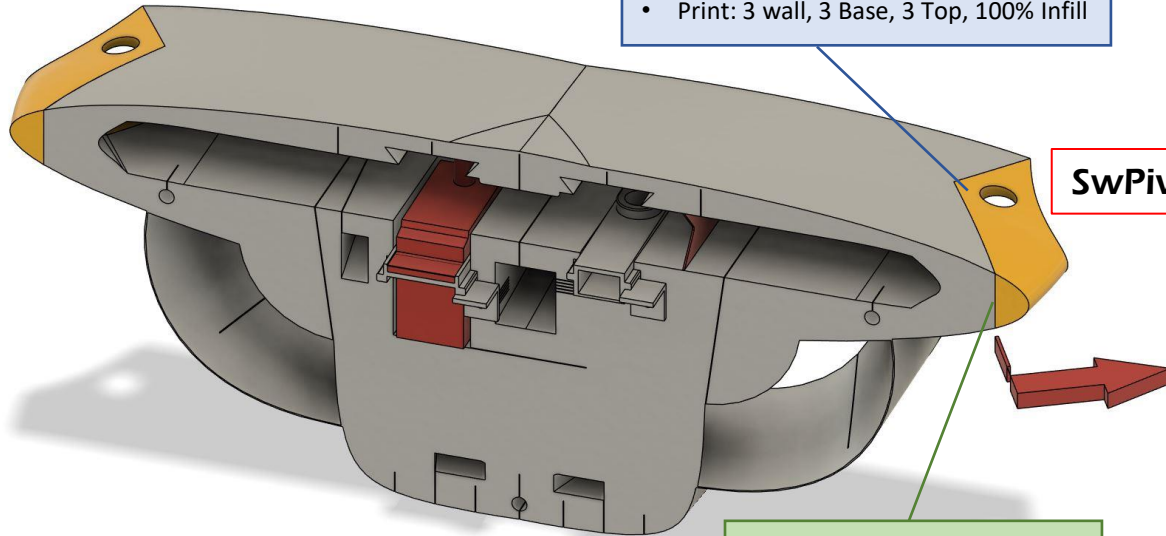
Fuse4A - Remove fillet after printing



Fuse4B - Remove fillet only after gluing to Fuse4A & Fuse5



SwPivotL  
mirror



- LW-PLA - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 100% Infill

SwPivotL

Sand faces for tight fit & Glue

SwingWR1

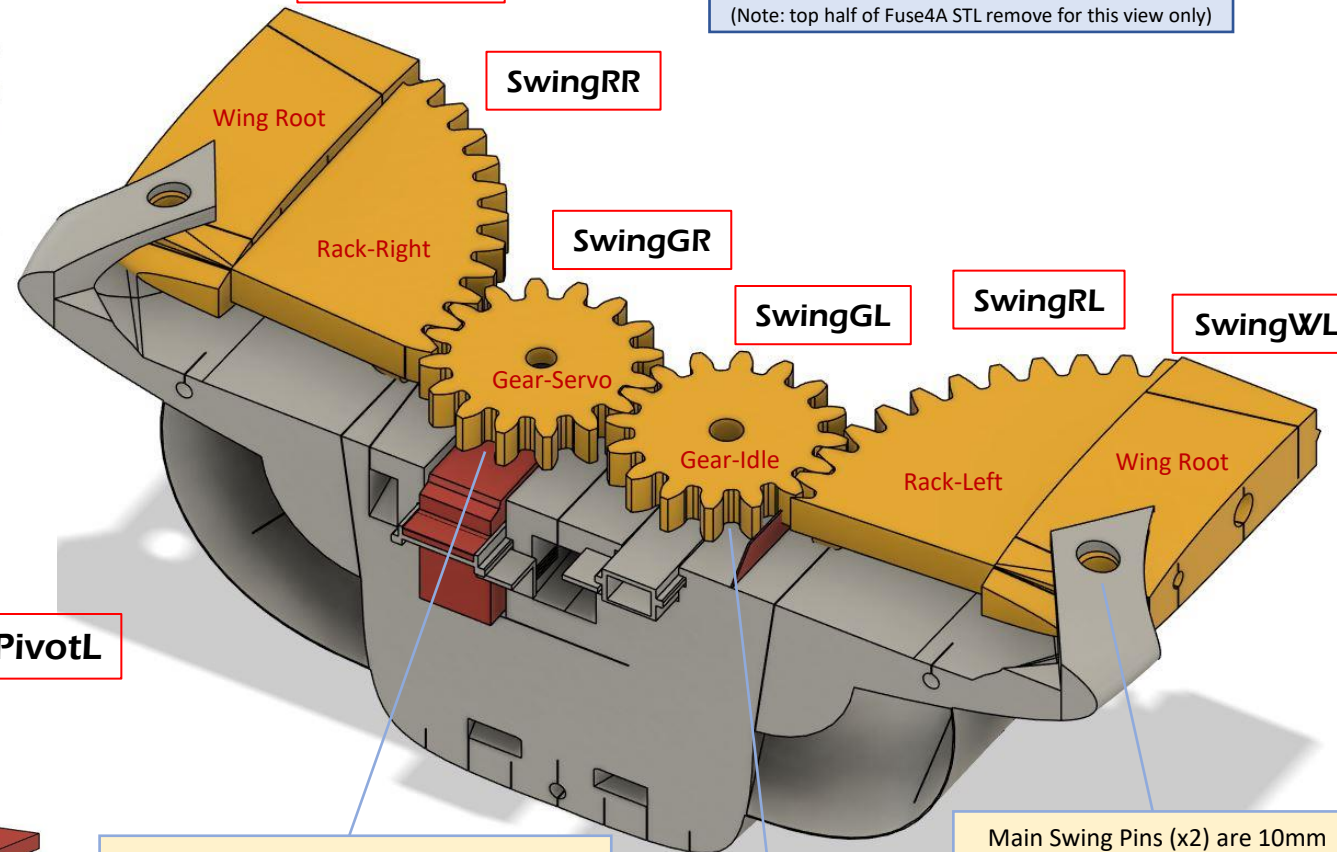
SwingRR

SwingGR

SwingGL

SwingRL

SwingWL1



All these STLs

- LW-PLA - Recommend PLA+
  - Print: 3 wall, 3 Base, 3 Top, 20% Infill
- (Note: top half of Fuse4A STL remove for this view only)

Round "disc-arm" from Servo Kit to be screwed into underside of **SwingGR**

Main Swing Pins (x2) are 10mm Carbon Tube 32mm long

**SwingGearHolder** to interference-fit x1 Pin of 8mm Carbon Tube 26mm long.  
**SwingGL** is to freely rotate on this Pin.

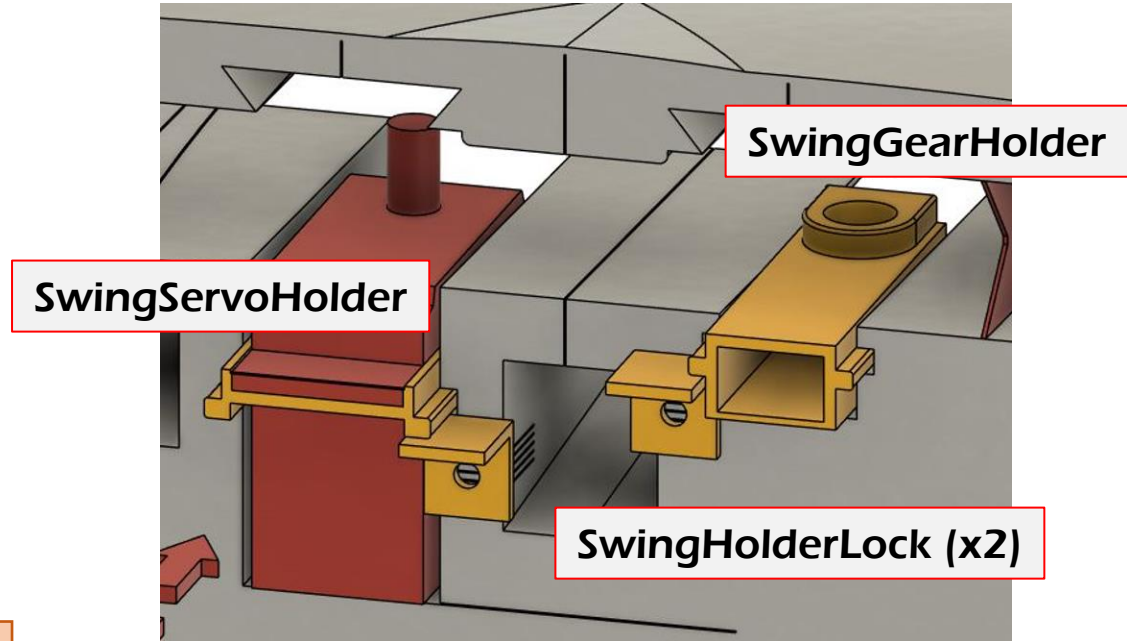
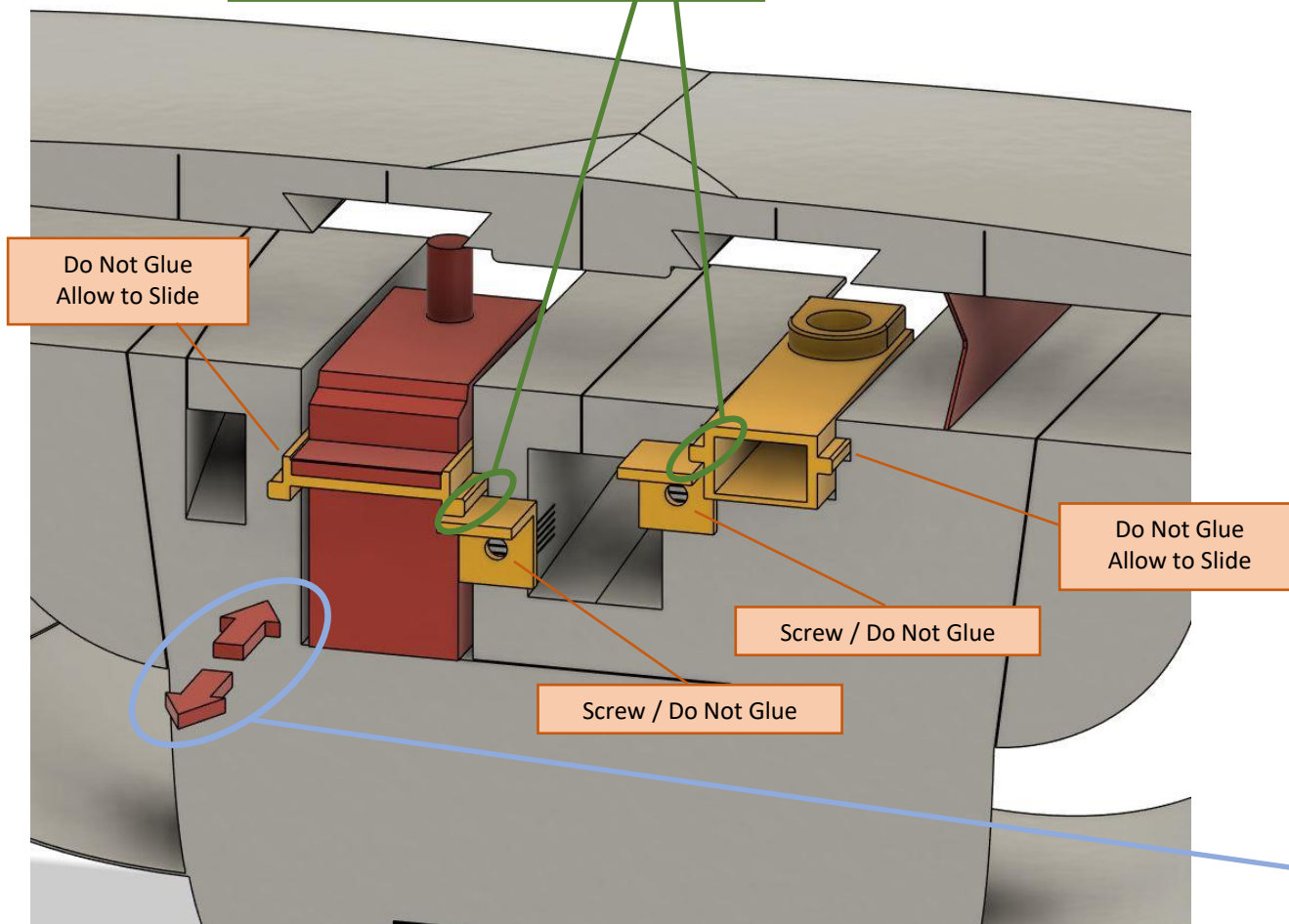




# Fuse4A Arrangements

- All these STLs**
- ~~LW-PLA~~ - Recommend PLA+
  - Print: 2 wall, 3 Base, 3 Top, 100% Infill

**Gear Positioners**  
Once Gears have been adjusted, lightly GLUE each **SWINGHOLDERLOCK** to the **HOLDERS**



**Positioning Servo & Idle Gears**

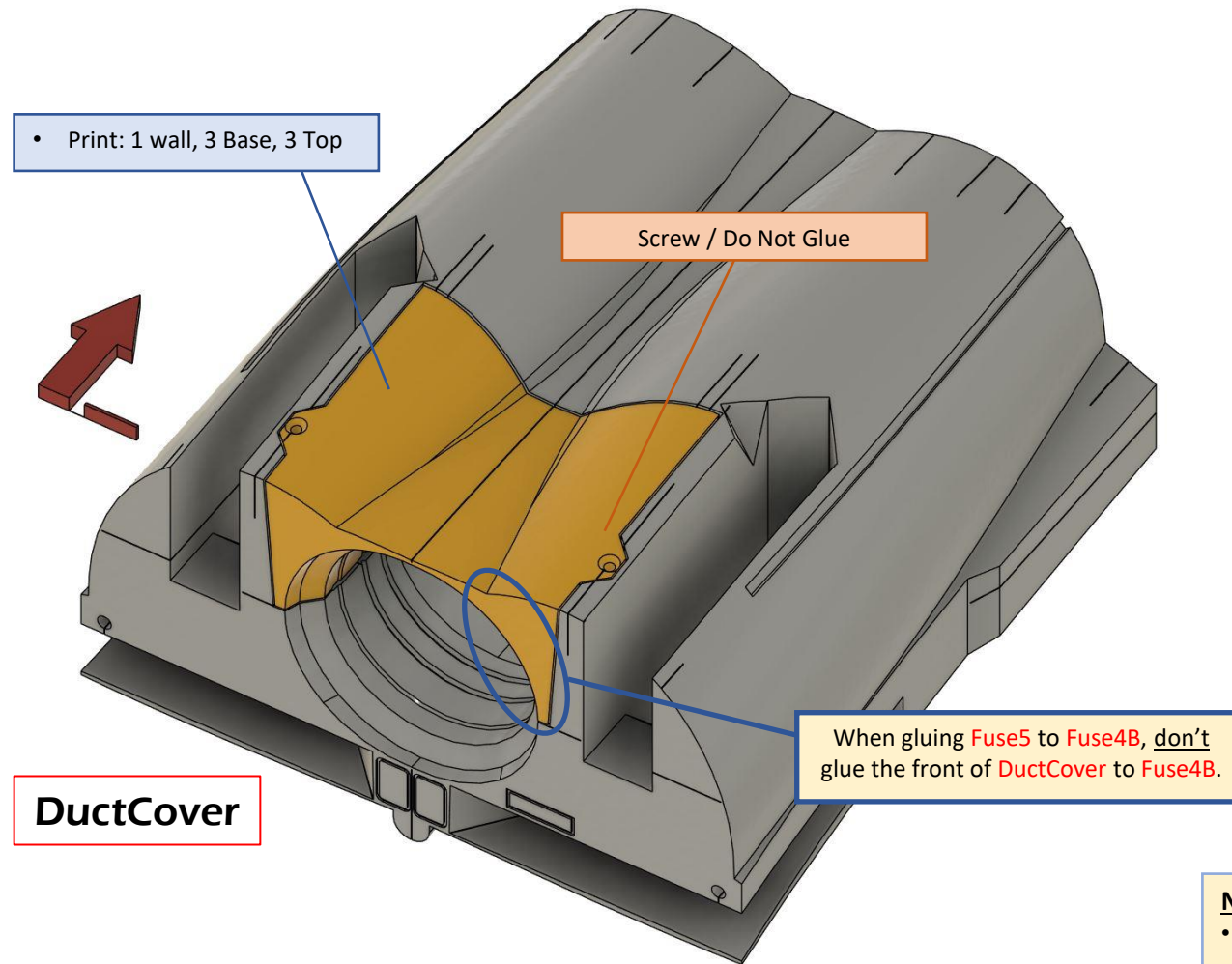
Test the Servo action only once all Swing-Wing parts and both assembled Wings are in place on **FUSE4A**.

**FRICITION** : Adjust both gears in and out IN PARALLEL to achieve the right amount of friction. Too little and there will be too much free movement of the Wing. And too much will overload the Servo

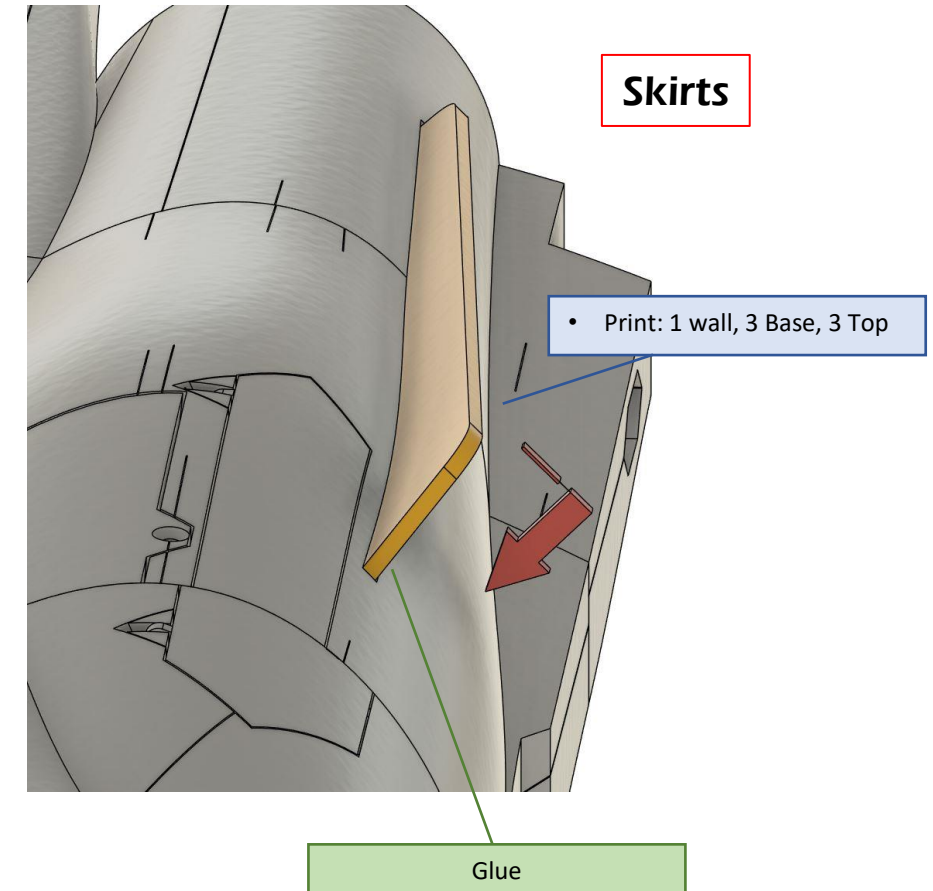
**POSITION** : Adjust servo limits such that **FULL FORWARD** (without jamming) is one end of servo travel, with whatever the other end allows being rearward swing. Servo Travel Extender could be used for additional swing.



# Fuse5 Extras



x2



## Note

- Skirts cross both Fuse5 and Fuse6



# EDF Mounting

## Assembly sequence

EDF should be installed in Fuse5 before Fuse5 is glued to Fuse4B

## EDF Mount Tabs

Reinforced clearance areas are provided to accommodate the typical EDF body mounting tabs of all brands of EDF mentioned in the parts section. Choices could include screwed or hot-glued. Or physically restrain the unit using extra plastic glued in front of Tabs. Test fit with DuctCover to ensure flush fit.

## EDF Position

Leave the bellmouth (curved inlet) in place on the EDF body and slide the unit rearward until the bellmouth touches/seals to the Fuse5 body (& DuctCover). These provide more efficiency operation.

## FMS Unit

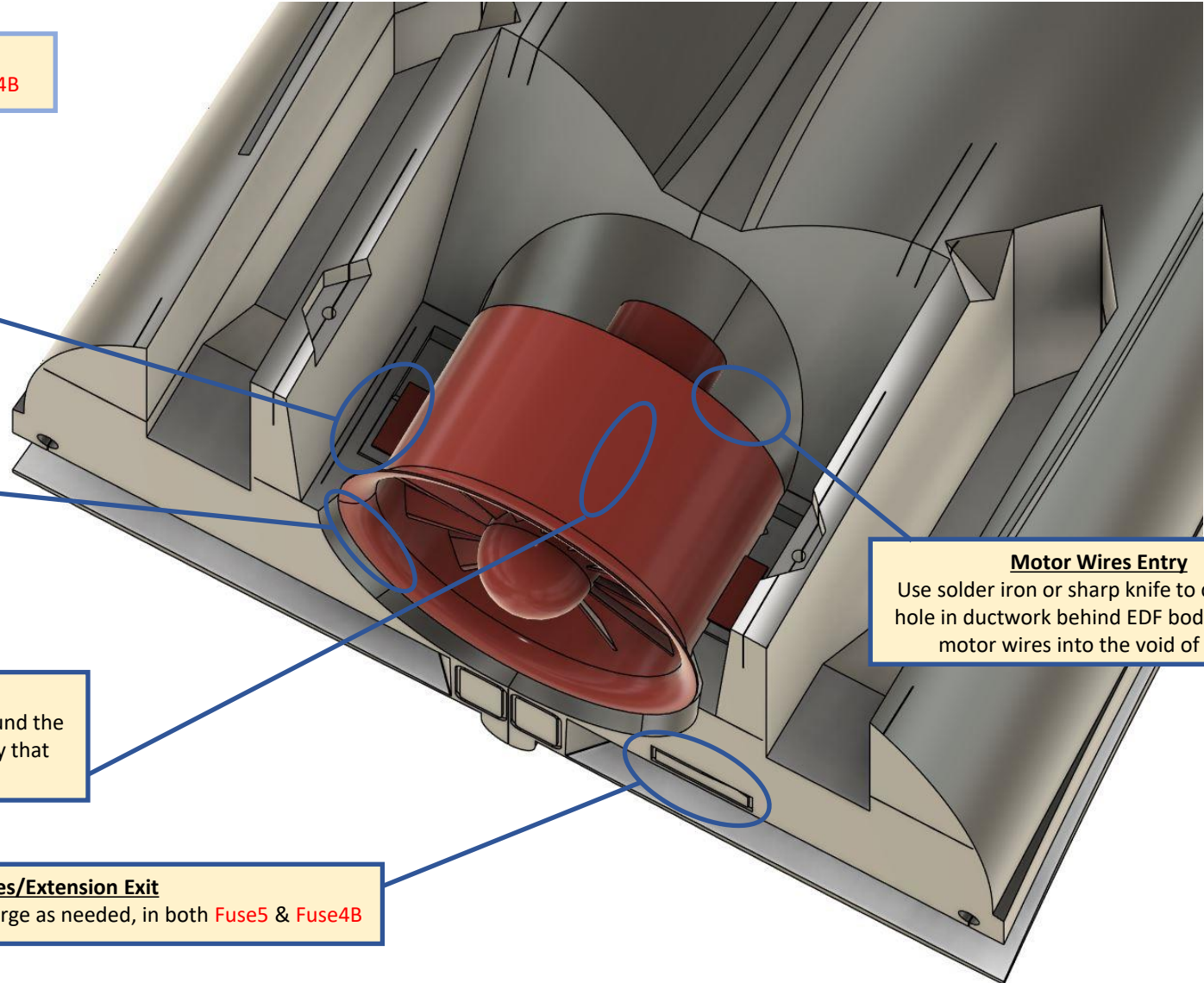
The 4S FMS branded unit has several circumferential ribs around the outside of the body. Grooves are provided in the Fuse5 body that should accommodate and avoid mounting issues.

## Motor Wires/Extension Exit

Remove panel / cut opening as large as needed, in both Fuse5 & Fuse4B

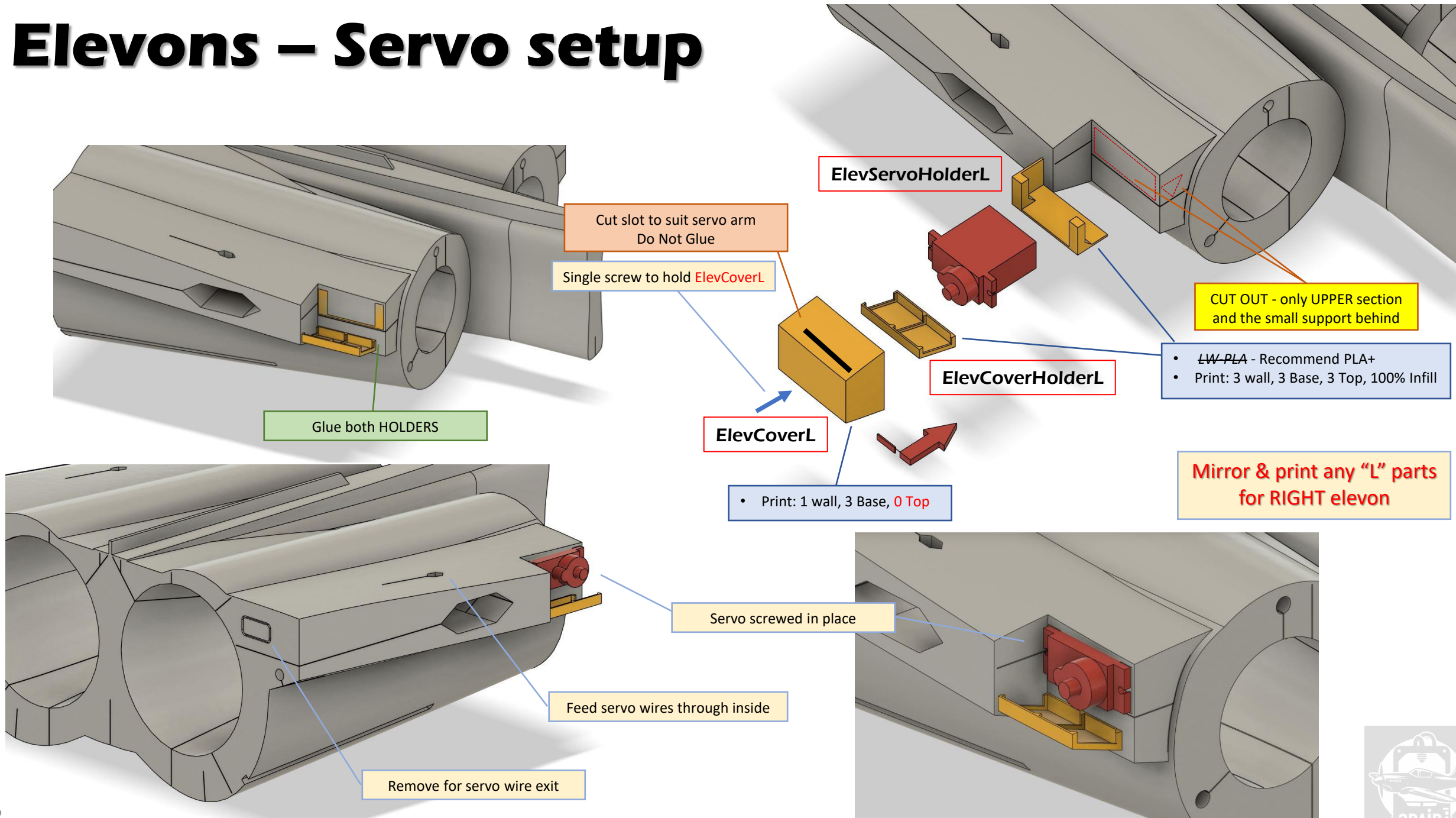
## Motor Wires Entry

Use solder iron or sharp knife to cut a small hole in ductwork behind EDF body, allowing motor wires into the void of Fuse5





# Elevons – Servo setup



# Elevons

## Elevon Arrangments

CARBON TUBE : (6mm) Glue Carbon Tube to ElevL and ElevHorn only at where these 3 pieces interface. Then glue ElevSpacer to ElevHorn.

**PIVOT BLOCK :** Drill or sand 6mm hole in **ElevPivotL** such that Carbon Tube begins to freely rotate. Drill or sand 6mm hole in **ElevHolder** such that it is firm enough on the Carbon Tube to stop the Elevon easily exiting the pivot block, but not too firm that Elevon can't be pulled out of its pivot block with reasonable force.

Carbon Tube Length : Cut just short of its internal exit of **ElevPivotL**.

## All these STLs

- ~~LW-PLA~~ - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

Do Not Glue

## ElevHolder

## ElevPivotL

# ElevSpacer

ElevHorn

Glue

ElevL

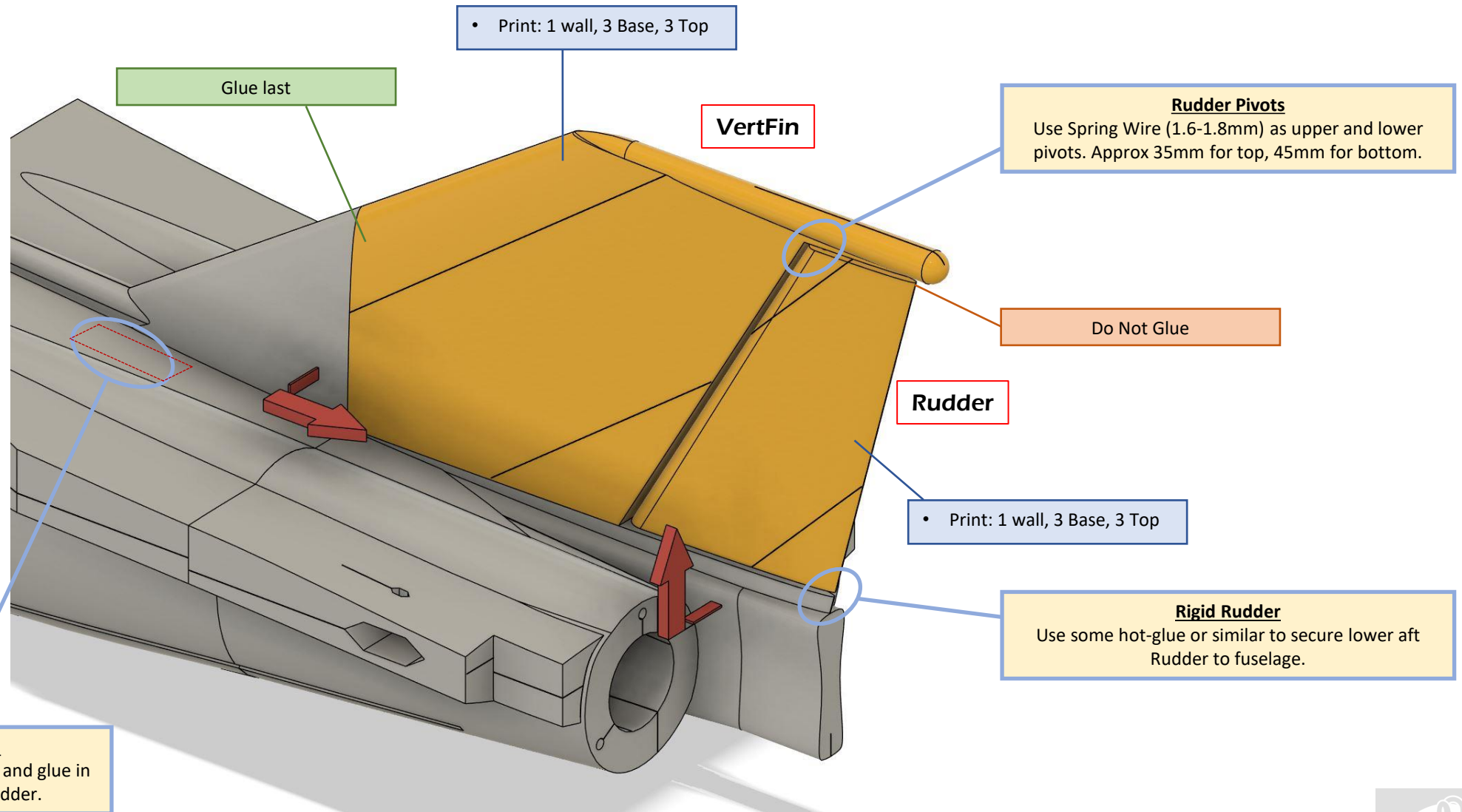
Mirror & print any "L" parts  
for RIGHT Elevon

- Print: 1 wall, 3 Base, 3 Top

### Attaching Elevon to Fuselage

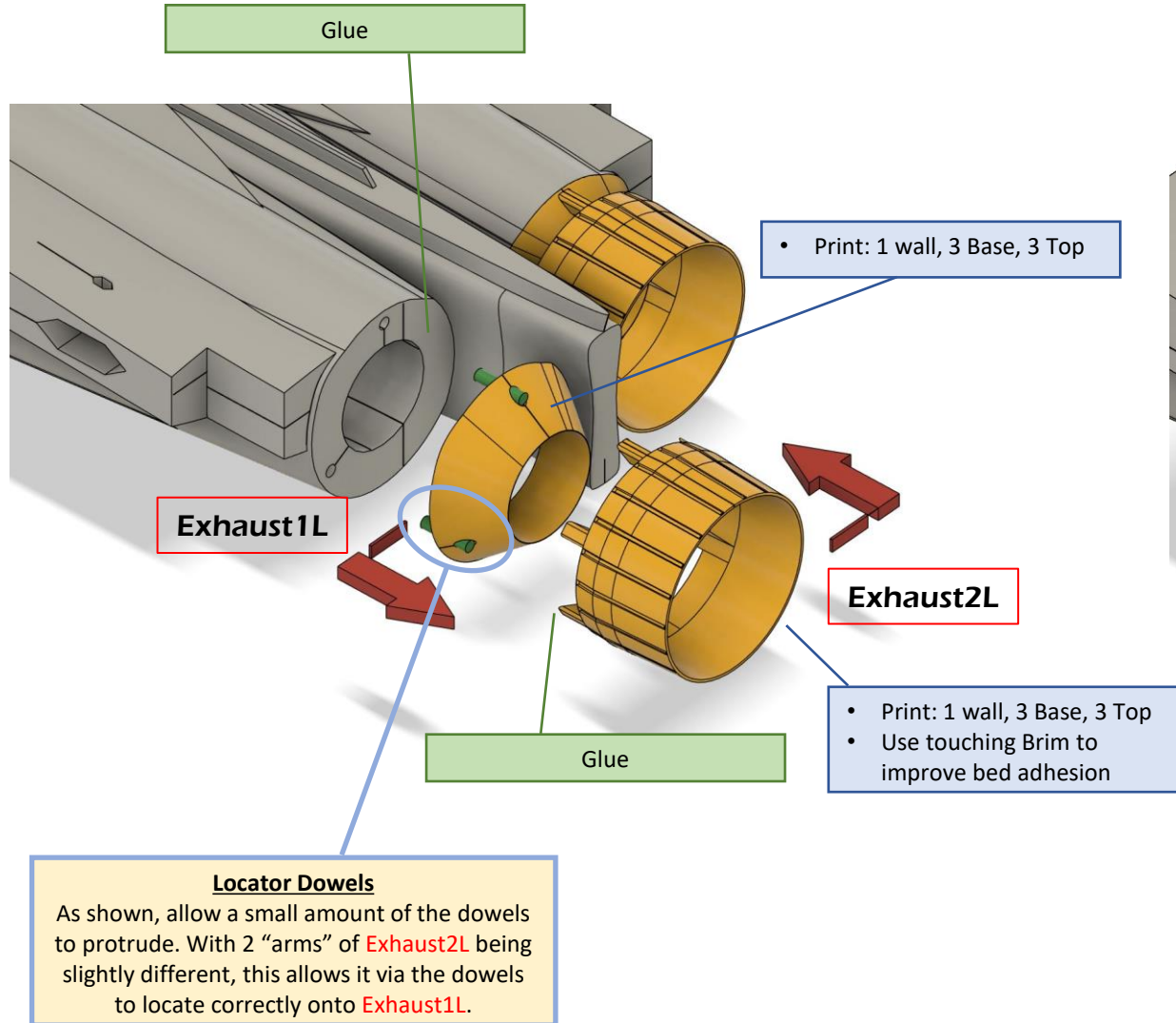
During final assembly : Ensure **ElevPivotL** slides firmly into main fuselage. **Recommend Do Not Glue**. Outside of pivot block should be flush with fuselage. Drill small hole in indicated location and use small screw to hold pivot block in place

# Tail

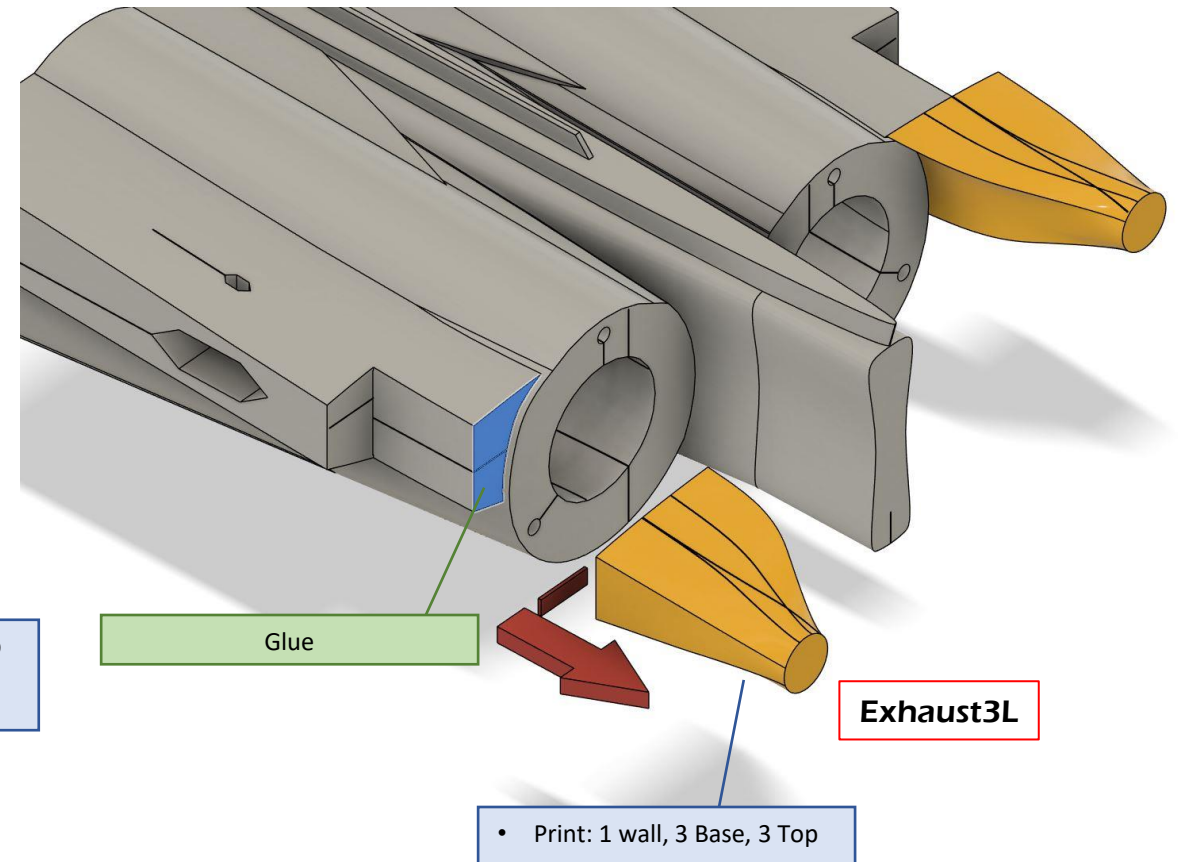




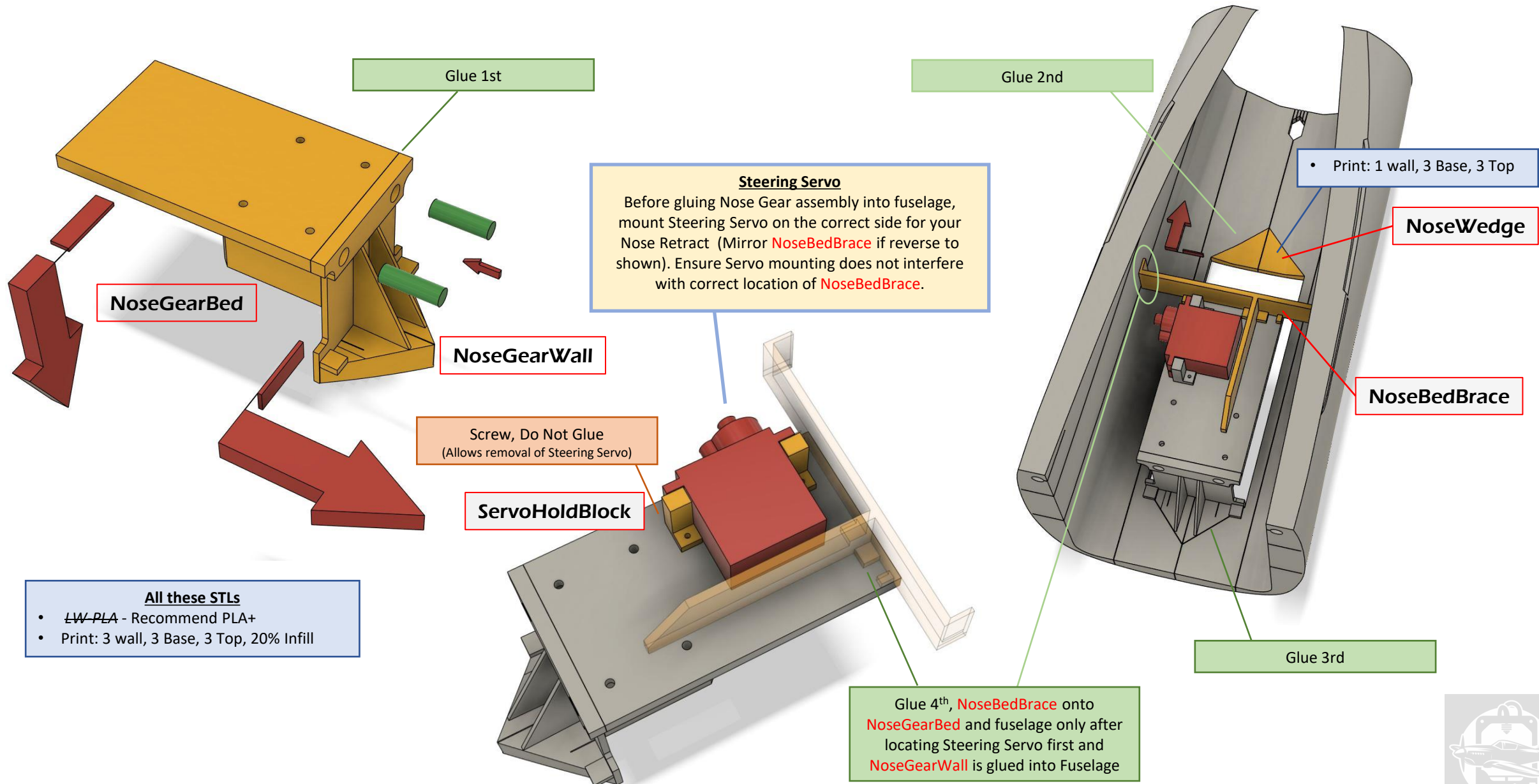
# Exhaust



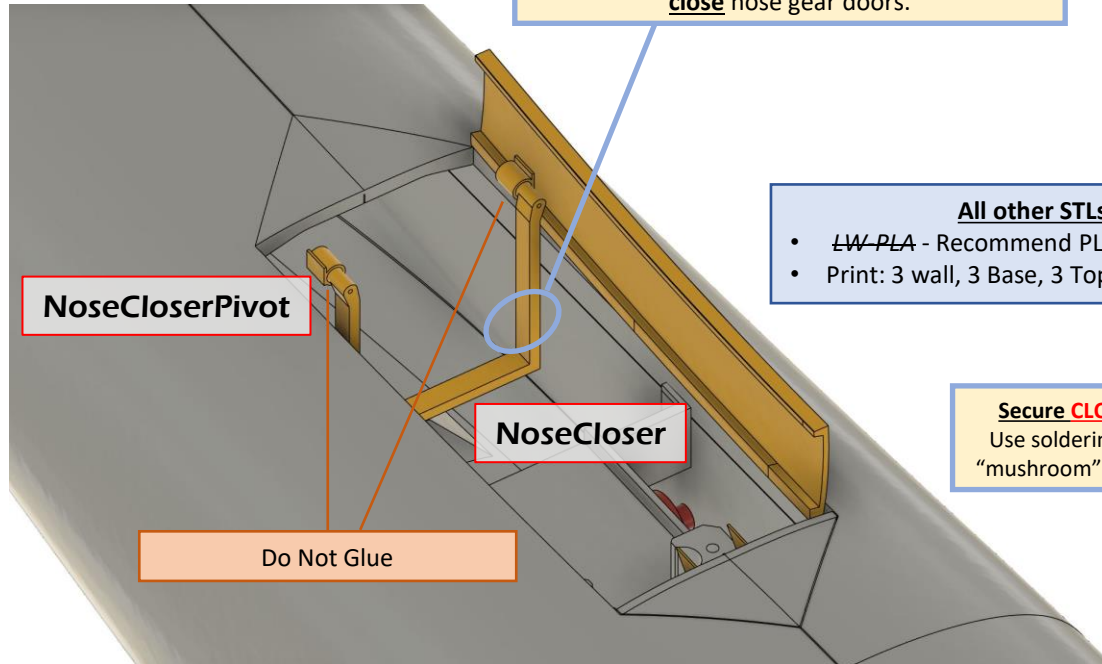
Mirror & print any “L” parts for RIGHT Exhaust



# Nose Gear



# Nose Gear



## Nose Door Open & Close

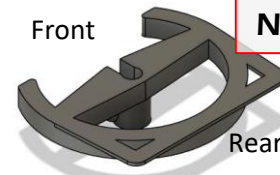
Use **NoseGearGuide** attached to Retract Leg to push **open** nose gear doors.  
Use nose wheel(s) pushing on **NoseCloser**. To **close** nose gear doors.

## All other STLs

- ~~LW-PLA~~ - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

## Secure CLOSER Pin

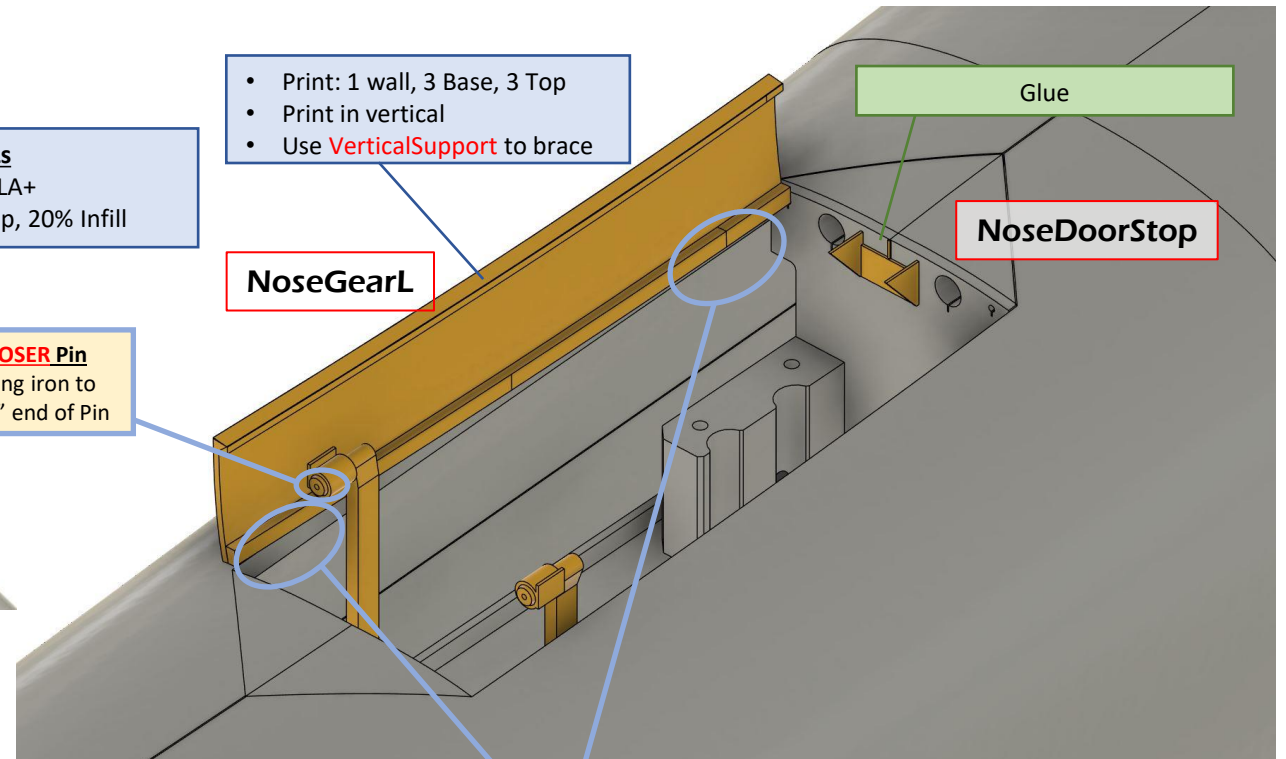
Use soldering iron to "mushroom" end of Pin



## **NoseGearGuide**

Use screw to attach **NoseGearGuide** to 3mm gear wire. Should be aligned to lowest portion of door when open

Mirror & print any "L" parts for RIGHT Door



- Print: 1 wall, 3 Base, 3 Top
- Print in vertical
- Use **VerticalSupport** to brace

## **NoseGearL**

## Nose Door Hinges

Use 2x Dubro type hinges in each door. Use a scalpel to cut slots into **hollow centre** of fuselage and **hollow centre** of **NoseGearL**. Push hinge with a small amount of glue into slots.

## Gear Door Actuation

The next few pages provide a Undercarriage Door opening and closing solution using only the (low) mechanical "push" energy of the 25gram retracts themselves. This can be difficult to get working and may not be 100% reliable. If you intend to use 6S power and an RX with enough channels, consider using micro-servos to actuate the doors instead. Suggest at least start with the Nose Gear Doors as they tend to be the more difficult to set up.





# Rear Gear

Mirror & print any "R" parts for LEFT Rear Gear

## Electric Retract Wire Exit

Run servo wire extensions from front compartment to each rear retract area.

## All other STLs

- LW-PLA - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

RearGearBedR

Glue

RearDoorR1

DoorHingeFR2

Glue

Glue

**Gluing Guide**  
Align 2 tags before gluing.

RearDoorR2

DoorHingeRR2

Glue

- Print: 1 wall, 3 Base, 3 Top
- Print in vertical
- Use **VerticalSupport** to brace

- Print: 1 wall, 3 Base, 3 Top
- Print in vertical
- Use **VerticalSupport** to brace



# Rear Gear

## How does it work?

**OPENING:** The rear retract wheel initially pushes the doors open. The retract Spring Wire holds the doors open.

**CLOSING:** The retract Spring Wire pushing on **RearDoorCloser** to push the doors closed.

## All these STLs

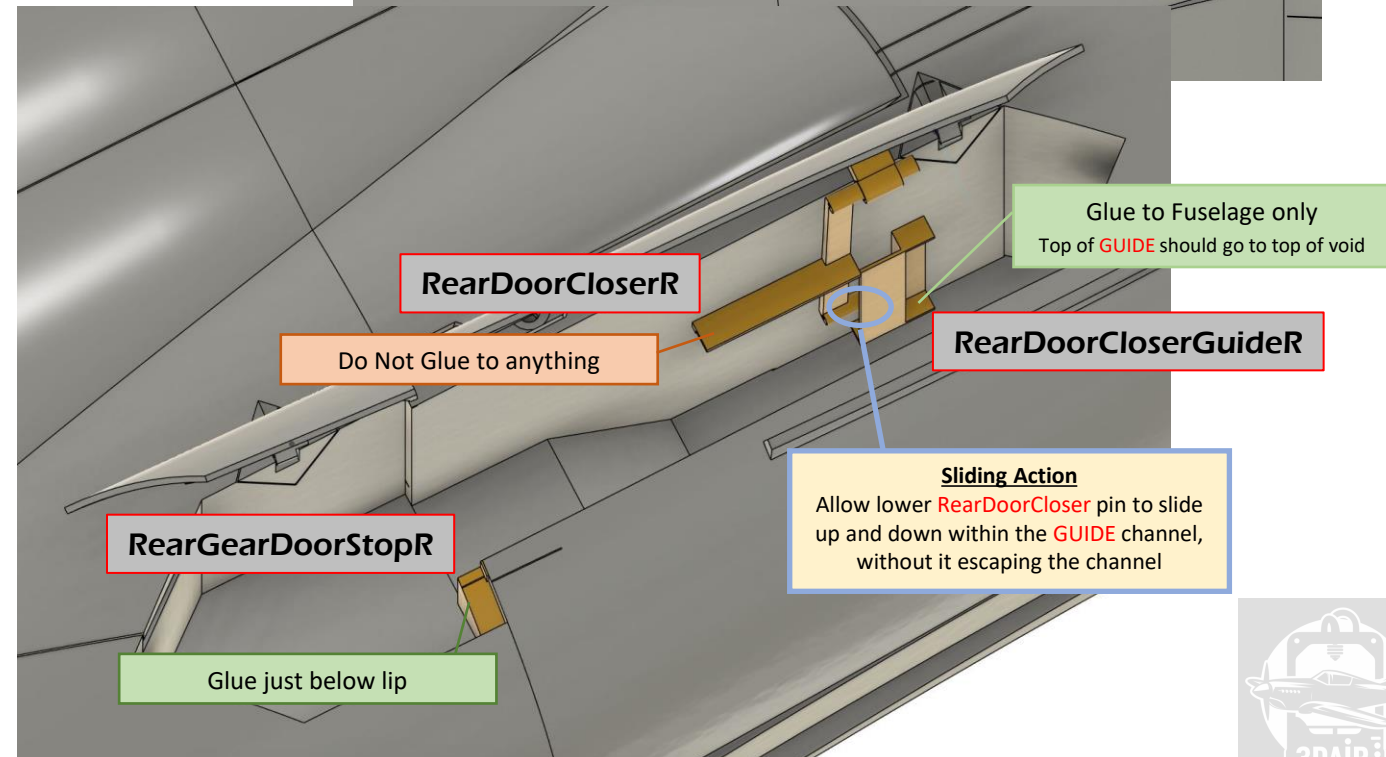
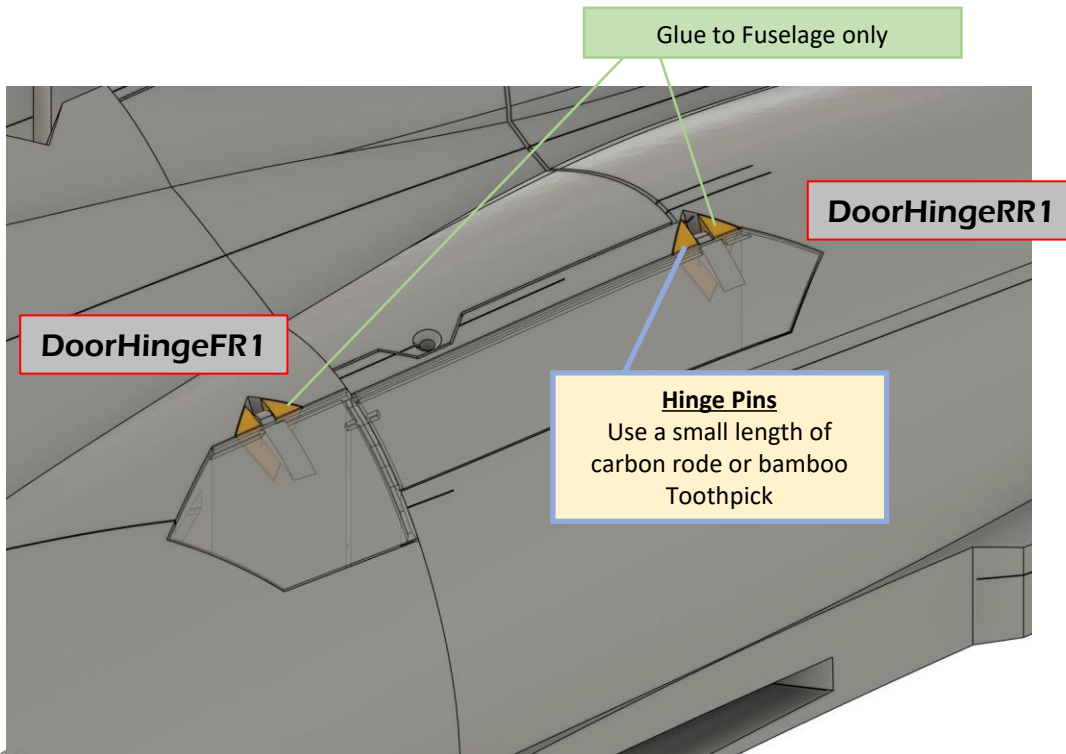
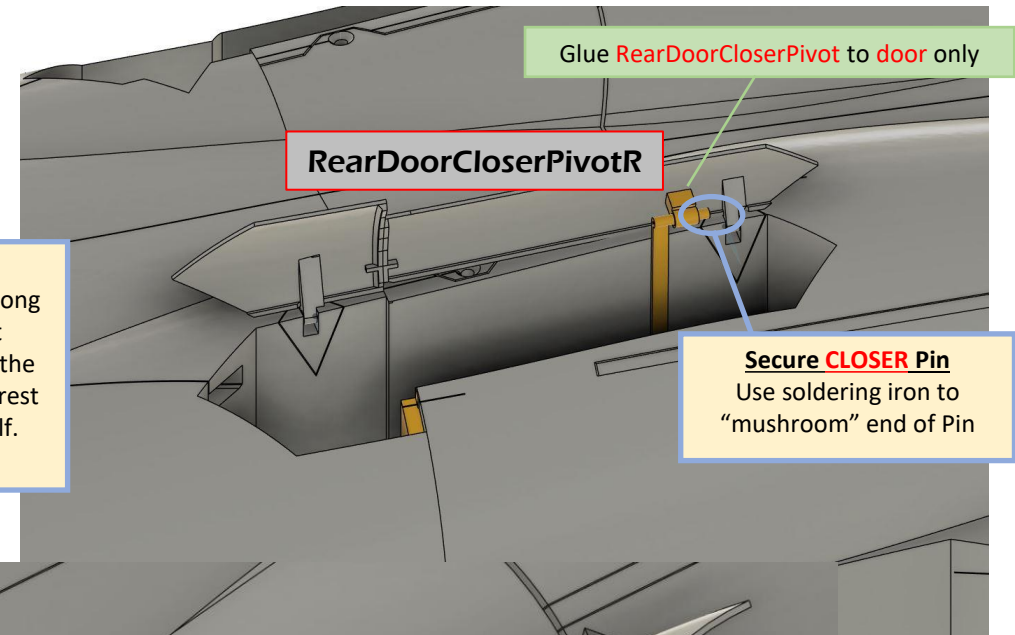
- ~~LW-PLA~~ - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

Mirror & print any "R" parts for Left Rear Gear

## Rear Gear Door Open/Closer Arrangements

Overall CLOSER arrangement can be positioned anywhere along the length of the rear gear wheel enclosure, but the best position is lining the horizontal Tab of **RearDoorCloser** with the lowest portion of the retracts Spring Wire, but allowing the rest of the CLOSER hardware to not tangle with the Wheel itself.

**RearGearWire** provides the Spring Wire template.



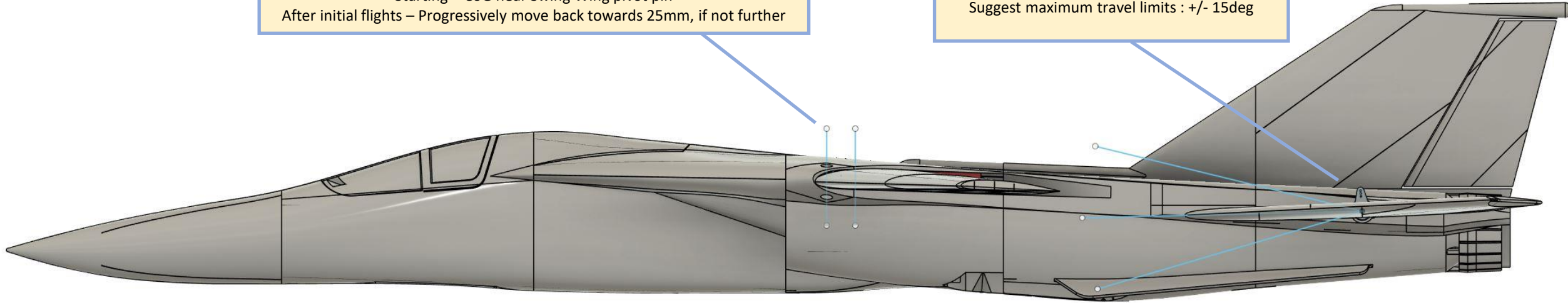
# Flight Setup

## CoG

With wings swept full forward / trailing edge of wing near perpendicular :  
Starting – CoG near Swing Wing pivot pin  
After initial flights – Progressively move back towards 25mm, if not further

## Elevons

Neutral position : Line leading edge point up  
with bottom ledge of the flat fuselage area.  
Suggest maximum travel limits : +/- 15deg



## Swing Wing Considerations

Not a lot of test time was spent with the wing swept, but these elements should be considered;

- Recommend don't start playing with Swept Wings in your first flights!
  - Un-Swept : Use a few flights to get comfortable with the right CoG
- As the wings are swept, the Centre of Lift moves rearward / model acts Nose-Heavy
- More Up-Elevator needs to be added. Try use your TX setup to do this automatically
  - The Roll-Rate increase. Try use your TX setup to reduce roll travel automatically
- Double check that any automatic setup work *TOGETHER* to provide reasonable Elevon travel in any direction
  - Depending on your EDF, model speed may not increase all that much (*For the LOOKS ONLY!* :D )
- If you have too much friction in your Swing Servo setup, air resistance may not allow wing to swing forward. If this happens try gaining altitude and do a quick pitch-over to remove upward forces on the wing underside
  - For obvious reasons trying to landing with wings swept is not recommended





# PHOTOS

Use these for long, thin pints

VerticalSupport

Use **Discs** for thin contact areas or STLs prone to warping.

AdhesionDisc

Your SLICER software will have a BRIM feature that allows improved Bed adhesion. Best when offset from STL is small ( $\sim 0.2\text{mm}$ )

VASE/SPIRAL Print mode

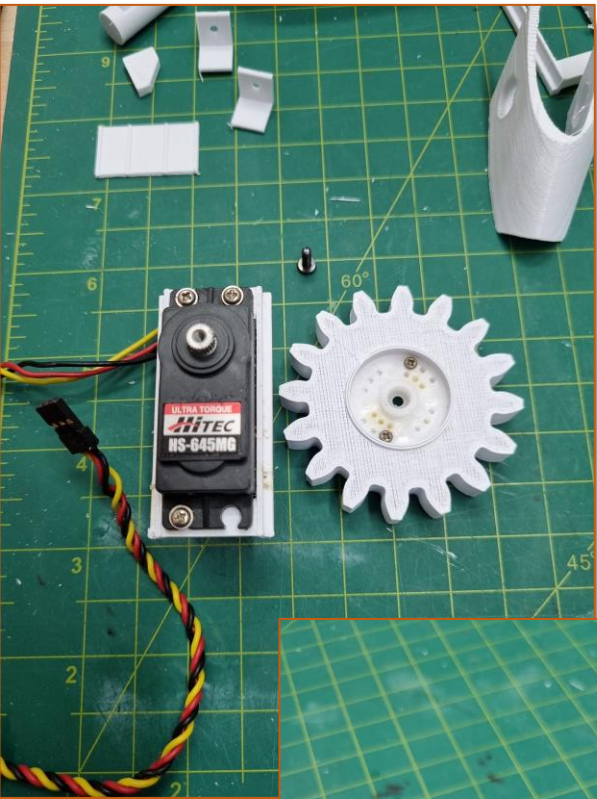
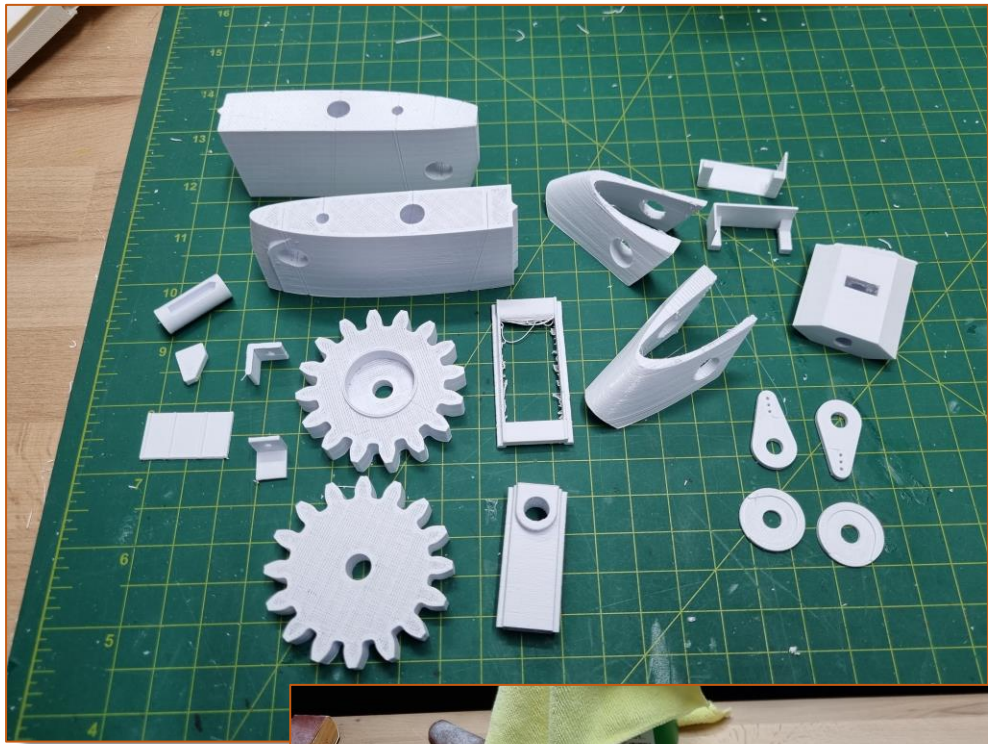
Most of the larger LW-PLA pieces have been optimised for this mode.  
Note the significant reduction in STRINGING

Fuse4A

AdhesionDisc





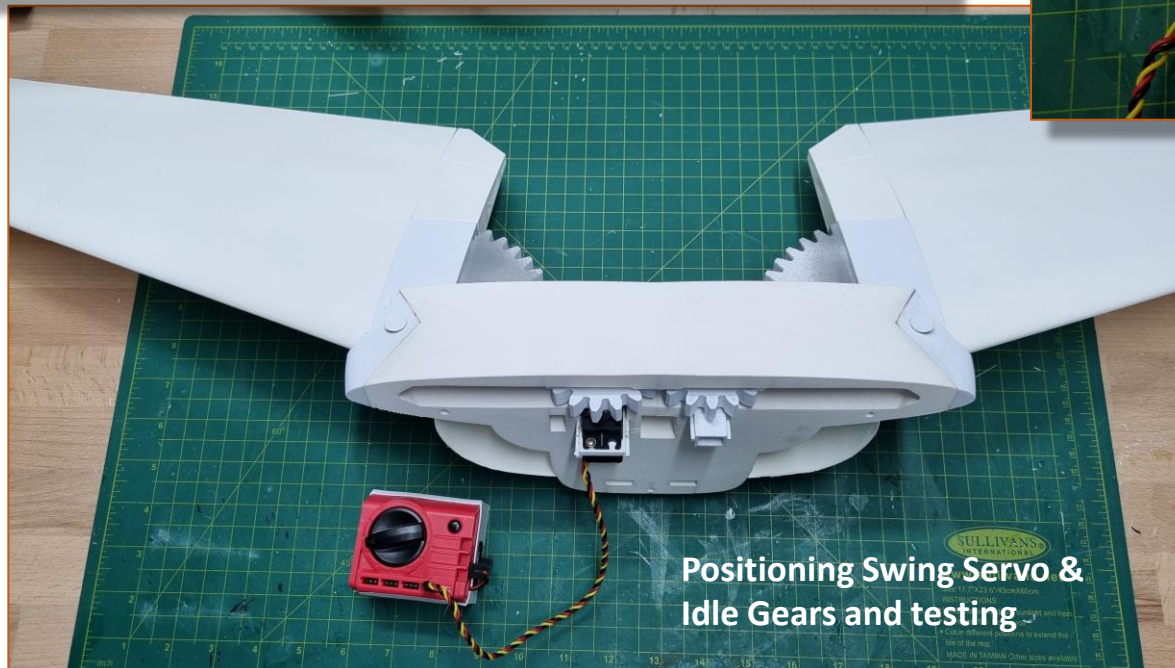
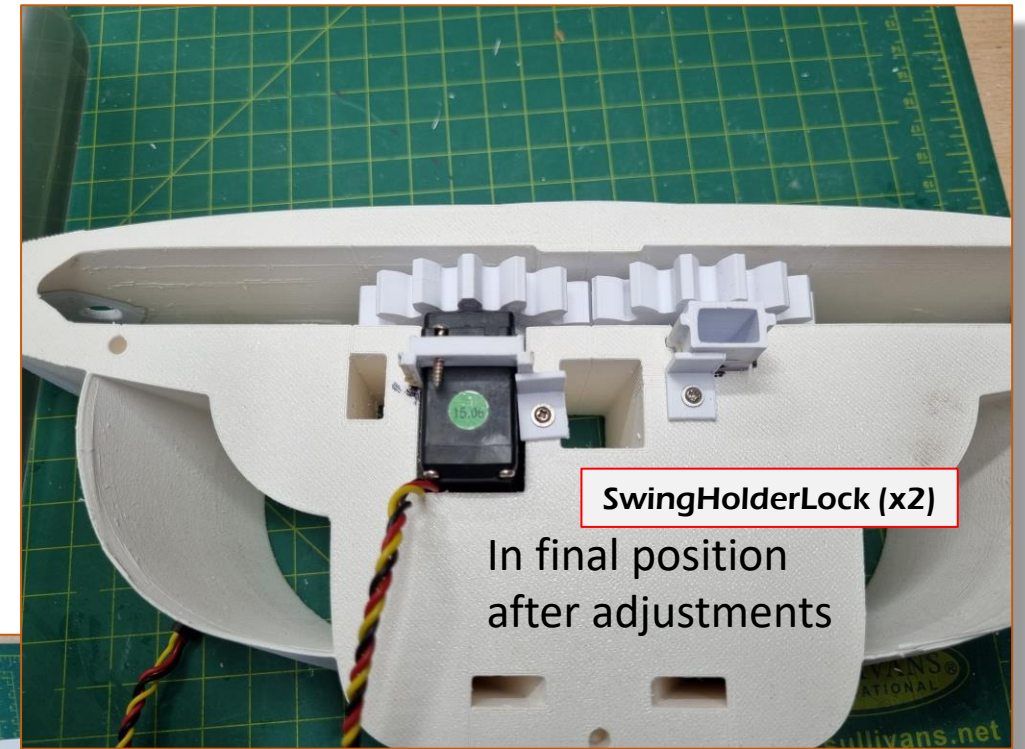
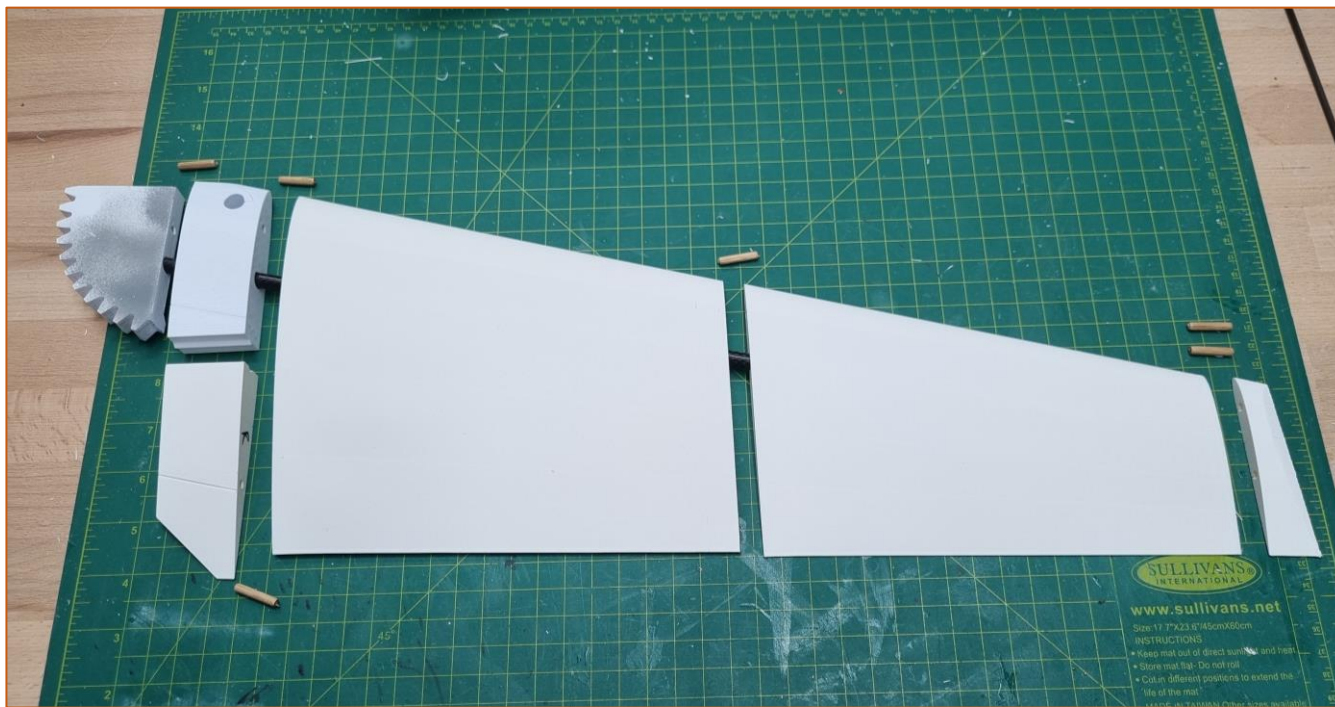


Main Swing Wing Pins

SwingPinCap



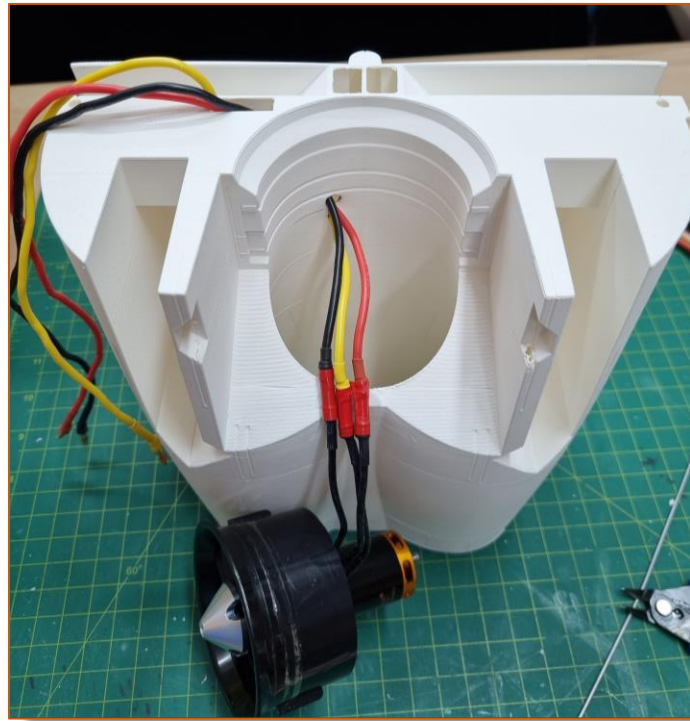




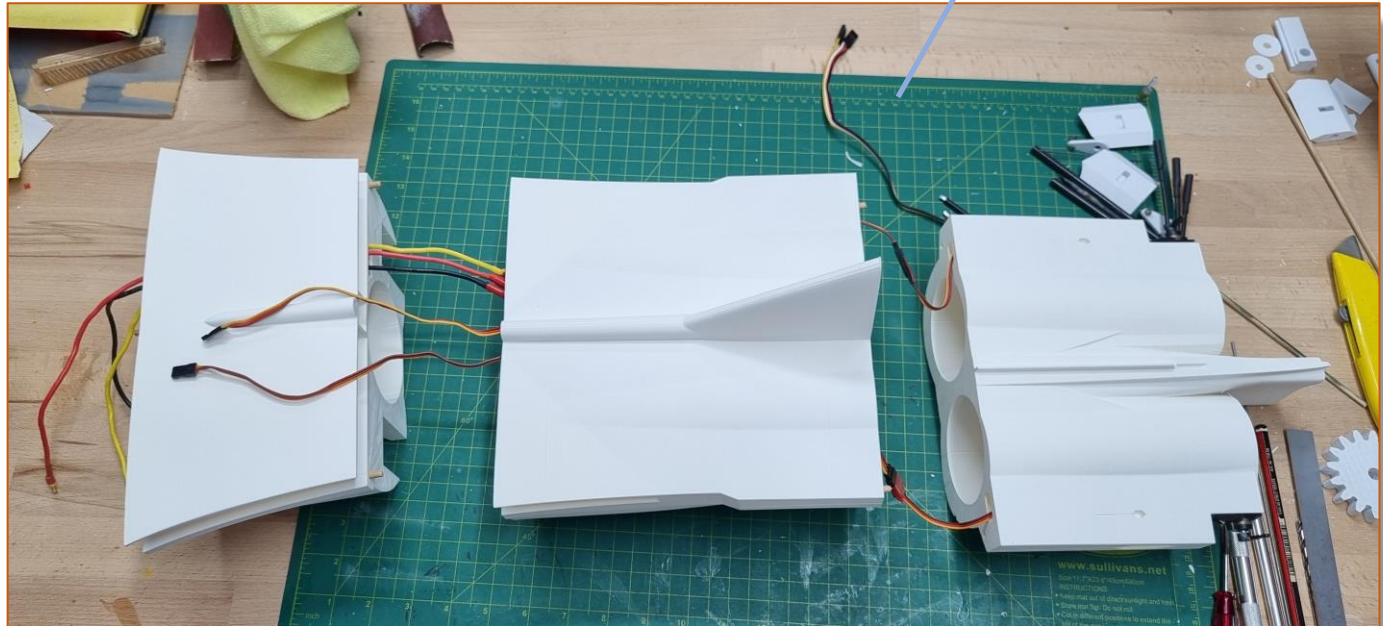


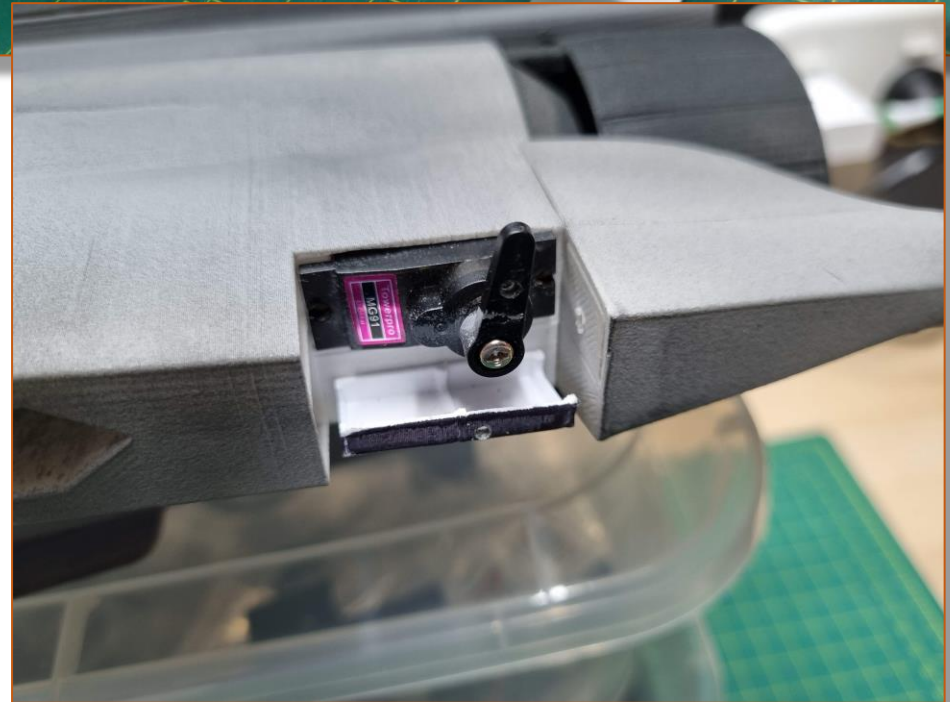
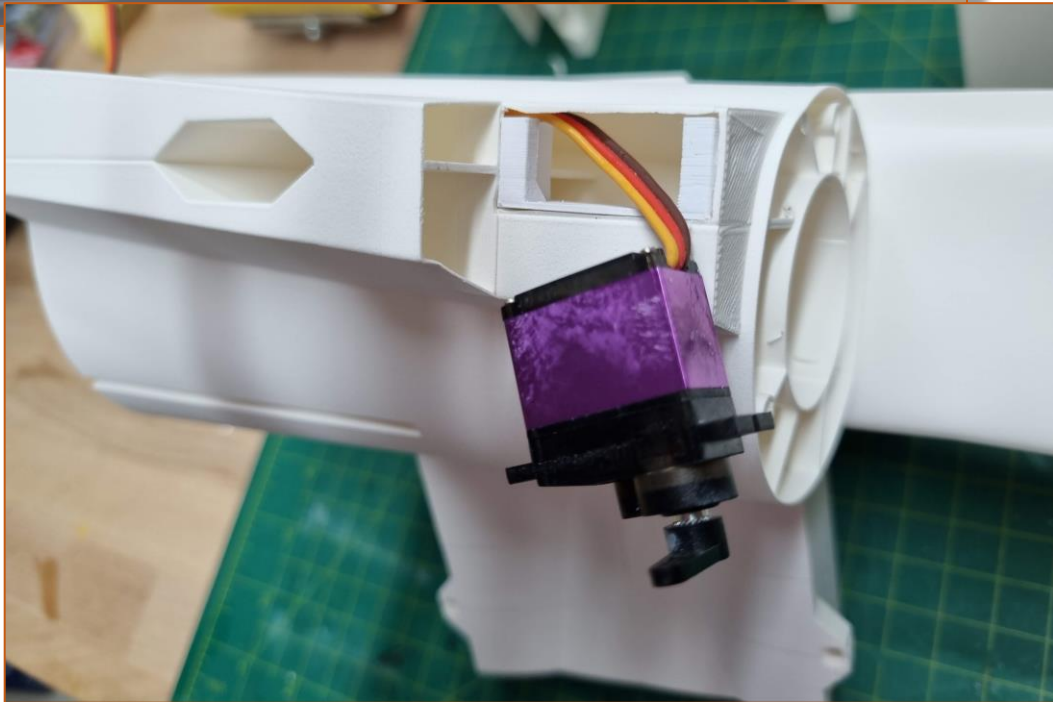
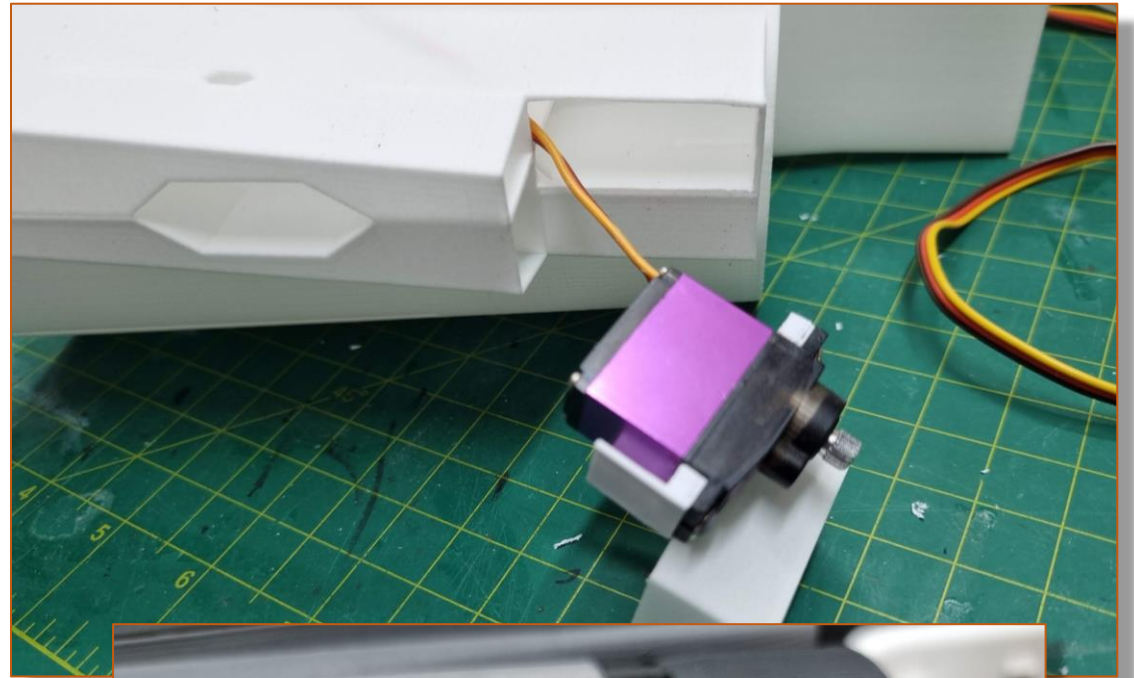
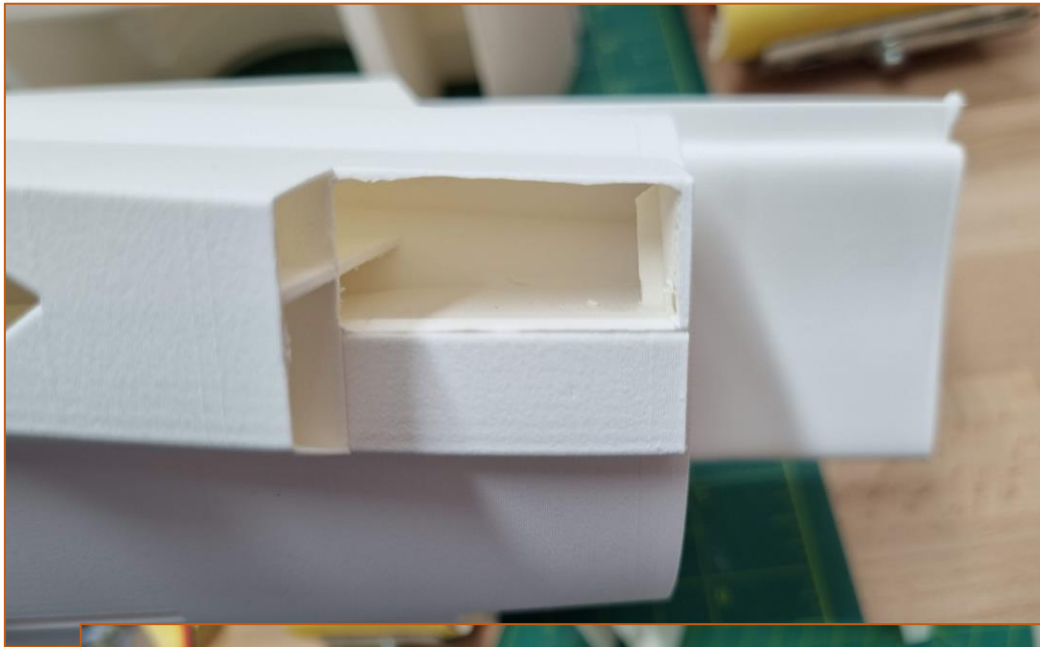


Using a soldering Iron, cut holes just rearward of the fan EDF structure, only just large enough to first Feed the motor leads, then hold the motor leads

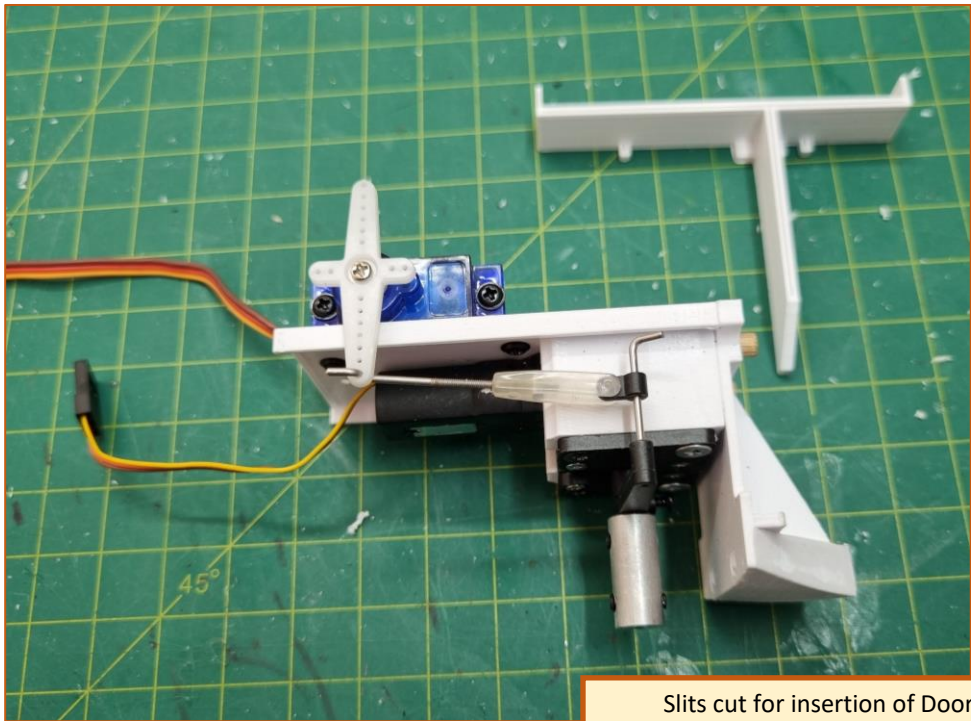


Mount Elevon servos, add extension leads and install EDF unit with motor leads before gluing Fuse6, Fuse5, Fuse4B & Fuse4A together

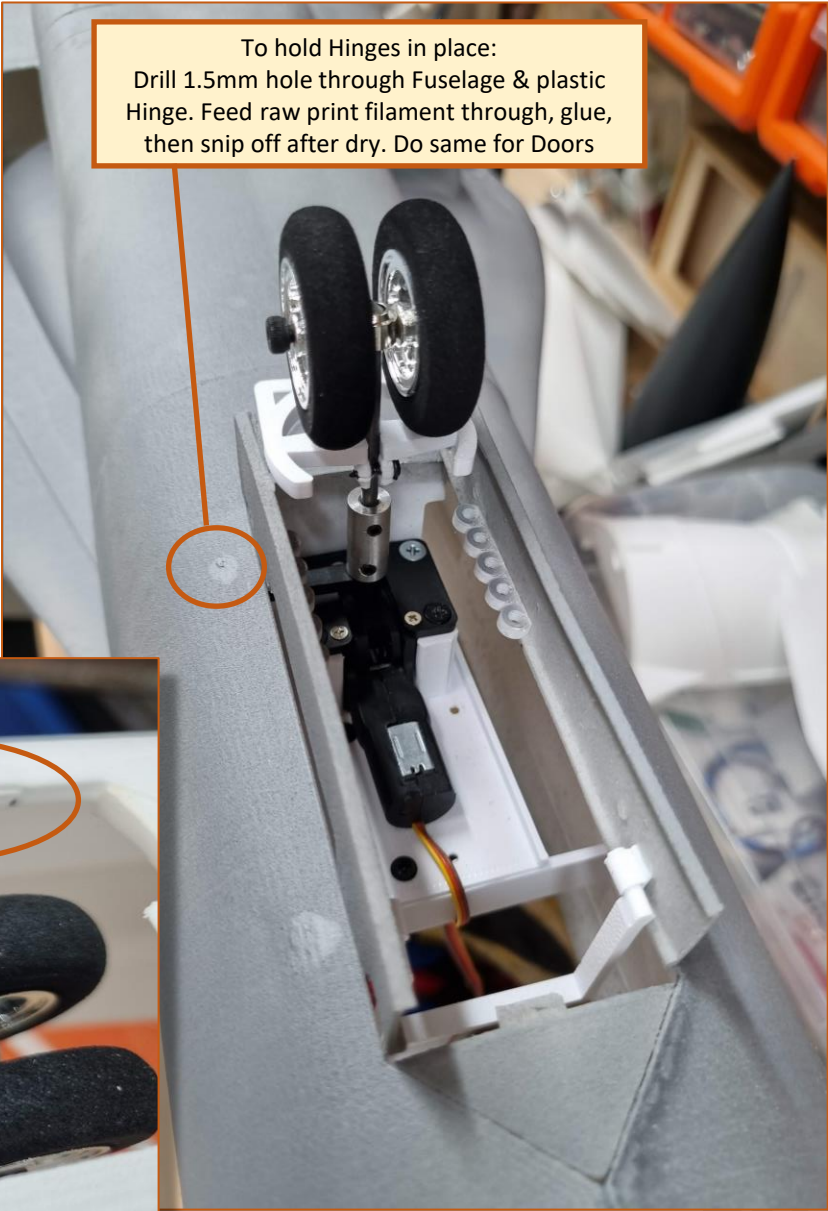








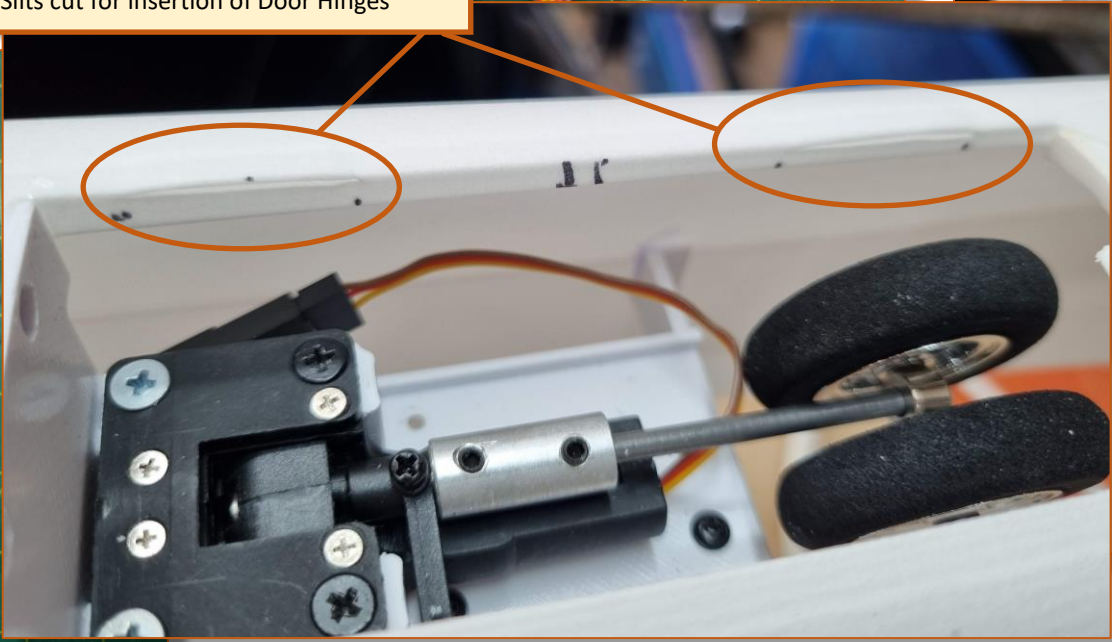
Slits cut for insertion of Door Hinges



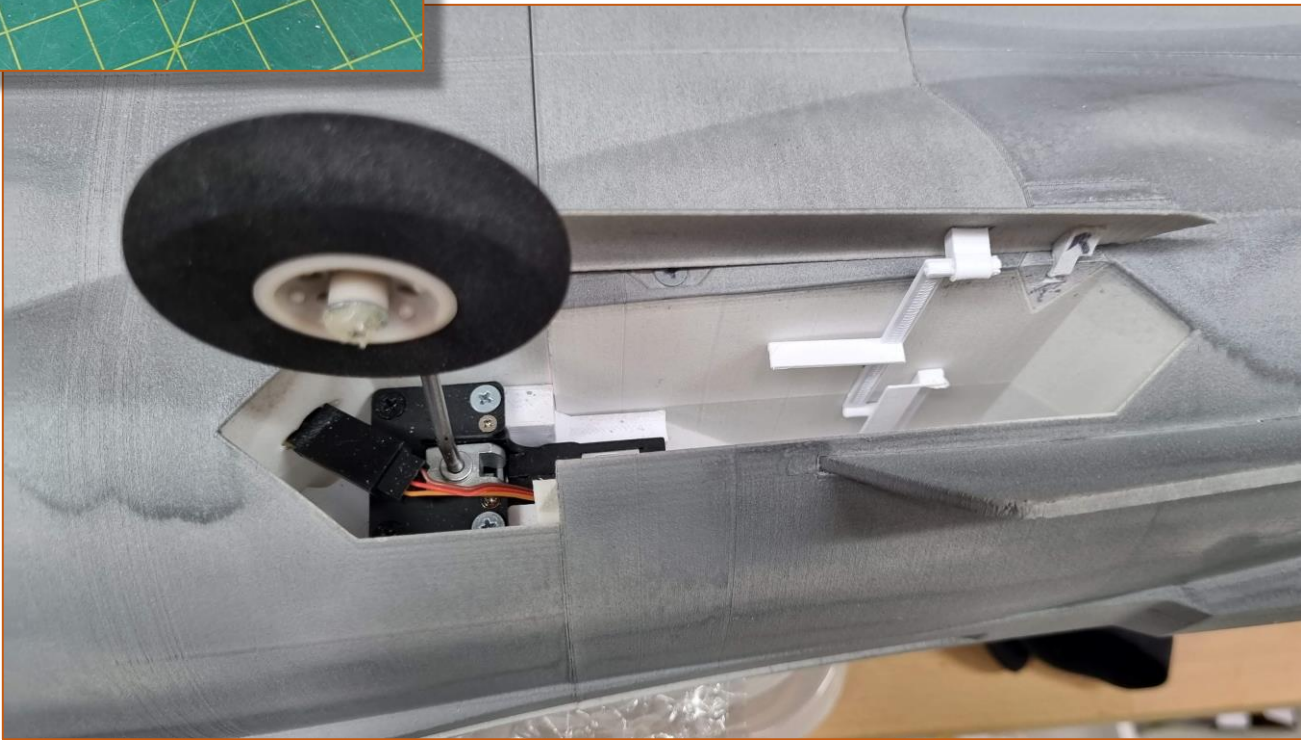
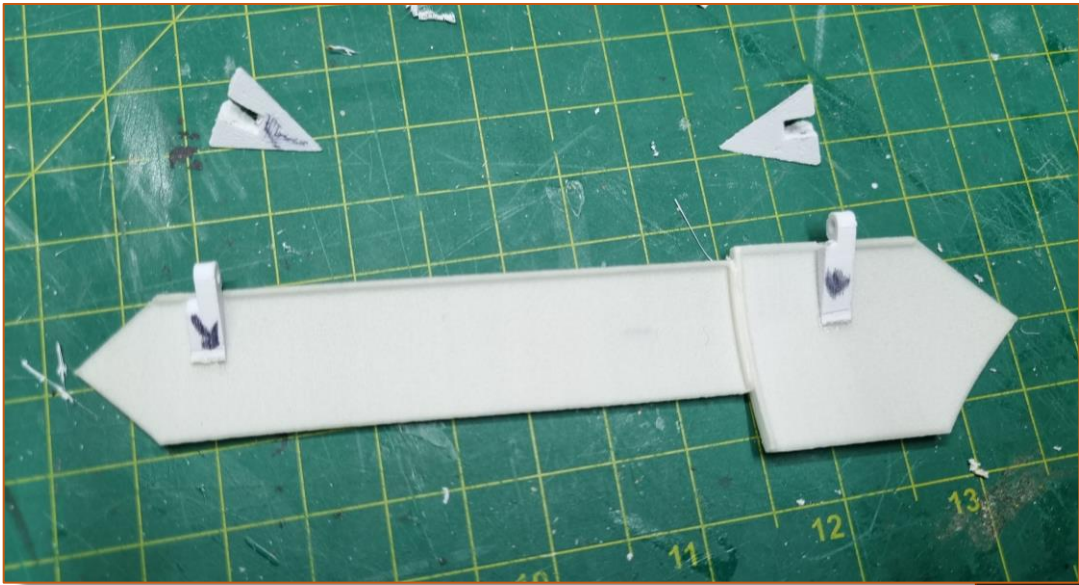
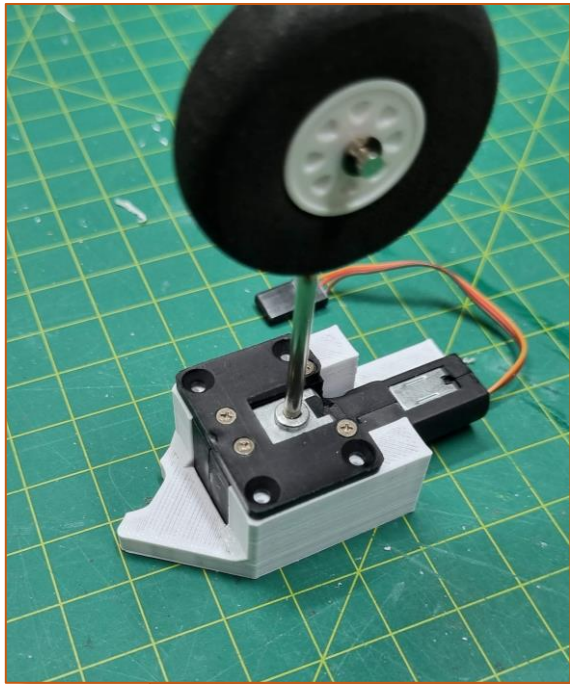
To hold Hinges in place:  
Drill 1.5mm hole through Fuselage & plastic Hinge. Feed raw print filament through, glue, then snip off after dry. Do same for Doors



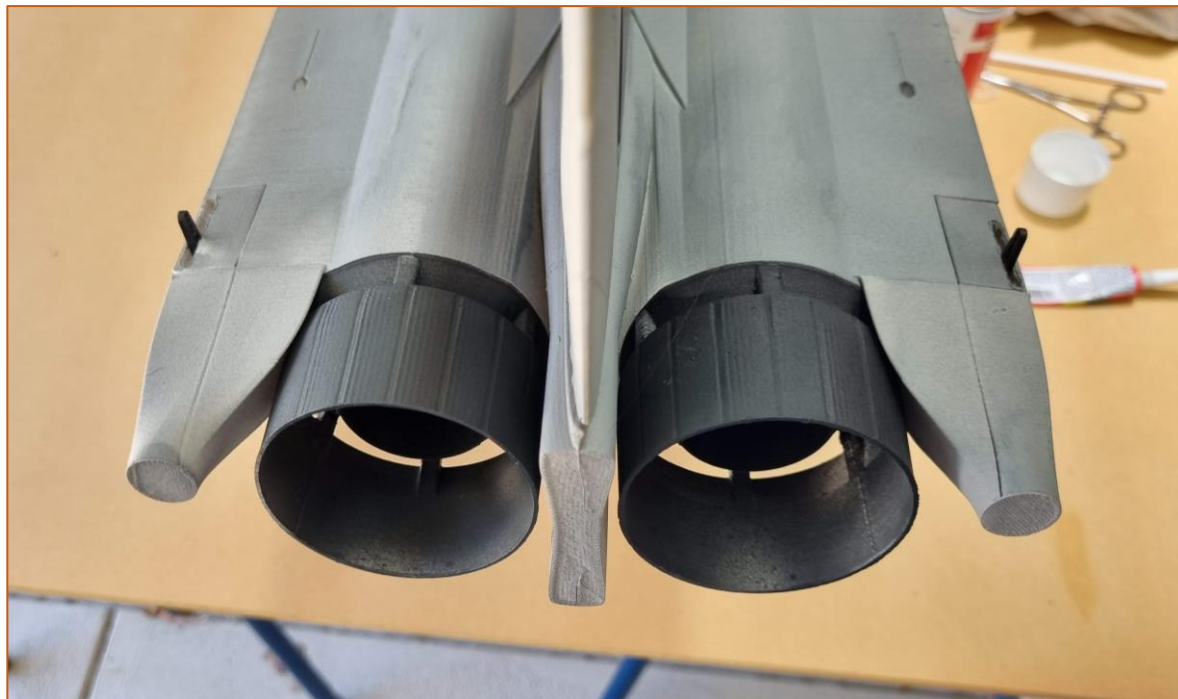
Double screwed Collar used to make nose wheel











MrWaz11 - YouTube

