

F-111 Aardvark
3D Printed RC EDF Model
Build Manual



SPECS



- 1200mm span (47in)
- 1350mm length
- 64mm EDF unit
- Servo driven Swing-Wing mechanism
- Elevon control w/ optional Rudder
- 2 Versions included
 - No undercarriage : ~1kg AUW
 - With Undercarriage : ~1.7kg AUW
- LW-PLA for most of model, PLA+ for select
- Optimised for Spiral / Vase print mode

Notes

- Suits 3D Printer with minimum Bed size of approx; 220mm square or 300mm round (Check *SmallerBed* folder for possible alternate STLs)
- This model is not recommended for a first-time builder. This manual assumes you already have basic modelling skills and are familiar with printing, assembling, fitting-out and flying 3D Printed model aircraft.
- Check hosting sites (like CULTS3D.com) and RCGROUPS.com/3D Printed Planes for news and updates ([LINK](#))
- And please share your masterpieces photos and flight videos with the community. I only started making 3D printed models because of what I saw others doing ...
- While I enjoyed spending many 100's of hours designing this model, I'm selling the files for a very small amount, so please don't distribute copies of the files



PARTS

Electric Ducted Fans – 64mm

1 off either;

- FMS 3S or 4S 11 blade
 - 3900 or 3150KV
- QX-Motor 3S-6S 12 Blade
 - 2200 or 2400KV
- ESC to suit (typically 50-80amp)
- Motor lead extensions ~400mm
- With no undercarriage - recommend 3S-4S
- With undercarriage – recommend 4S-6S

Battery – Typical

- 1400mAh to 2600mAh
- Approx. 200 grams to 340 grams
- Shorter/fat drone batteries will also fit

Fittings – Typical

- Spring Wire for various : 1.6-1.8mm dia. – approx. 200mm
- Spring Wire for Undercarriage / 3mm typical
- 2x E/Z Connectors or similar for Elevon Horns
- 4x Dubro type hinges for Nose Gear Doors
- 4mm wooden dowel

Carbon

10mm Tube

- Swing Pivots: 10 x 8 x 32mm (2)

8mm Tube

- Wings: 8 x 6 x 465mm (2)
- Idle Gear: 8 x 6 x 26mm (1)

6mm Rod/Tube

- Elevons: 6 x 120mm (2)

4mm Rod

- Wings: 4 x 120mm (2) optional

Servos

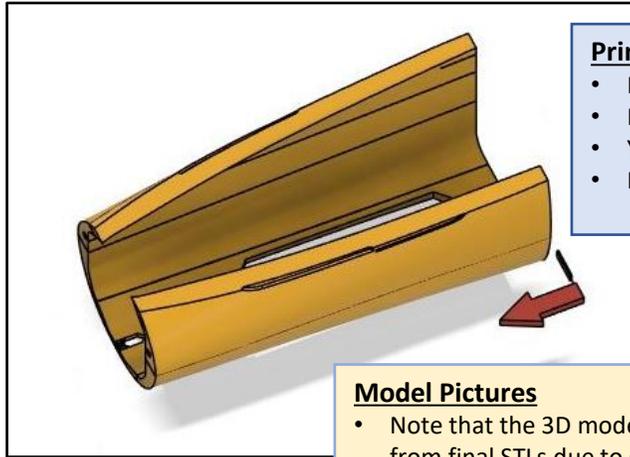
- 1x Hitec HS645MG (Swing Wing)
 - Optional Travel Expander/Tuner
- 2x Towerpro MG91 (Elevons)
 - 2x ~500mm extension leads
- Optional : 1 or 3 microservos for Retract Doors

Electric Retracts

- 1x set of 25 gram retracts with steerable nose gear
 - Often found at AliExpress
- Wheels - 2x 52mmx14mm (max) / 2x 35mmx9mm
 - 3mm Spring Wire



Typical Arrangements

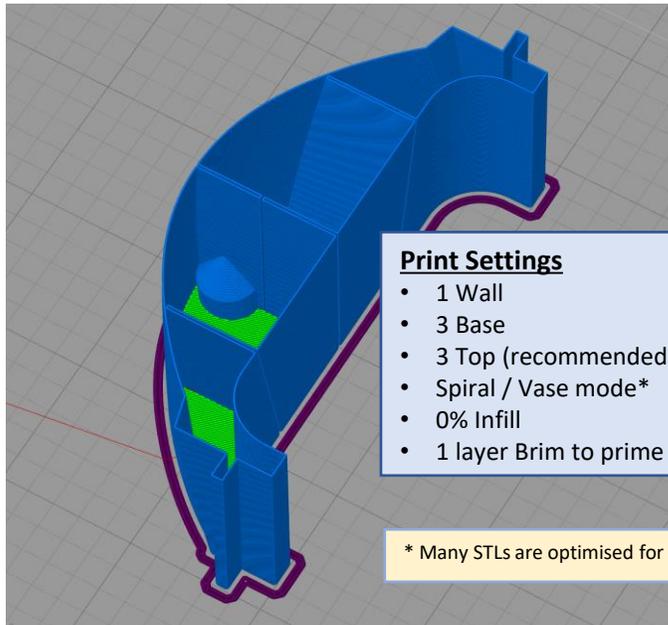


Printing Orientation

- Red Arrow BASE = Print Bed
- Red Arrow Direction = Z Axis UP
- Yellow indicates component focus
- No Arrow = Pick simplest print arrangement

Model Pictures

- Note that the 3D model pictures may vary slightly from final STLs due to subsequent improvements



Print Settings

- 1 Wall
- 3 Base
- 3 Top (recommended. 0 may work)
- Spiral / Vase mode*
- 0% Infill
- 1 layer Brim to prime nozzle

* Many STLs are optimised for Spiral / Vase mode

Notes

* Many STLs are optimised for Spiral / Vase mode. While most main body STLs recommend 3 TOP LAYERS for strength reasons, in most cases this could be reduced to 0/zero.

Typical Print Settings

>>LW-PLA

- 0.4 nozzle / 0.4 width
- 0.2 layer height
- 0.6 Extrusion Multiplier
- 250°C nozzle / 60°C bed
- First Layer: 200% height & Width
- No Retraction, No Cooling

>>LW-PLA-HT

- 0.4 nozzle / 0.4 width
- 0.25 layer height
- 0.65 Extrusion Multiplier
- 230°C nozzle / 60°C bed
- First Layer: 200% height & Width
- No Retraction, 33% Cooling

Coloured Guides

Do Not Glue

Glue

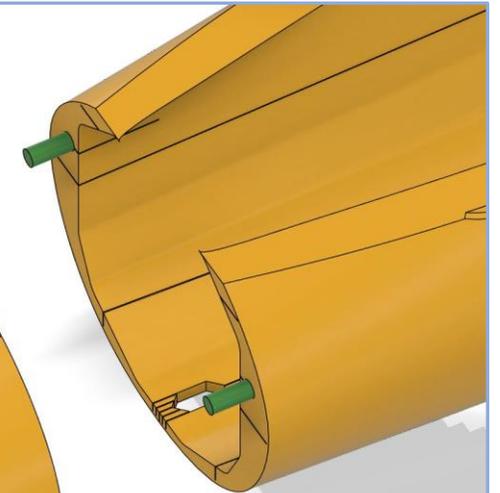
- Print Parameters

STL file name

INFO

Doweling

- 4mm dowels are used to align large pieces
- Typical length : ~18mm
- Wood dowel is adequate
- If not firm fitting, glue dowel in 1 side first



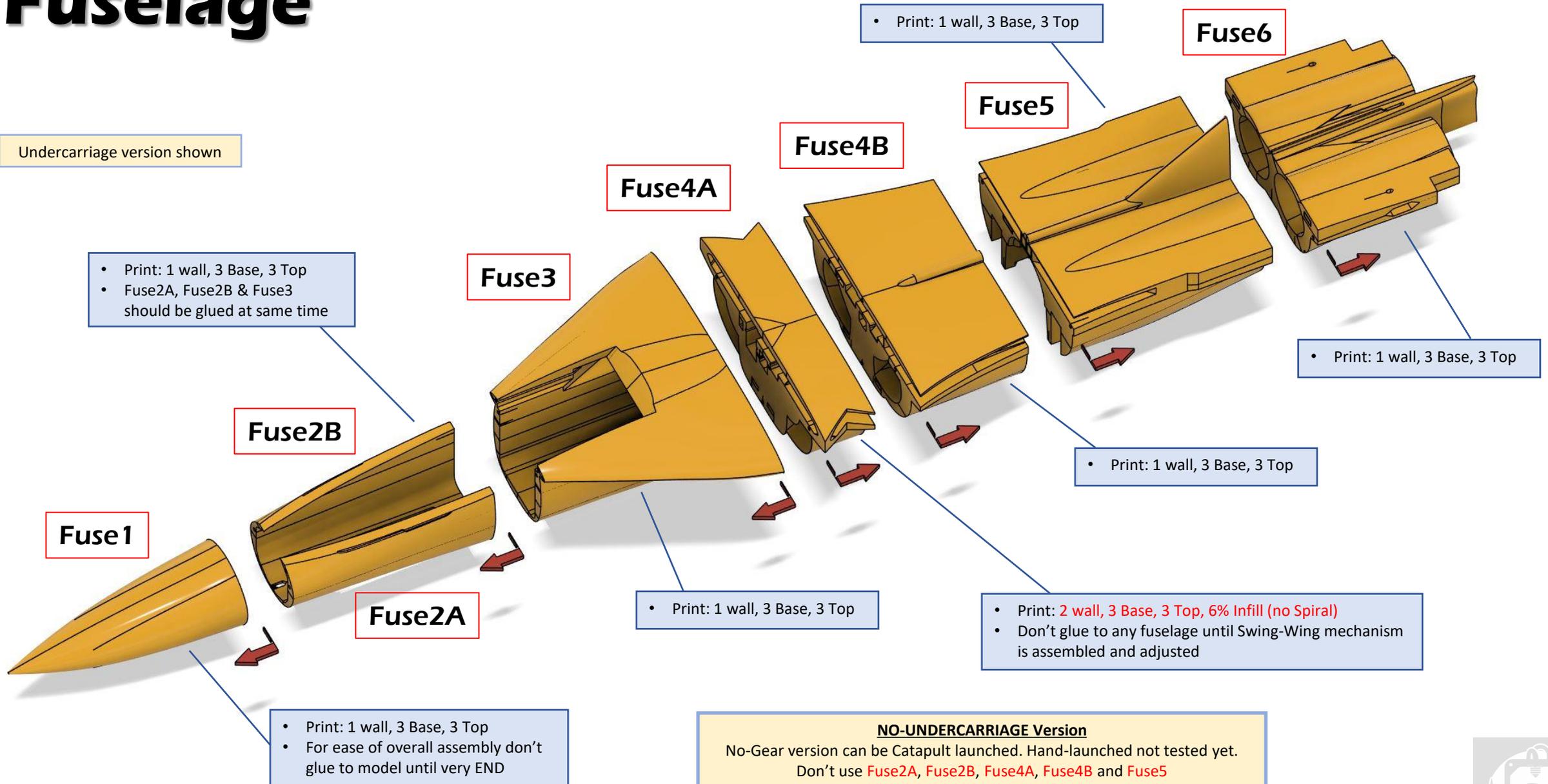
Fuselage Gluing

- Sand TOP level/flat
- Apply CA to only where faces touch
- Use dowels to align
- Apply firm pressure
- Use Accelerator if preferred



Fuselage

Undercarriage version shown

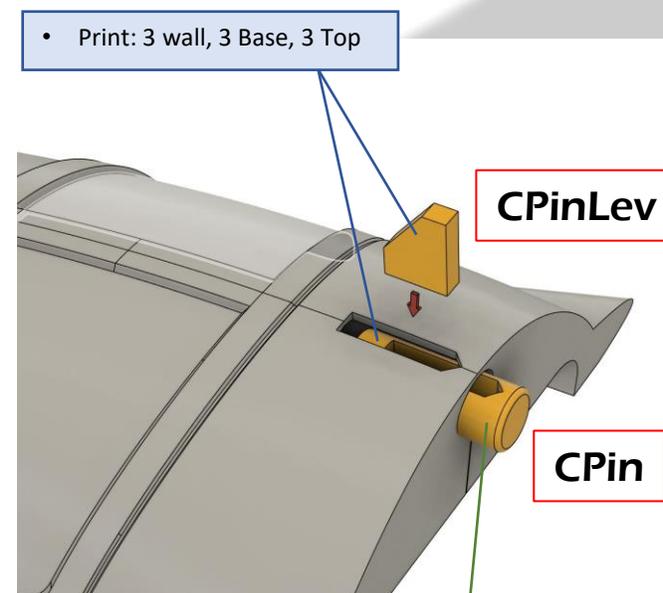
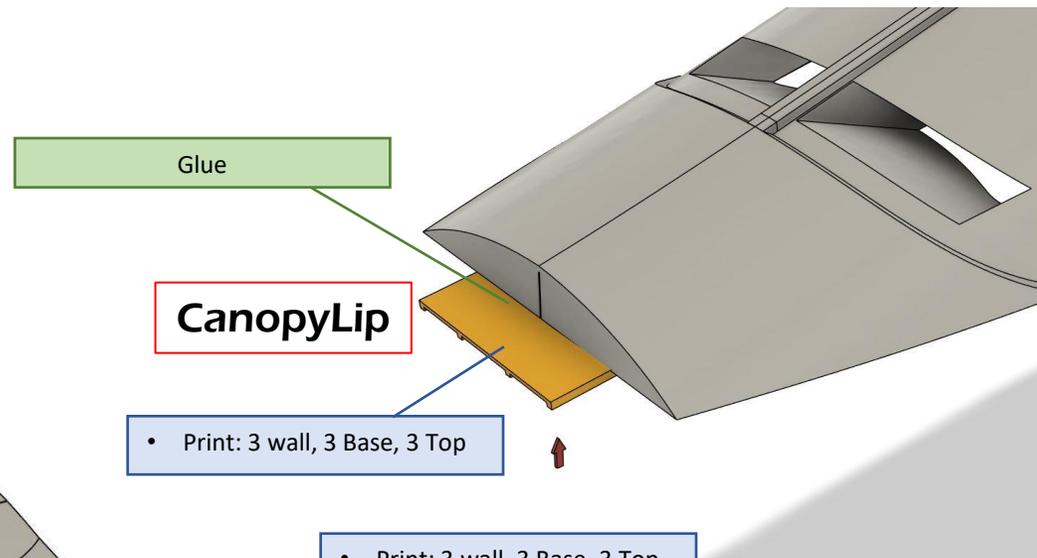
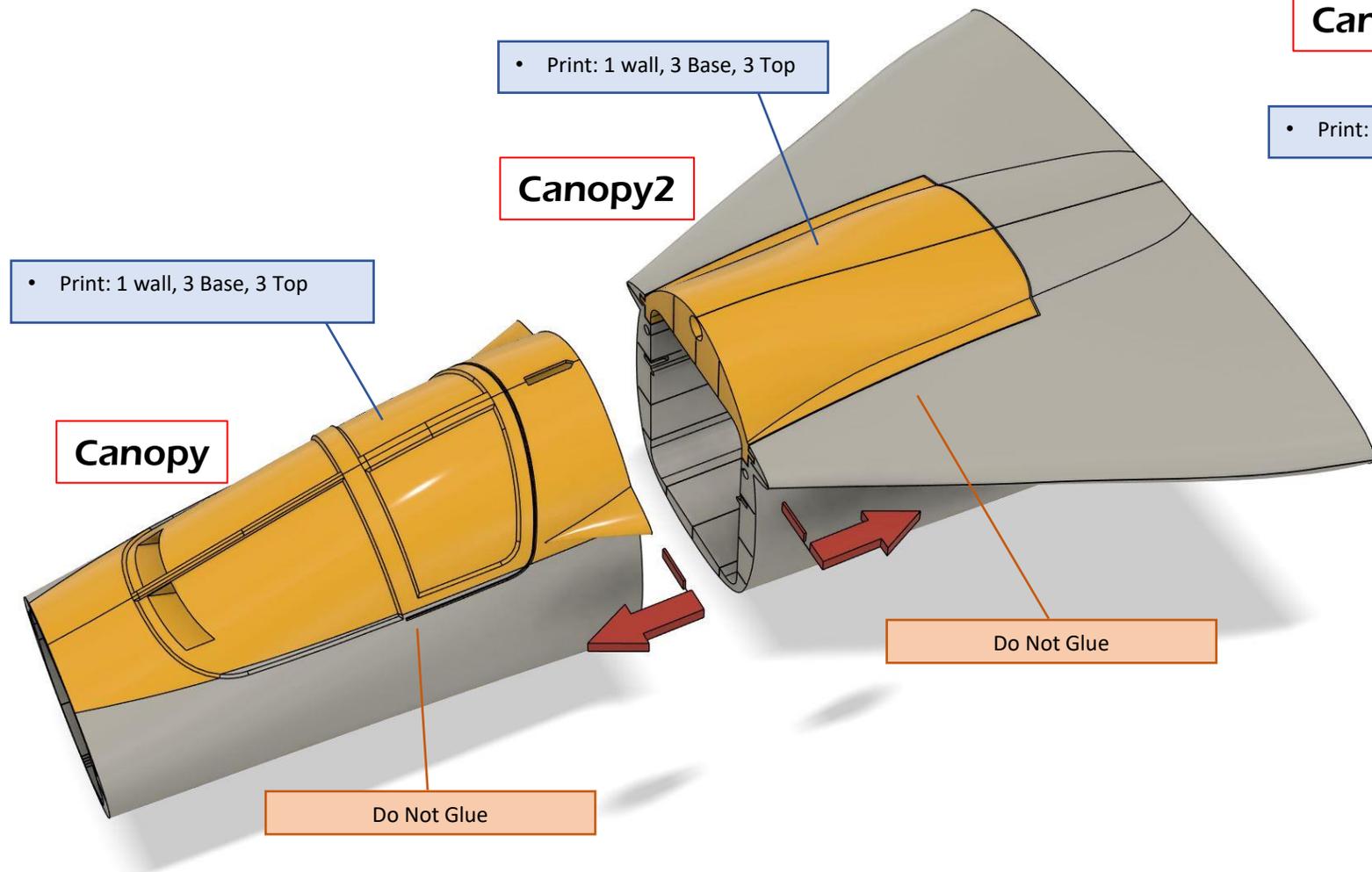


NO-UNDERCARRIAGE Version

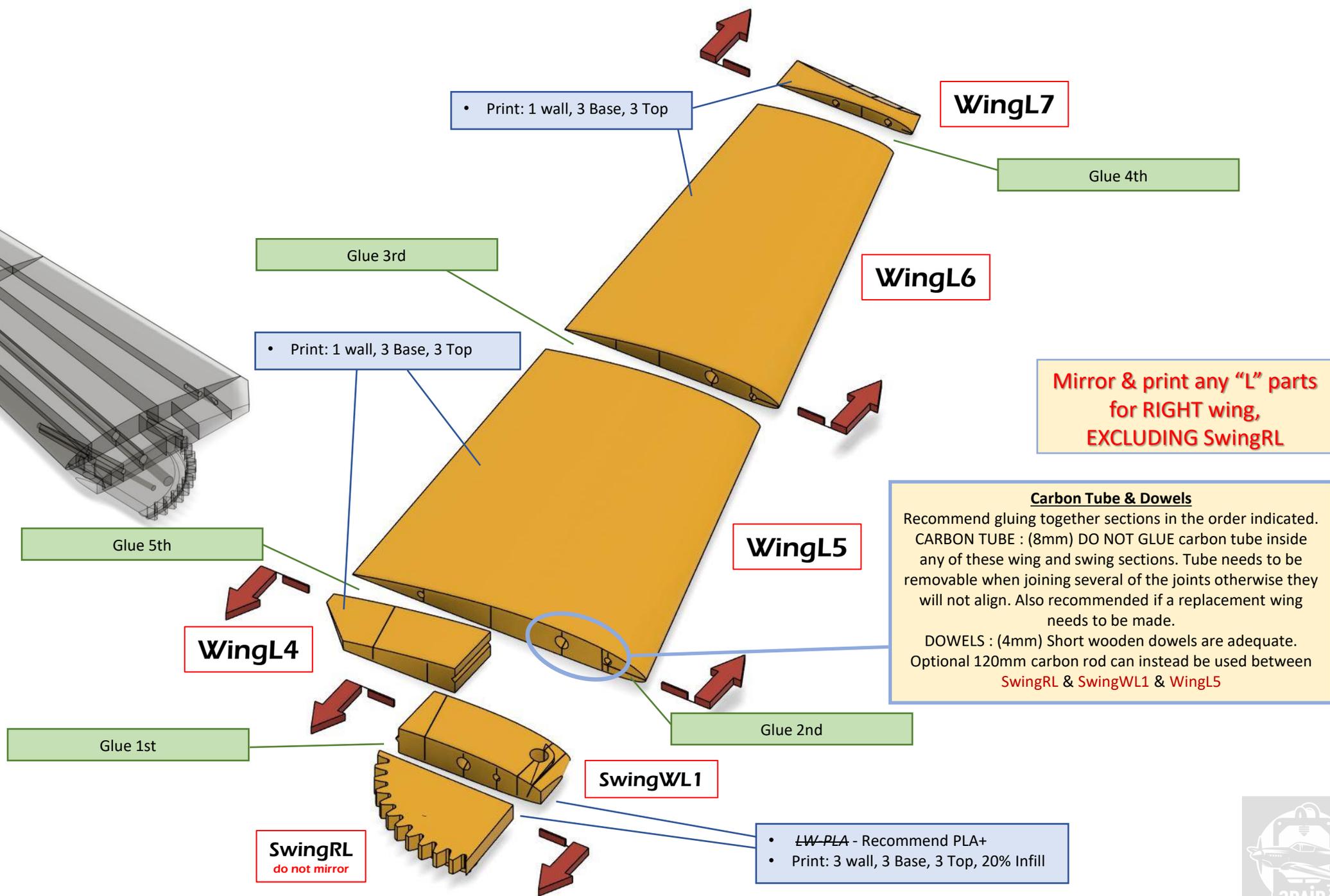
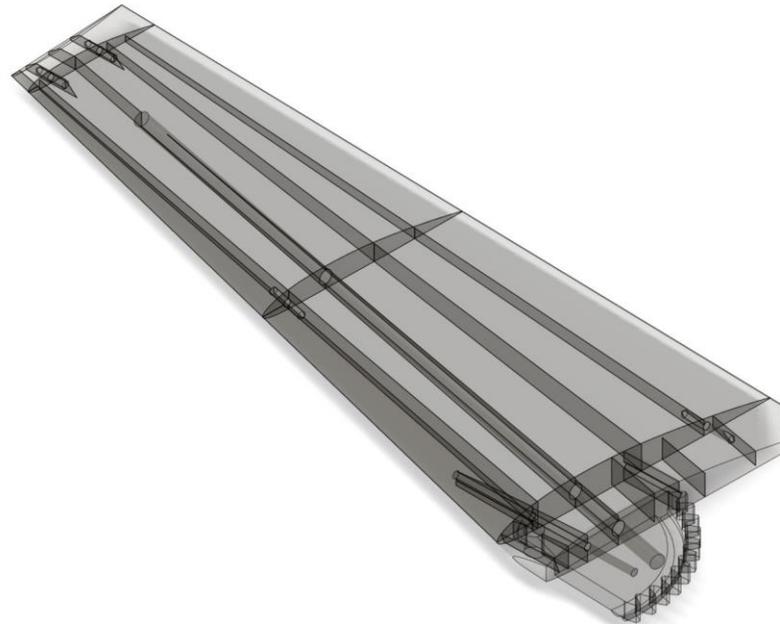
No-Gear version can be Catapult launched. Hand-launched not tested yet.
Don't use **Fuse2A**, **Fuse2B**, **Fuse4A**, **Fuse4B** and **Fuse5**
Instead use **Fuse2**, **Fuse4**, and **Fuse5** found in "NoGear" folder.
TowHook can be printed with PLA+. Add wire to make a small hook.



Canopy

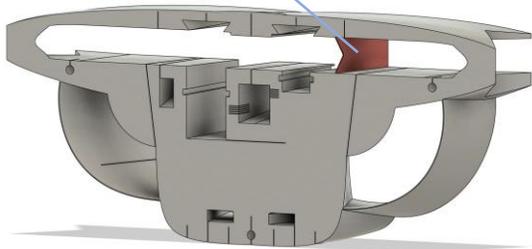


Wings

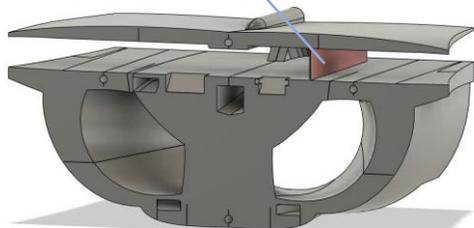


Fuse4A Arrangements

Fuse4A - Remove fillet after printing



Fuse4B - Remove fillet only after gluing to Fuse4A & Fuse5



All these STLs

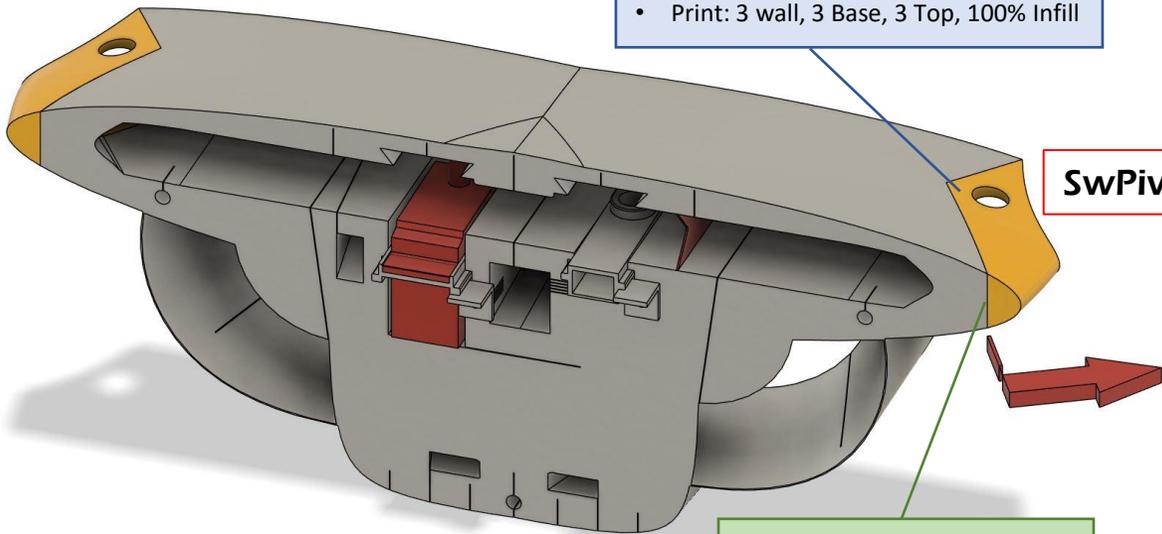
- ~~LW-PLA~~ - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

(Note: top half of Fuse4A STL remove for this view only)

SwPivotL
mirror

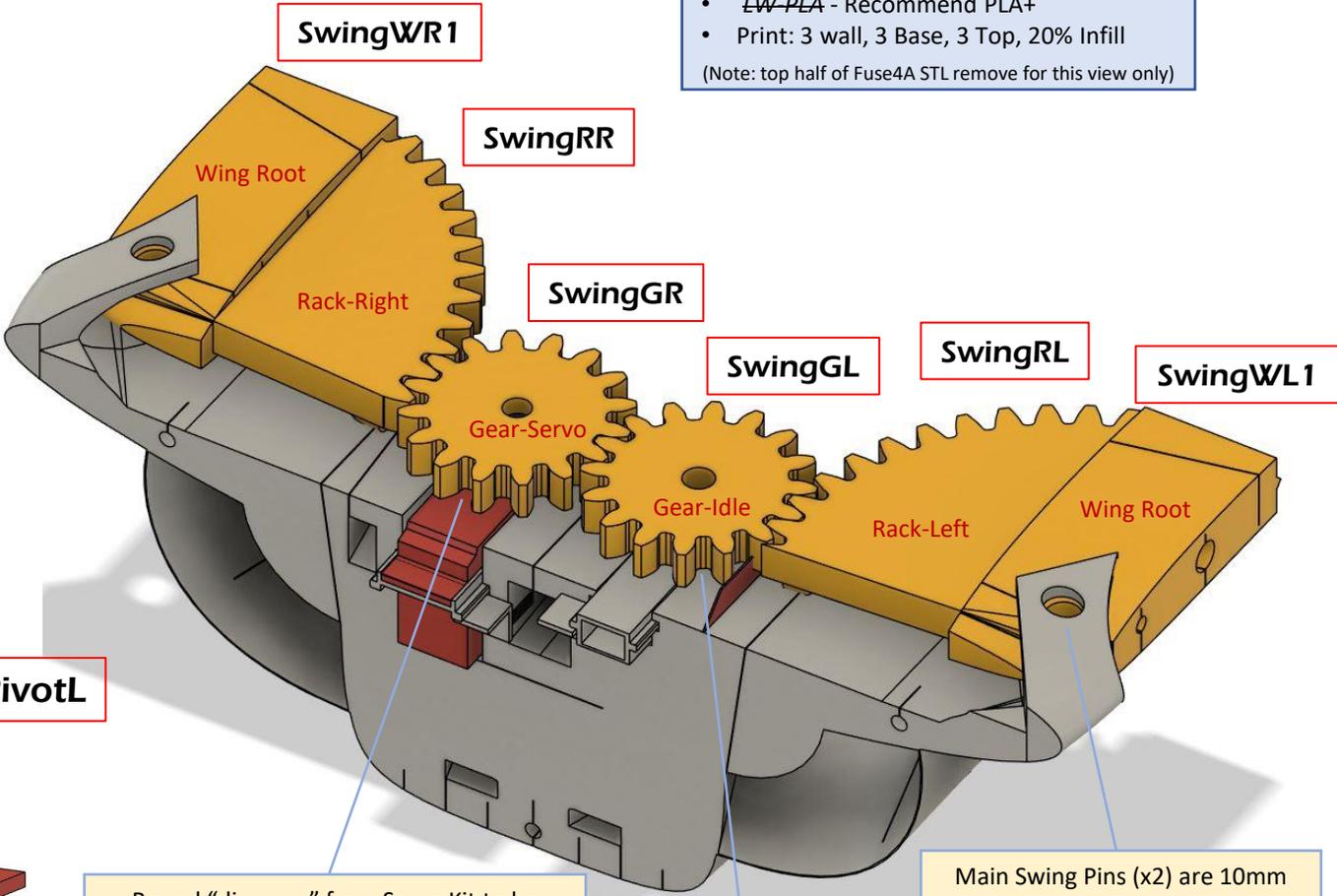
• ~~LW-PLA~~ - Recommend PLA+

• Print: 3 wall, 3 Base, 3 Top, 100% Infill



Sand faces for tight fit & Glue

SwPivotL



Round "disc-arm" from Servo Kit to be screwed into underside of *SwingGR*

Main Swing Pins (x2) are 10mm Carbon Tube 32mm long

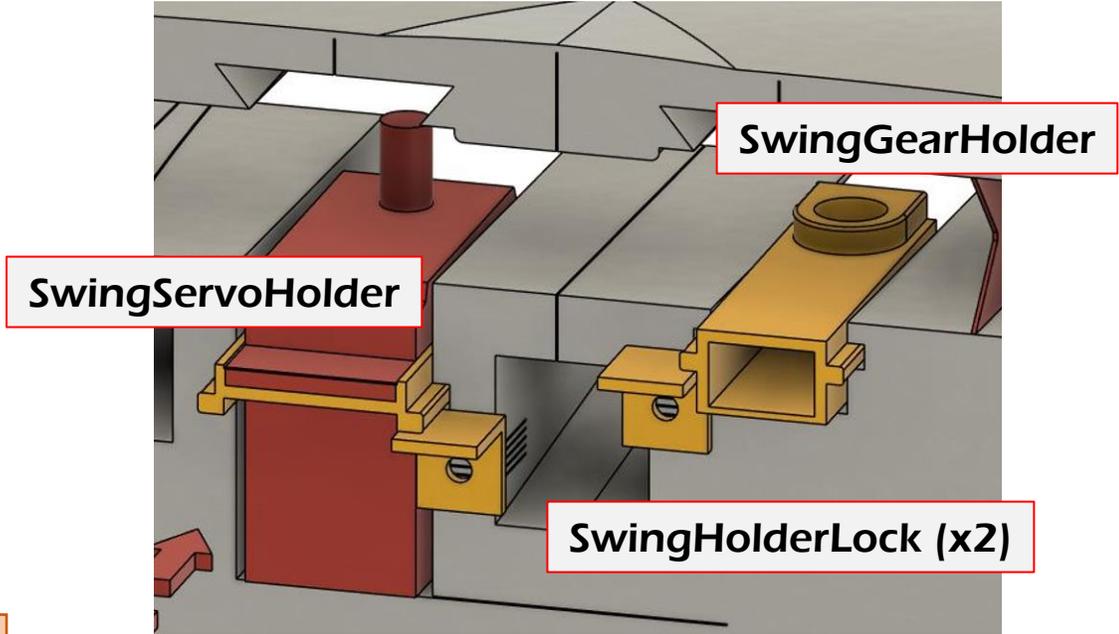
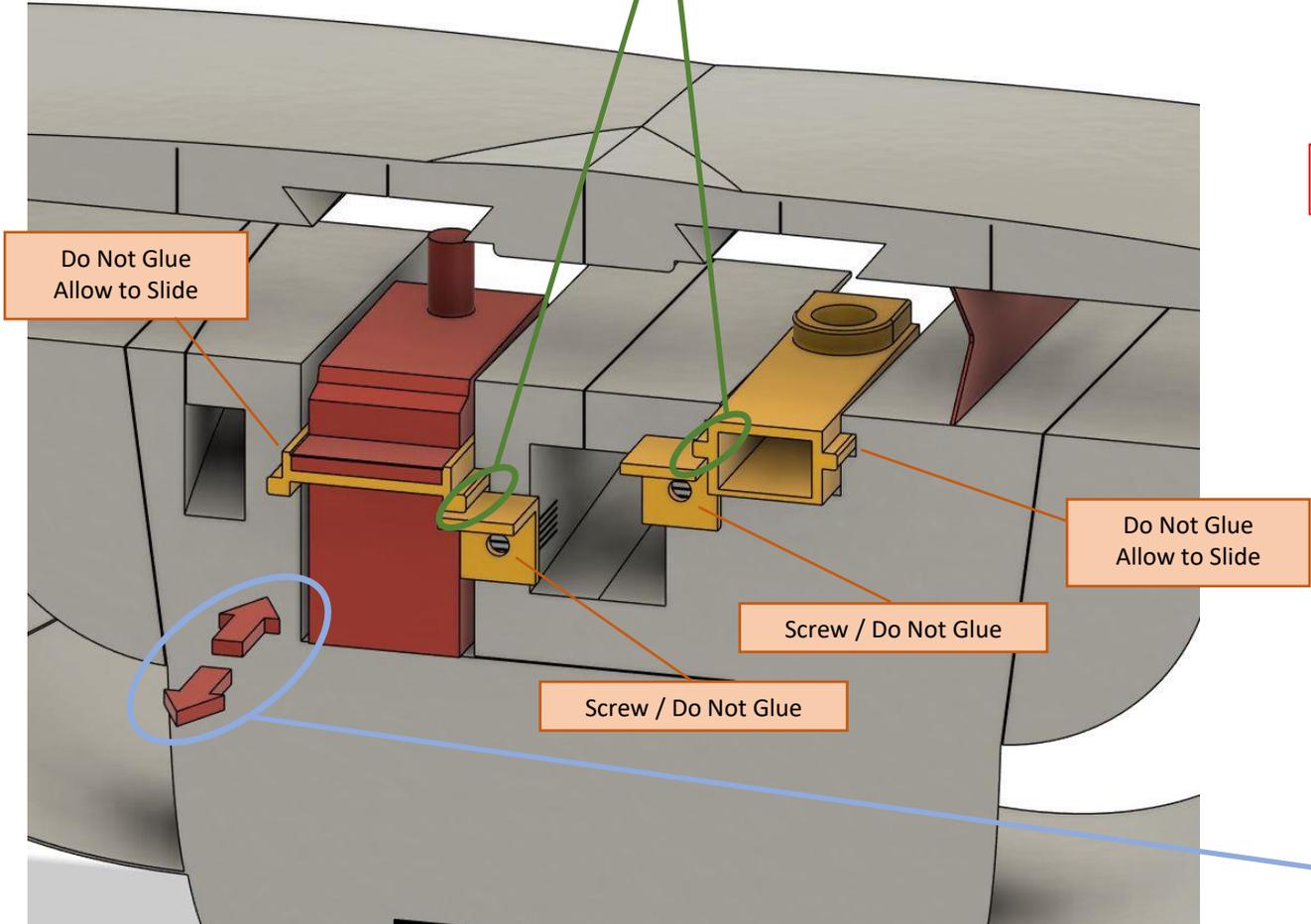
SwingGearHolder to interference-fit x1 Pin of 8mm Carbon Tube 26mm long. *SwingGL* is to freely rotate on this Pin.



Fuse4A Arrangements

- All these STLs**
- ~~LW-PLA~~ - Recommend PLA+
 - Print: 2 wall, 3 Base, 3 Top, 100% Infill

Gear Positioners
Once Gears have been adjusted, lightly GLUE each **SWINGHOLDERLOCK** to the **HOLDERS**



Positioning Servo & Idle Gears

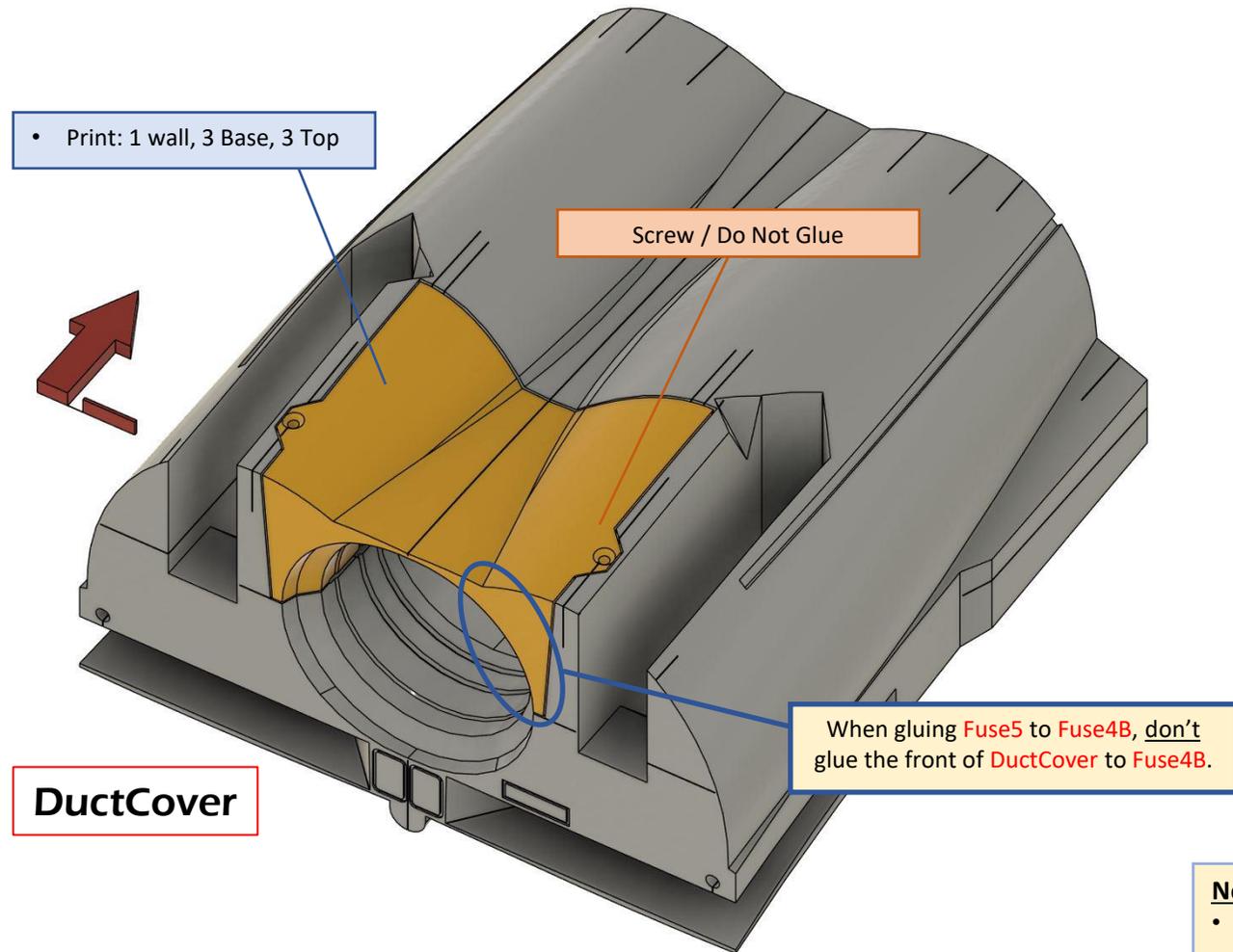
Test the Servo action only once all Swing-Wing parts and both assembled Wings are in place on **FUSE4A**.

FRICITION : Adjust both gears in and out **IN PARALLEL** to achieve the right amount of friction. Too little and there will be too much free movement of the Wing. And too much will overload the Servo

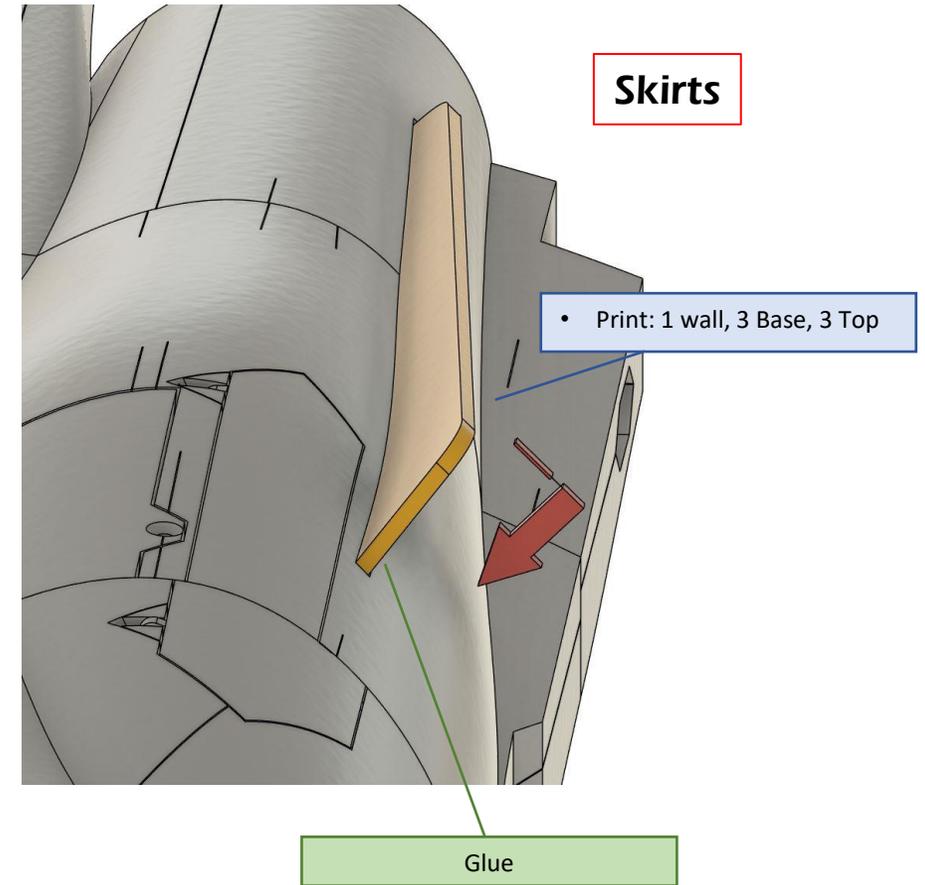
POSITION : Adjust servo limits such that **FULL FORWARD** (without jamming) is one end of servo travel, with whatever the other end allows being rearward swing. Servo Travel Extender could be used for additional swing.



Fuse5 Extras



x2



Note

- Skirts cross both Fuse5 and Fuse6



EDF Mounting

Assembly sequence

EDF should be installed in Fuse5 before Fuse5 is glued to Fuse4B

EDF Mount Tabs

Reinforced clearance areas are provided to accommodate the typical EDF body mounting tabs of all brands of EDF mentioned in the parts section. Choices could include screwed or hot-glued. Or physically restrain the unit using extra plastic glued in front of Tabs. Test fit with DuctCover to ensure flush fit.

EDF Position

Leave the bellmouth (curved inlet) in place on the EDF body and slide the unit rearward until the bellmouth touches/seals to the Fuse5 body (& DuctCover). These provide more efficiency operation.

FMS Unit

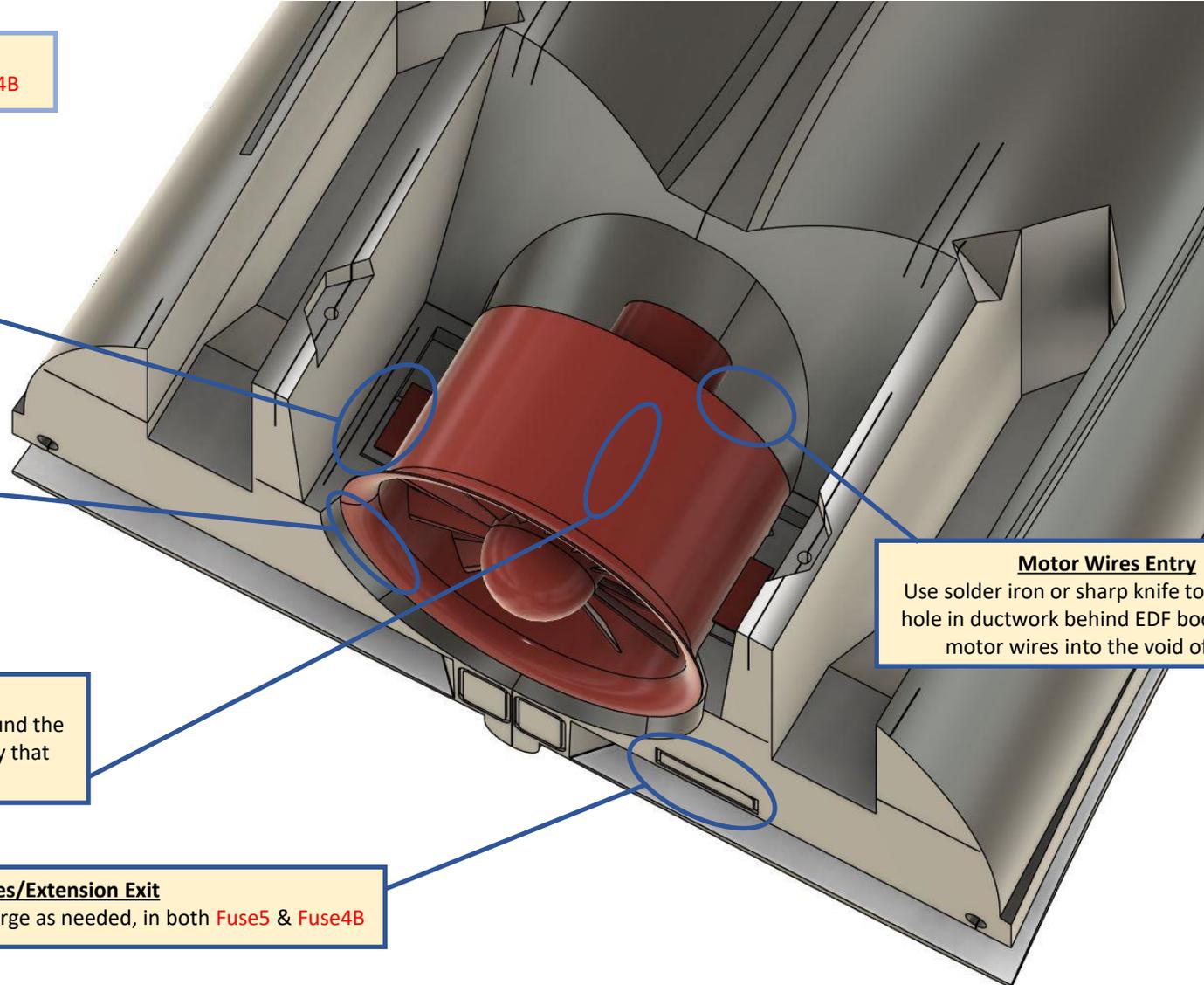
The 4S FMS branded unit has several circumferential ribs around the outside of the body. Grooves are provided in the Fuse5 body that should accommodate and avoid mounting issues.

Motor Wires/Extension Exit

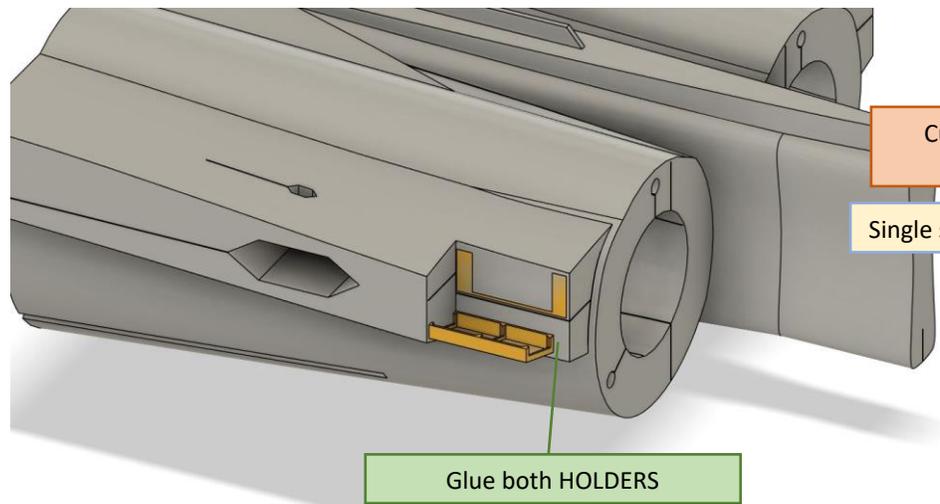
Remove panel / cut opening as large as needed, in both Fuse5 & Fuse4B

Motor Wires Entry

Use solder iron or sharp knife to cut a small hole in ductwork behind EDF body, allowing motor wires into the void of Fuse5



Elevons – Servo setup



Cut slot to suit servo arm
Do Not Glue

Single screw to hold ElevCoverL

ElevServoHolderL

CUT OUT - only UPPER section
and the small support behind

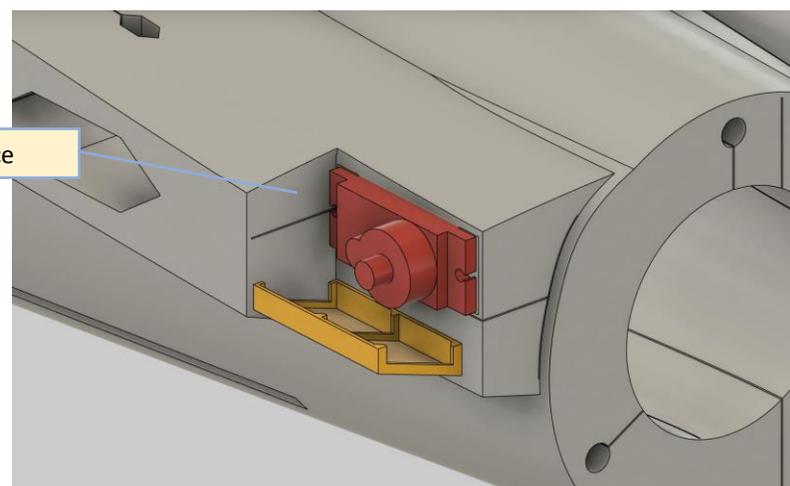
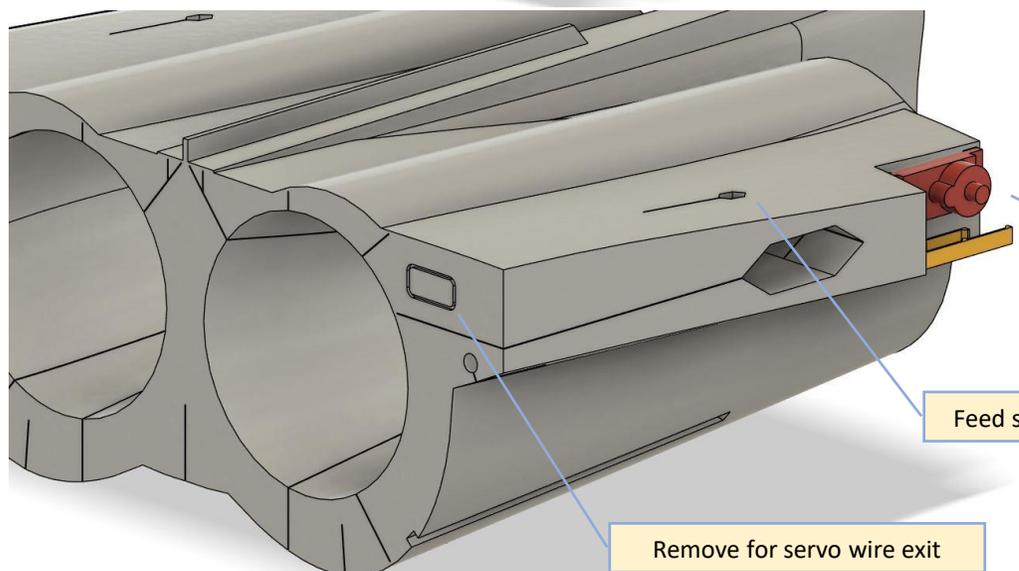
- LW-PLA - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 100% Infill

ElevCoverHolderL

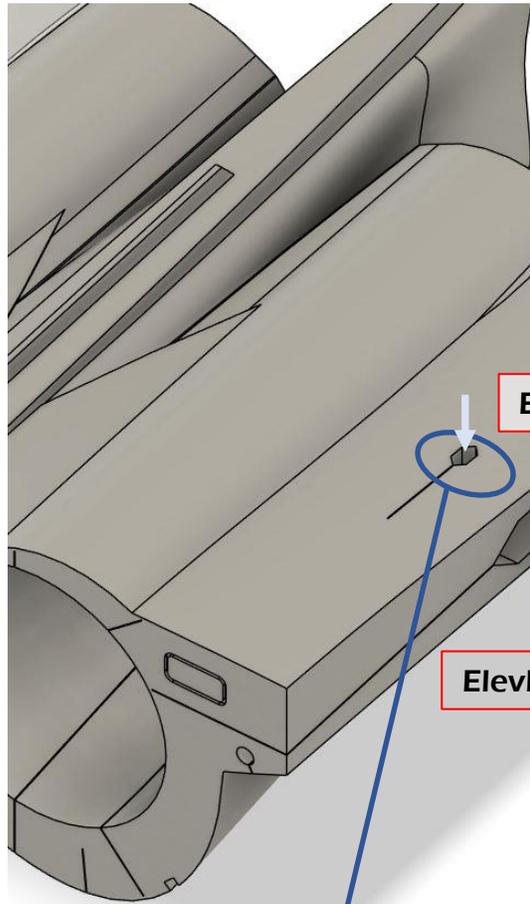
ElevCoverL

- Print: 1 wall, 3 Base, 0 Top

Mirror & print any "L" parts
for RIGHT elevon



Elevons



Elevon Arrangments
CARBON TUBE : (6mm) Glue Carbon Tube to **ElevL** and **ElevHorn** only at where these 3 pieces interface. Then glue **ElevSpacer** to **ElevHorn**.
PIVOT BLOCK : Drill or sand 6mm hole in **ElevPivotL** such that Carbon Tube begins to freely rotate. Drill or sand 6mm hole in **ElevHolder** such that it is firm enough on the Carbon Tube to stop the Elevon easily exiting the pivot block, but not too firm that Elevon can't be pulled out of its pivot block with reasonable force.
Carbon Tube Length : Cut just short of its internal exit of **ElevPivotL**.

Mirror & print any "L" parts for RIGHT Elevon

All these STLs
• ~~LW-PLA~~ - Recommend PLA+
• Print: 3 wall, 3 Base, 3 Top, 20% Infill

ElevHolder

Do Not Glue

ElevPivotL

ElevHorn

ElevSpacer

Glue

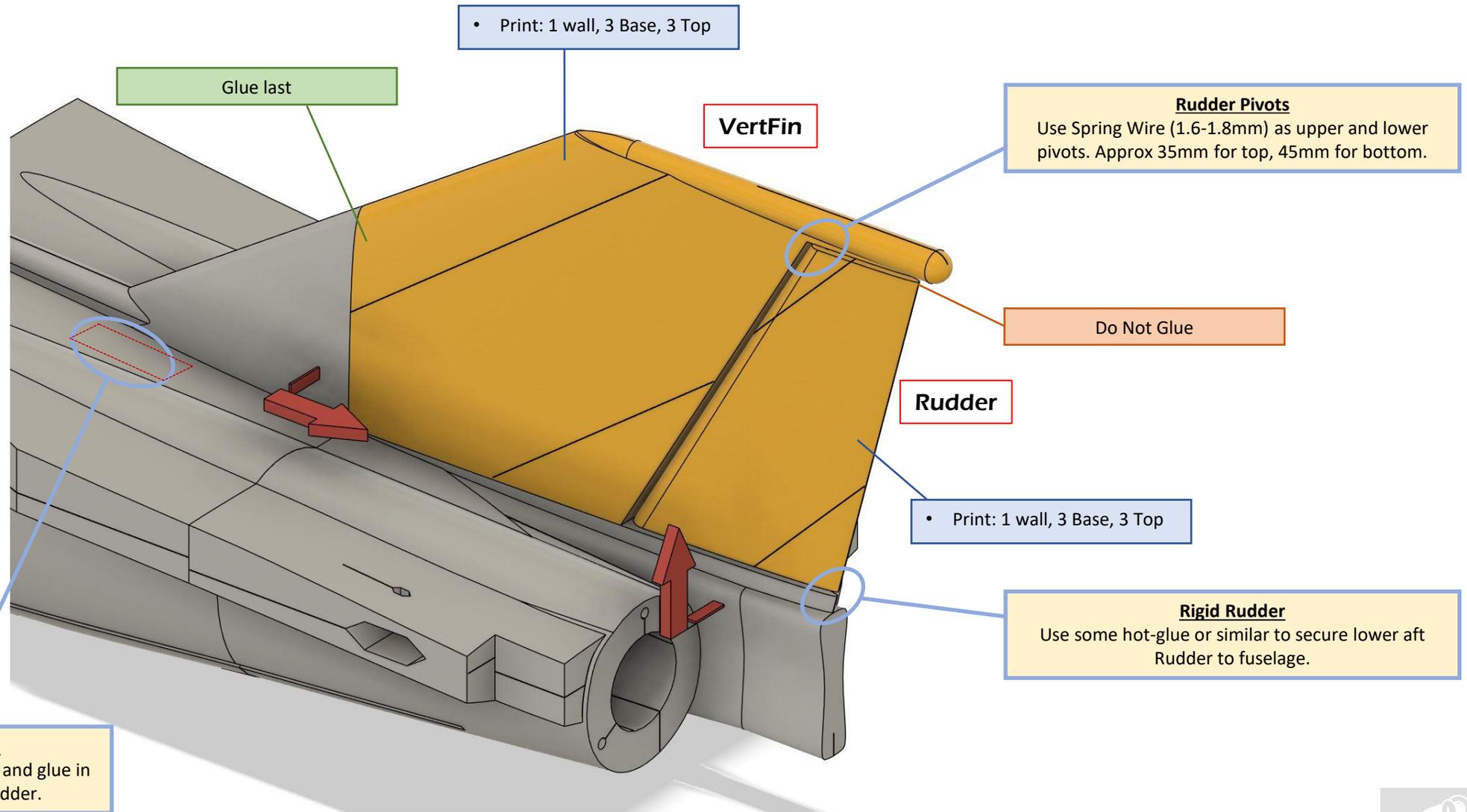
• Print: 1 wall, 3 Base, 3 Top

ElevL

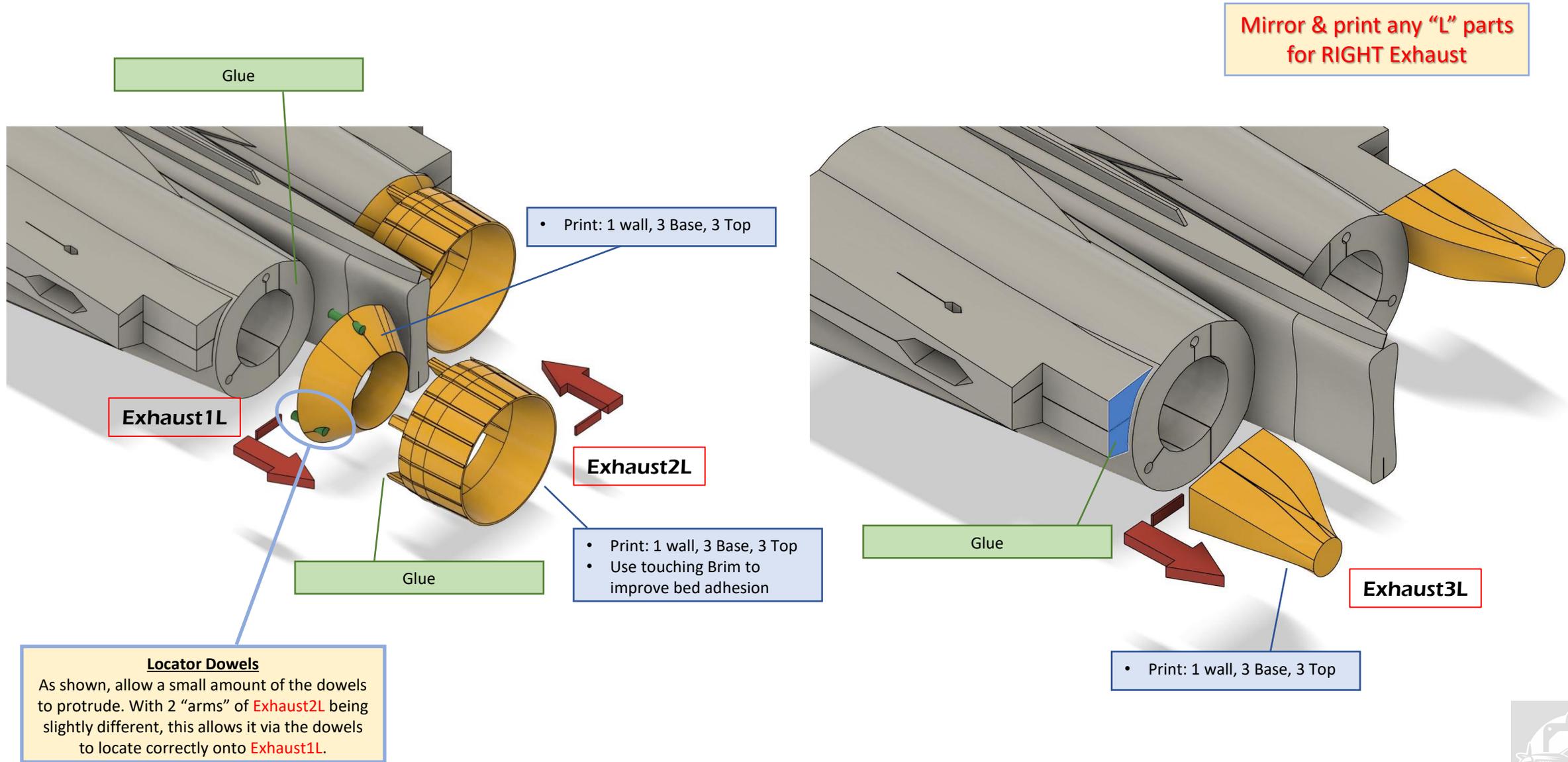
Attaching Elevon to Fuselage
During final assembly : Ensure **ElevPivotL** slides firmly into main fuselage. **Recommend Do Not Glue**. Outside of pivot block should be flush with fuselage. Drill small hole in indicated location and use small screw to hold pivot block in place



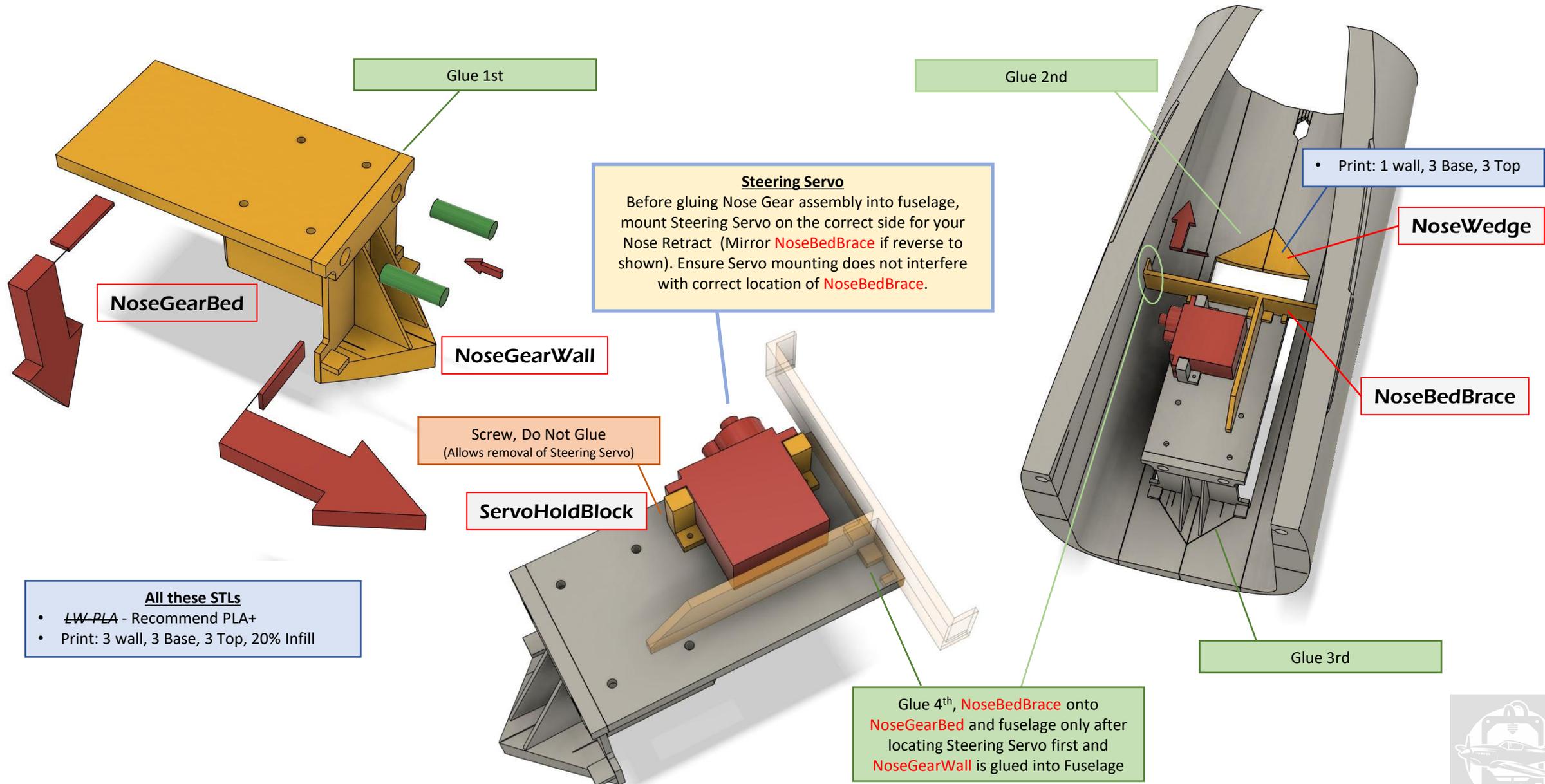
Tail



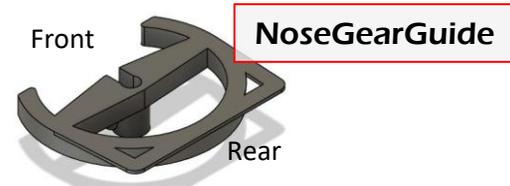
Exhaust



Nose Gear



Nose Gear

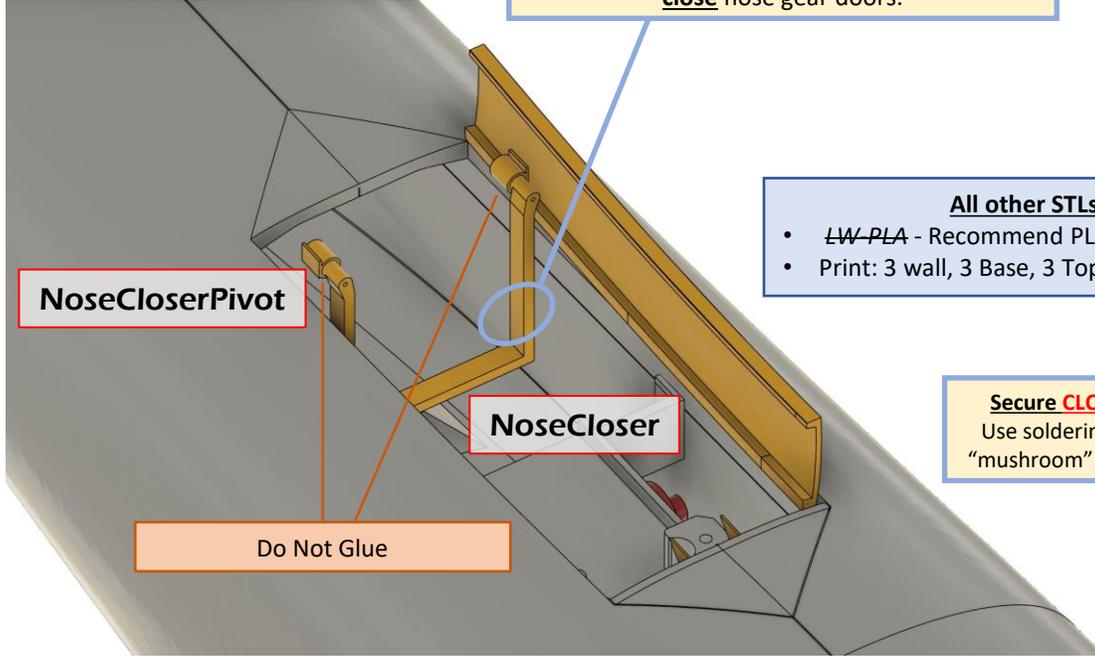


NoseGearGuide

Mirror & print any "L" parts for RIGHT Door

Use screw to attach **NoseGearGuide** to 3mm gear wire. Should be aligned to lowest portion of door when open

Nose Door Open & Close
 Use **NoseGearGuide** attached to Retract Leg to push **open** nose gear doors.
 Use nose wheel(s) pushing on **NoseCloser**. To **close** nose gear doors.



NoseCloserPivot

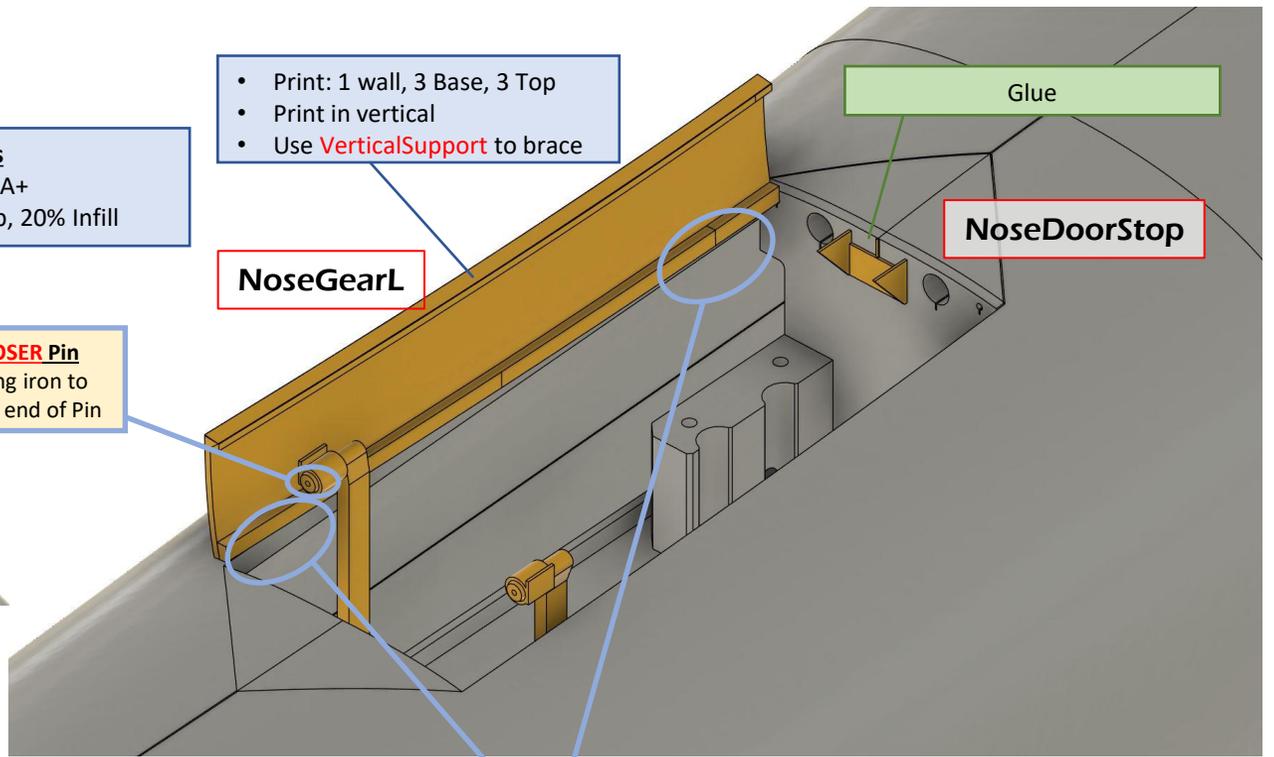
NoseCloser

Do Not Glue

All other STLs

- ~~LW-PLA~~ - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

Secure CLOSER Pin
 Use soldering iron to "mushroom" end of Pin



- Print: 1 wall, 3 Base, 3 Top
- Print in vertical
- Use **VerticalSupport** to brace

NoseGearL

NoseDoorStop

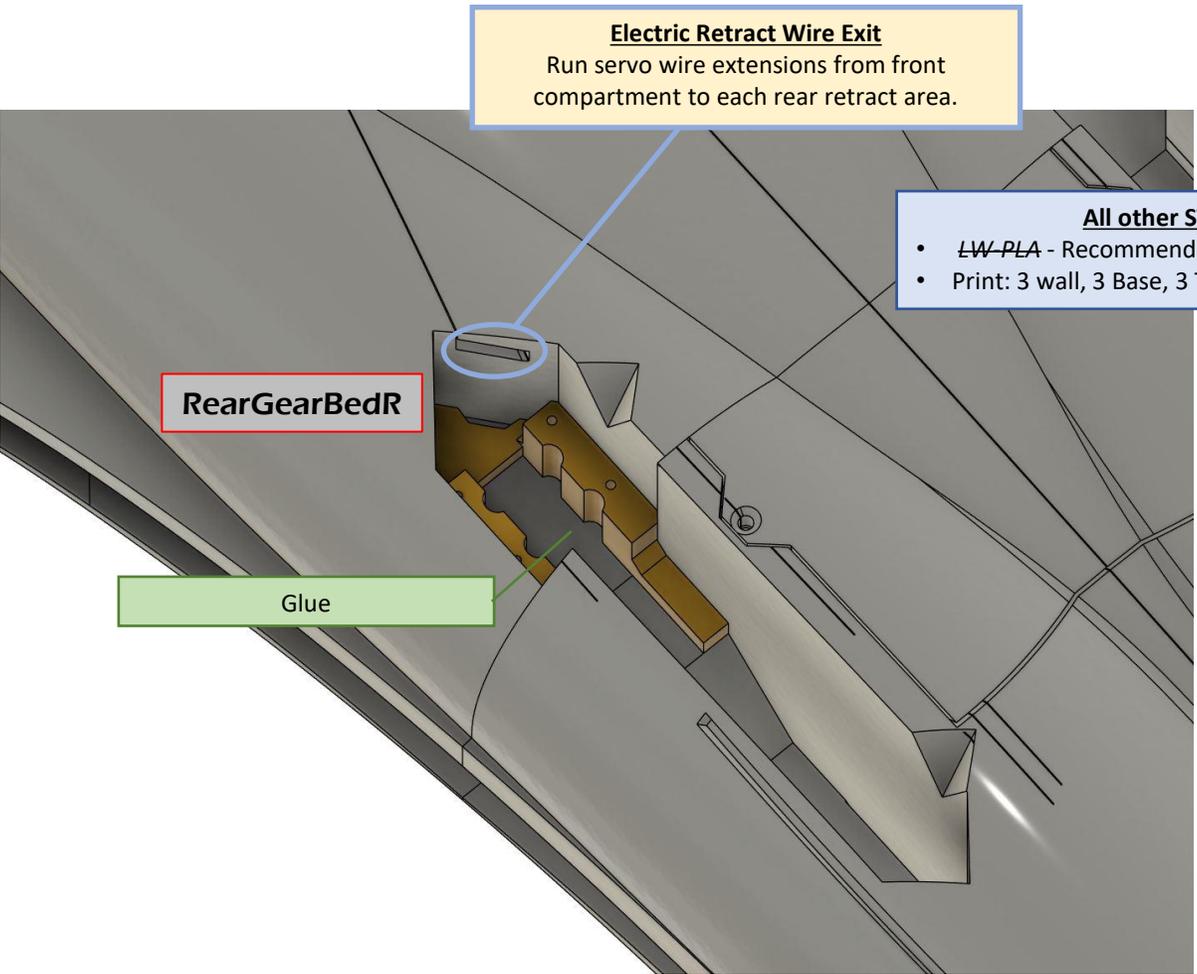
Glue

Nose Door Hinges
 Use 2x Dubro type hinges in each door. Use a scalpel to cut slots into **hollow centre** of fuselage and **hollow centre** of **NoseGearL**. Push hinge with a small amount of glue into slots.

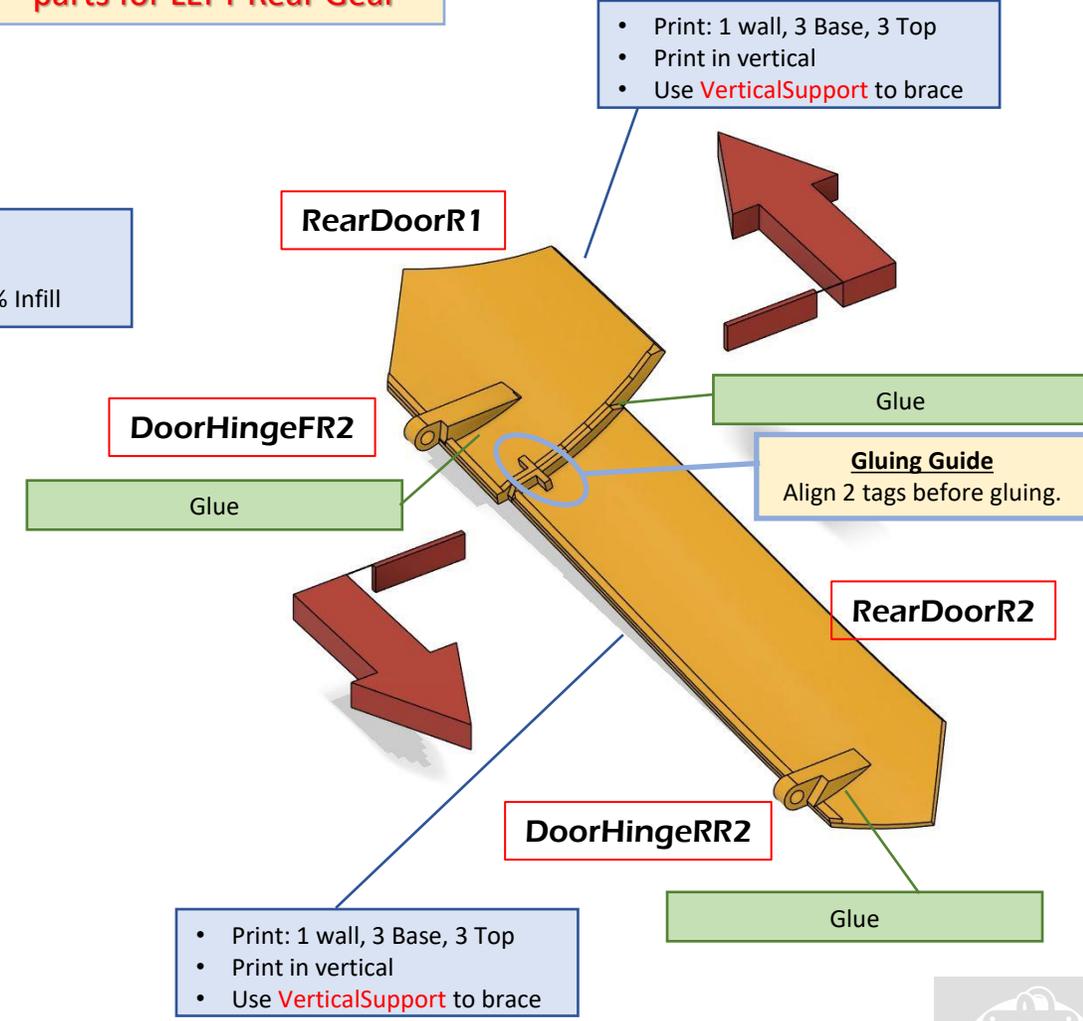
Gear Door Actuation
 The next few pages provide a Undercarriage Door opening and closing solution using only the (low) mechanical "push" energy of the 25gram retracts themselves. This can be difficult to get working and may not be 100% reliable. If you intend to use 6S power and an RX with enough channels, consider using micro-servos to actuate the doors instead.
 Suggest at least start with the Nose Gear Doors as they tend to be the more difficult to set up.



Rear Gear



Mirror & print any "R" parts for LEFT Rear Gear



Rear Gear

How does it work?

OPENING: The rear retract wheel initially pushes the doors open. The retract Spring Wire holds the doors open.

CLOSING: The retract Spring Wire pushing on **RearDoorCloser** to push the doors closed.

All these STLs

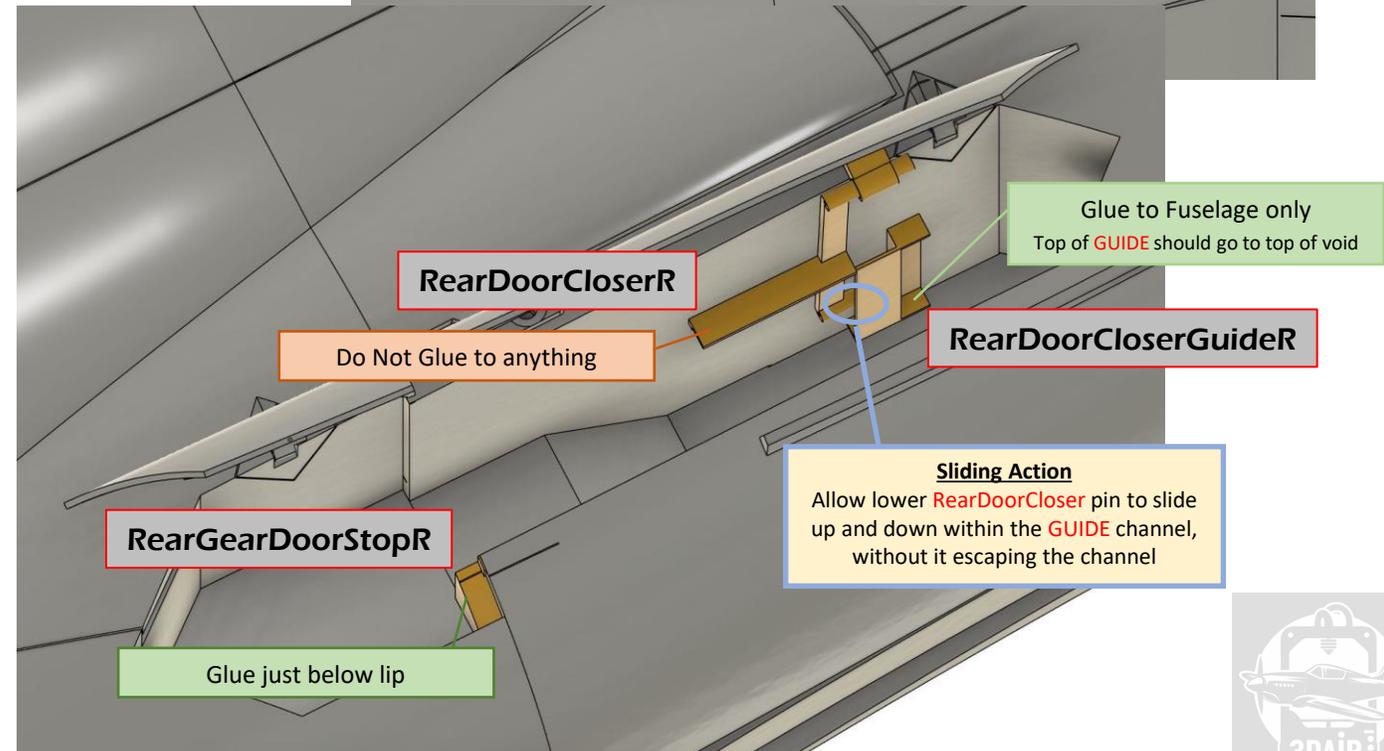
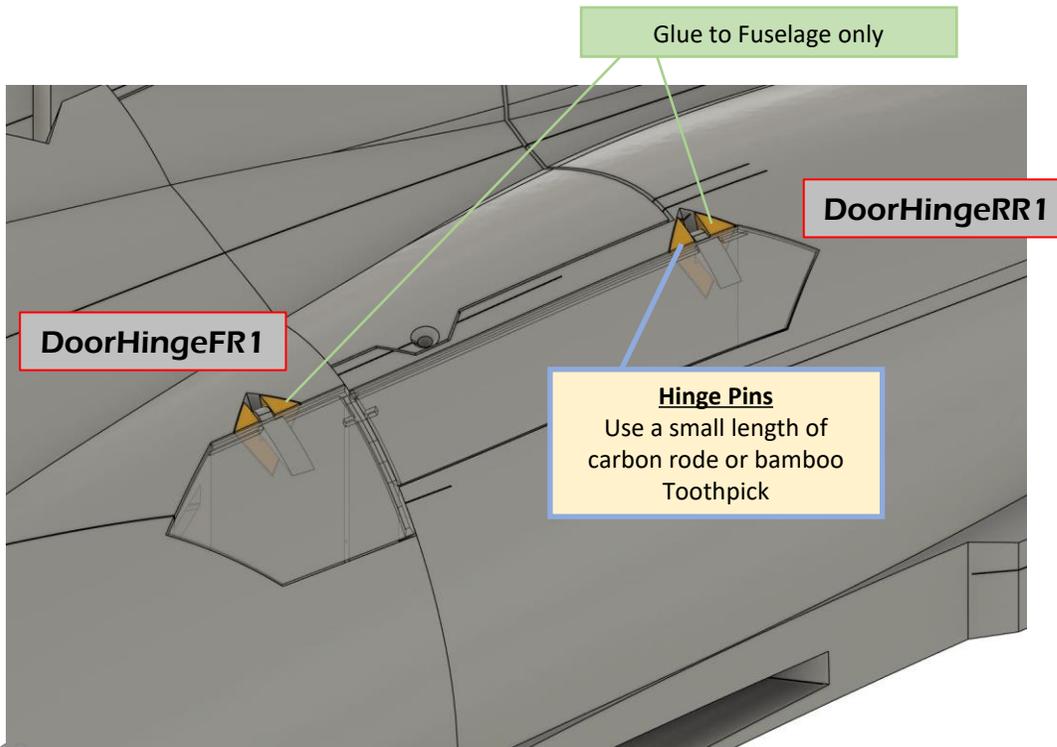
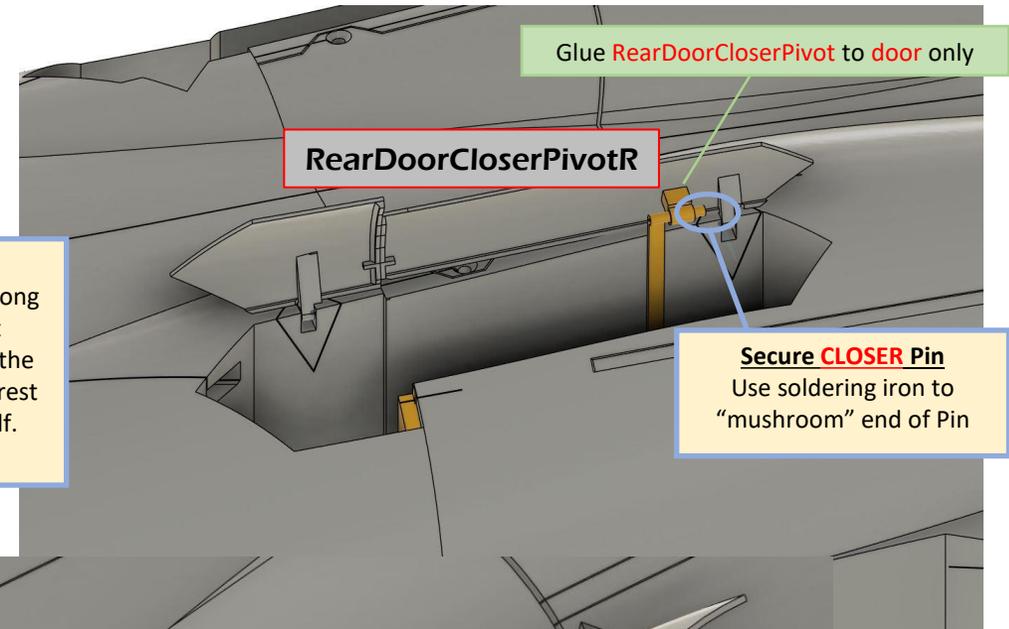
- LW-PLA - Recommend PLA+
- Print: 3 wall, 3 Base, 3 Top, 20% Infill

Mirror & print any "R" parts for Left Rear Gear

Rear Gear Door Open/Closer Arrangements

Overall CLOSER arrangement can be positioned anywhere along the length of the rear gear wheel enclosure, but the best position is lining the horizontal Tab of **RearDoorCloser** with the lowest portion of the retracts Spring Wire, but allowing the rest of the CLOSER hardware to not tangle with the Wheel itself.

RearGearWire provides the Spring Wire template.



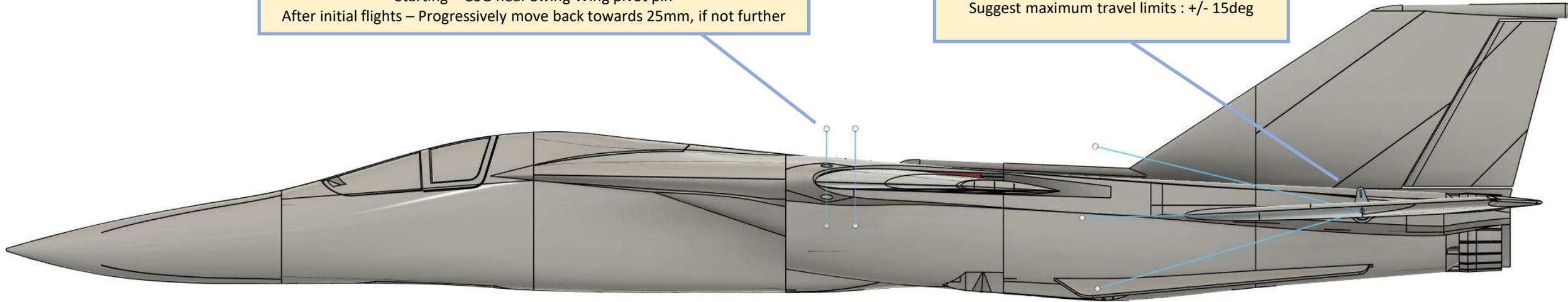
Flight Setup

CoG

With wings swept full forward / trailing edge of wing near perpendicular :
Starting – CoG near Swing Wing pivot pin
After initial flights – Progressively move back towards 25mm, if not further

Elevons

Neutral position : Line leading edge point up
with bottom ledge of the flat fuselage area.
Suggest maximum travel limits : +/- 15deg



Swing Wing Considerations

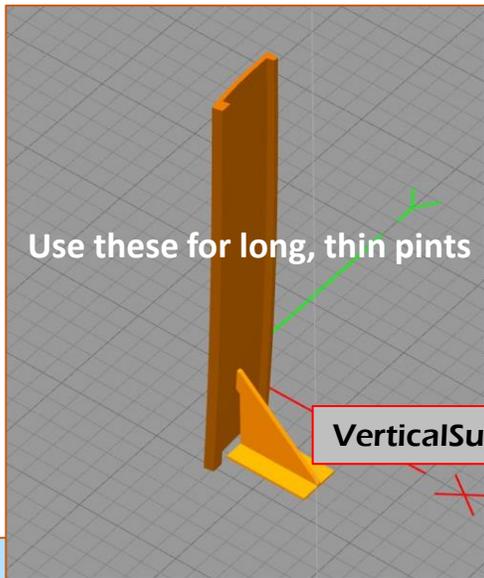
Not a lot of test time was spent with the wing swept, but these elements should be considered;

- Recommend don't start playing with Swept Wings in your first flights!
 - Un-Swept : Use a few flights to get comfortable with the right CoG
- As the wings are swept, the Centre of Lift moves rearward / model acts Nose-Heavy
- More Up-Elevator needs to be added. Try use your TX setup to do this automatically
 - The Roll-Rate increase. Try use your TX setup to reduce roll travel automatically
- Double check that any automatic setup work *TOGETHER* to provide reasonable Elevon travel in any direction
 - Depending on your EDF, model speed may not increase all that much (*For the LOOKS ONLY!* :D)
- If you have too much friction in your Swing Servo setup, air resistance may not allow wing to swing forward. If this happens try gaining altitude and do a quick pitch-over to remove upward forces on the wing underside
 - For obvious reasons trying to landing with wings swept is not recommended

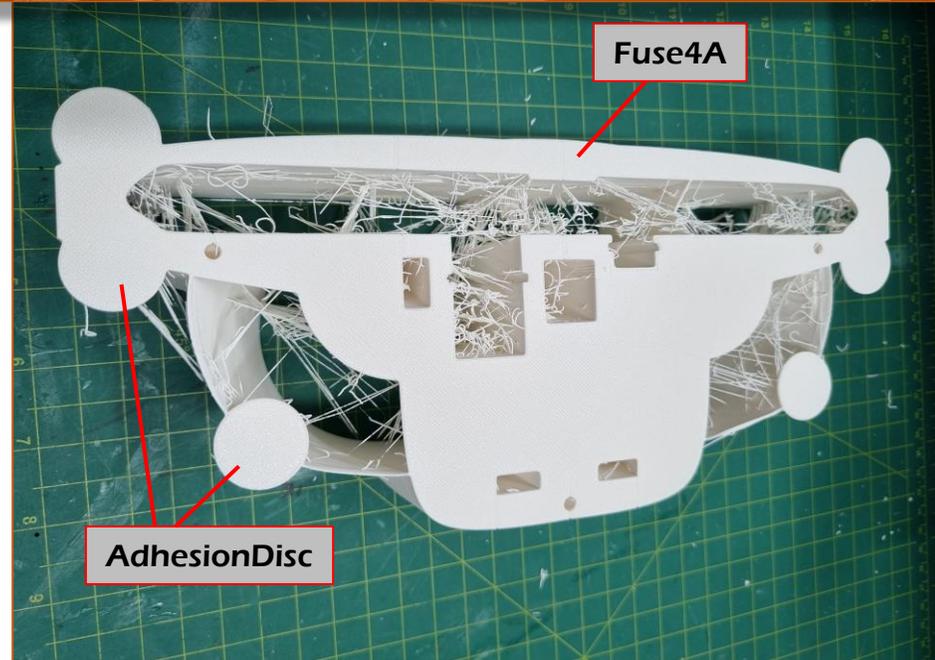
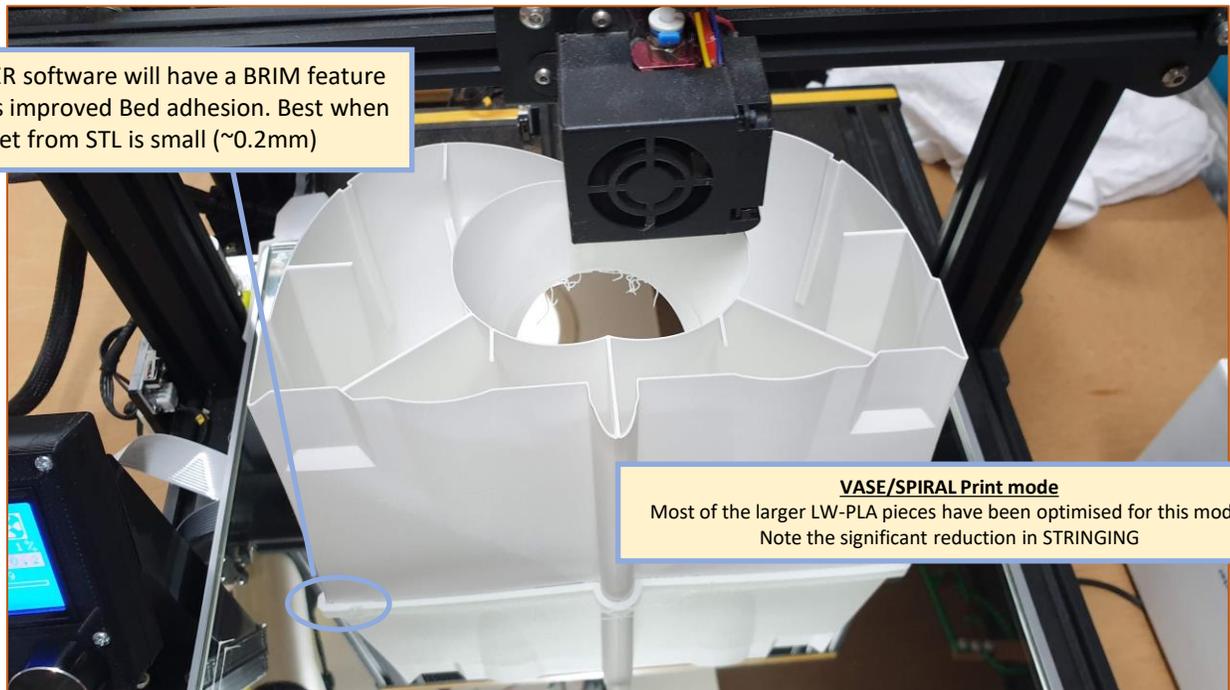


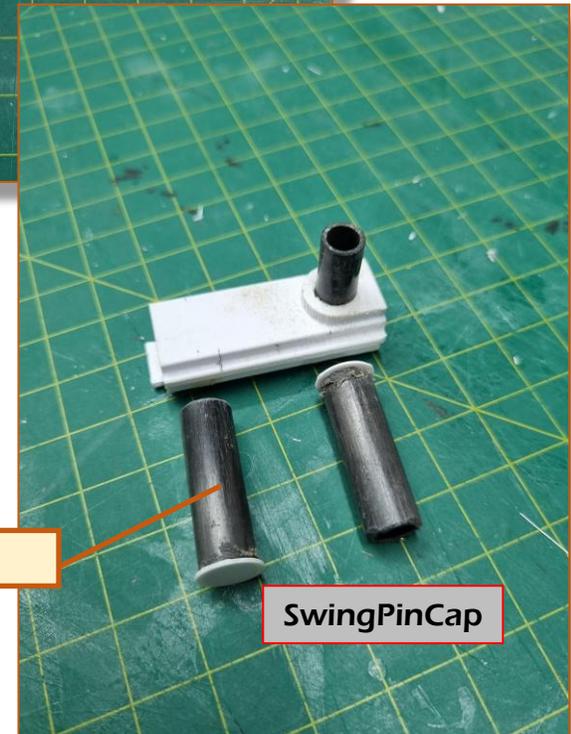
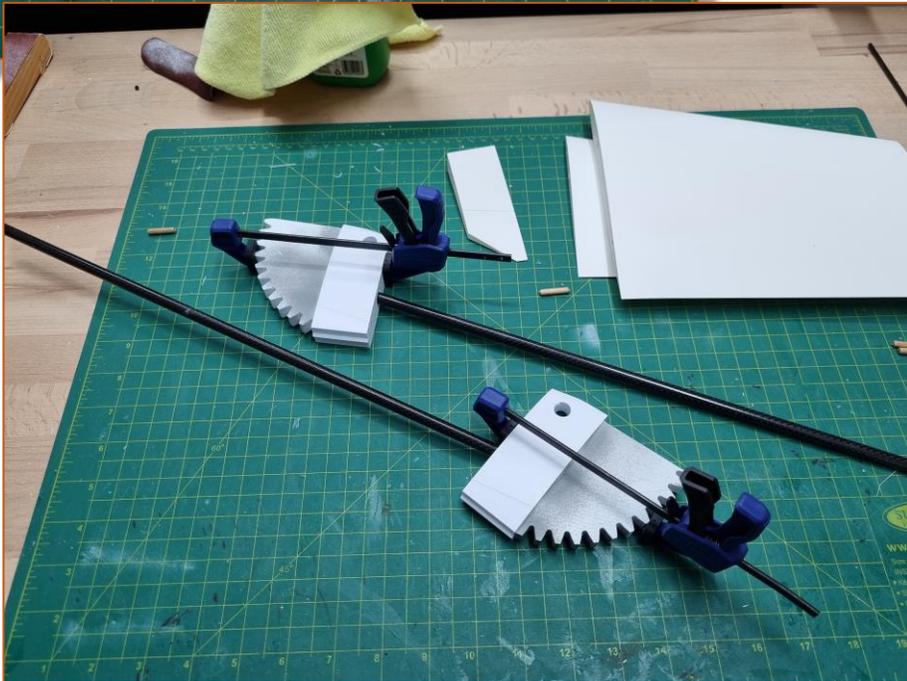
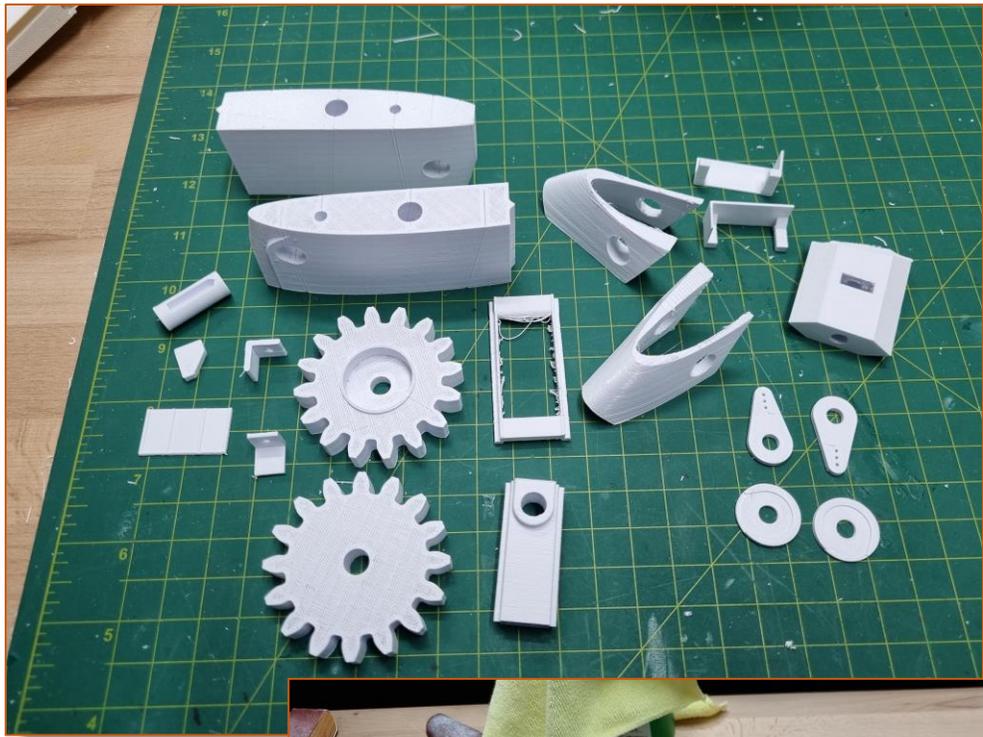
PHOTOS





Your SLICER software will have a BRIM feature that allows improved Bed adhesion. Best when offset from STL is small (~0.2mm)

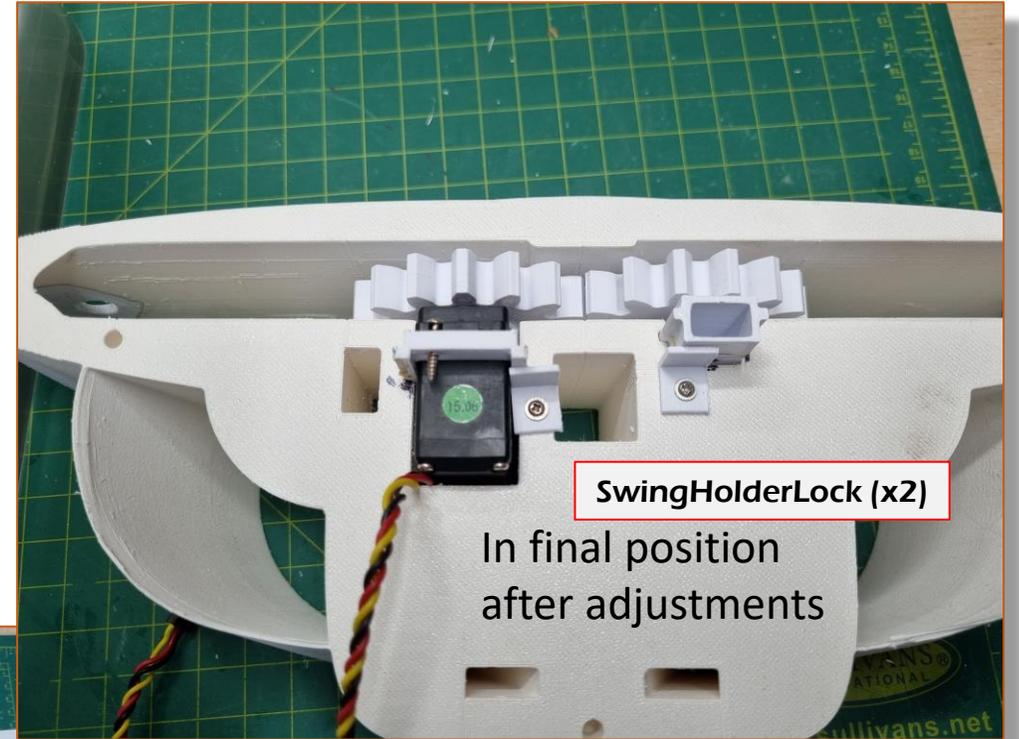
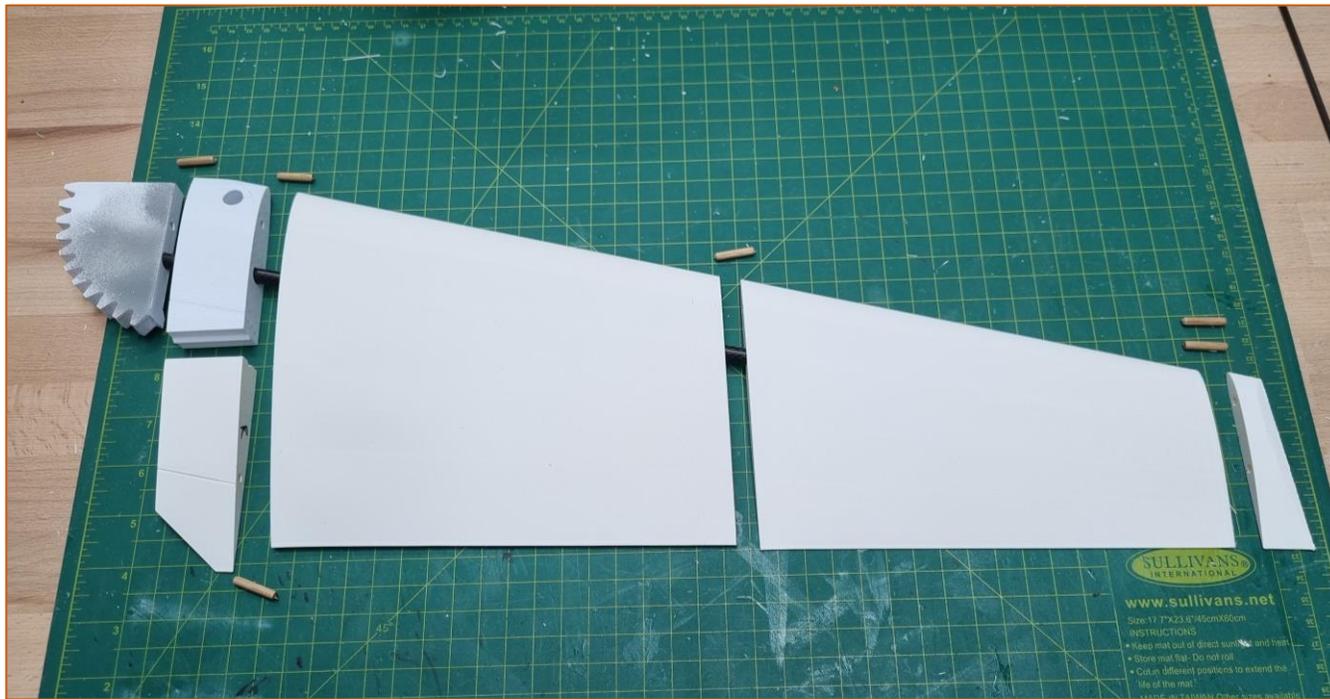




Main Swing Wing Pins

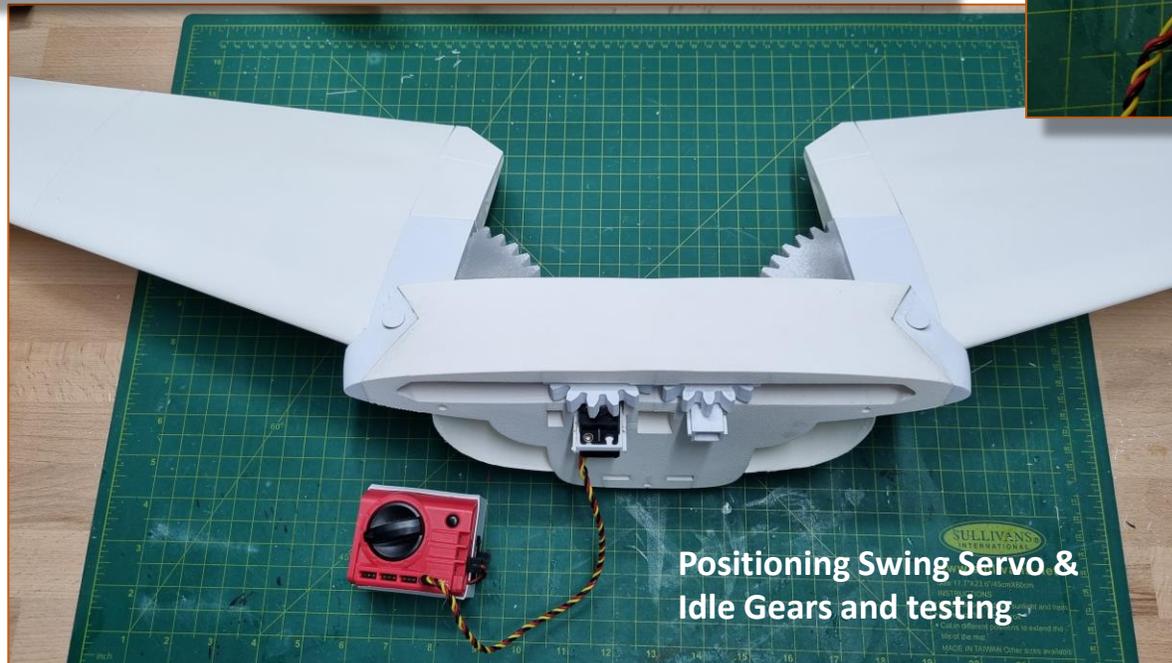
SwingPinCap



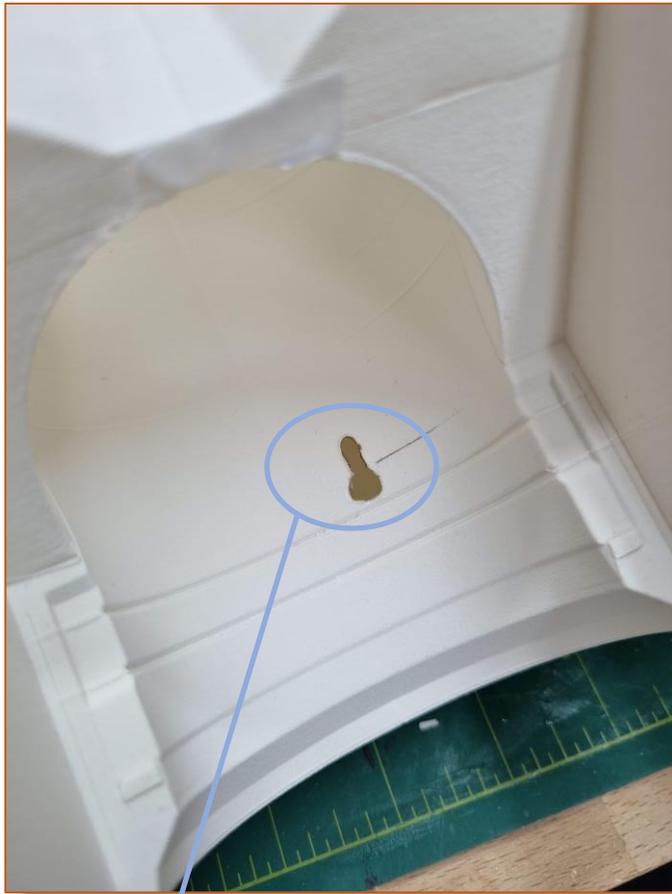


SwingHolderLock (x2)

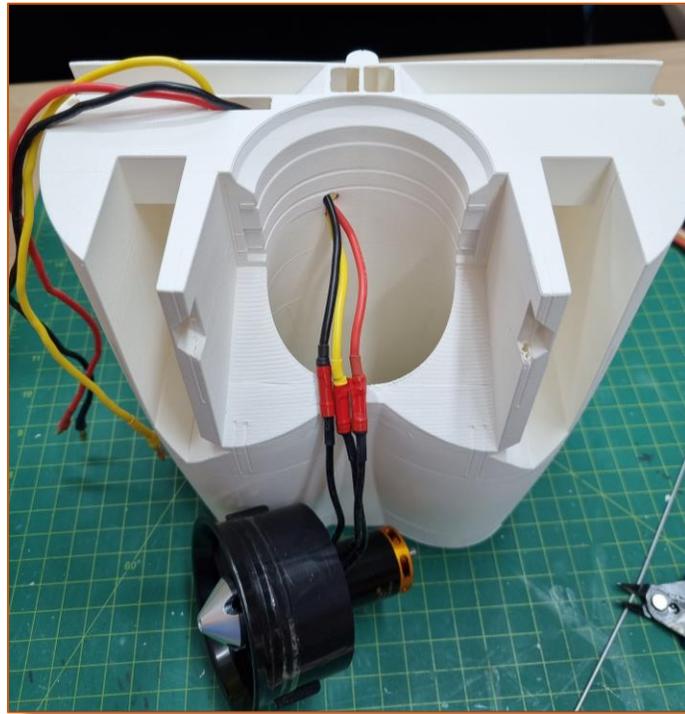
In final position after adjustments



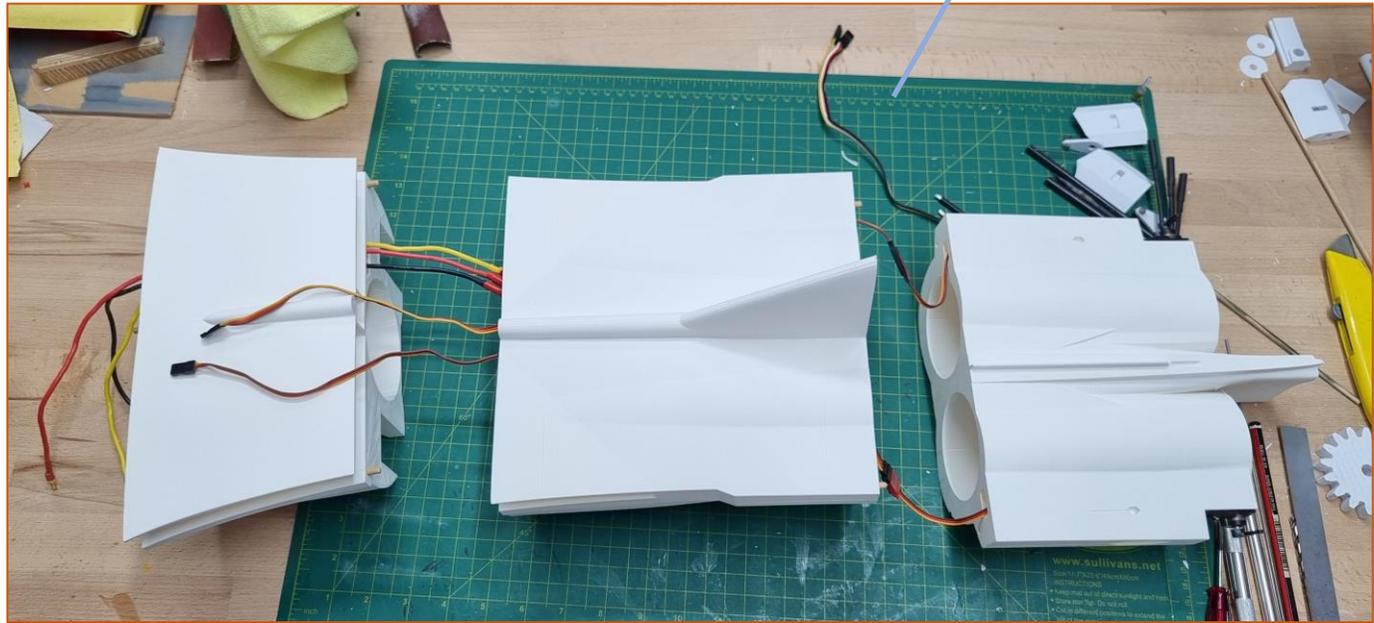
Positioning Swing Servo & Idle Gears and testing

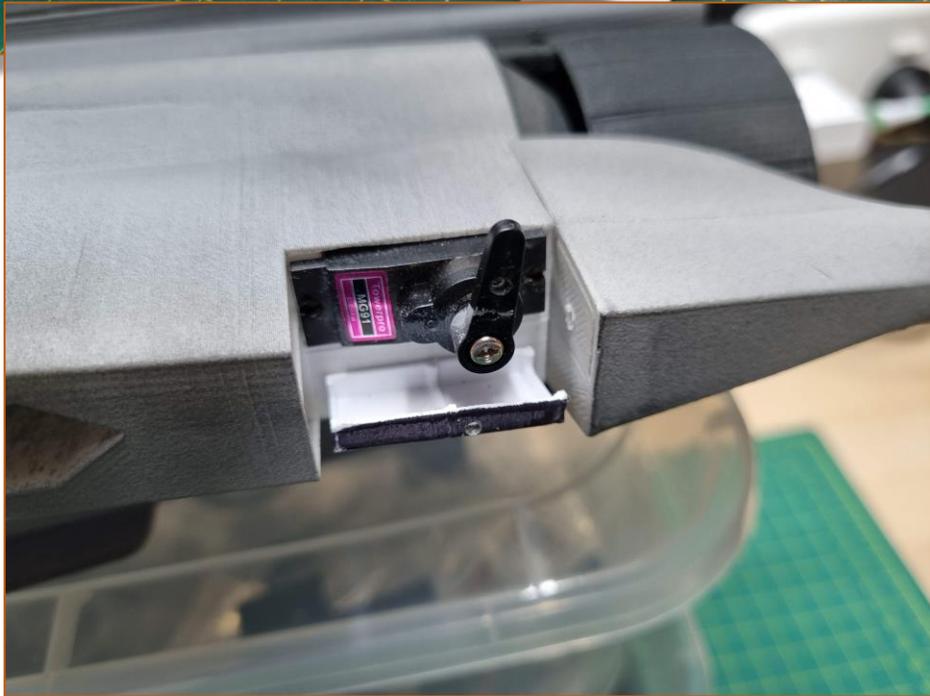
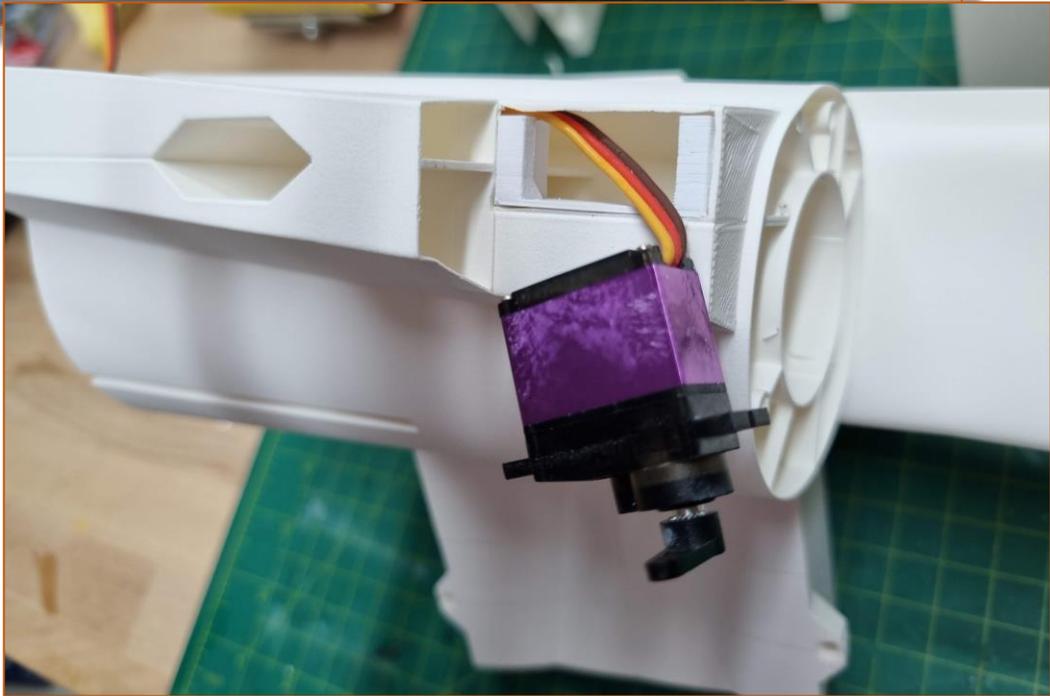
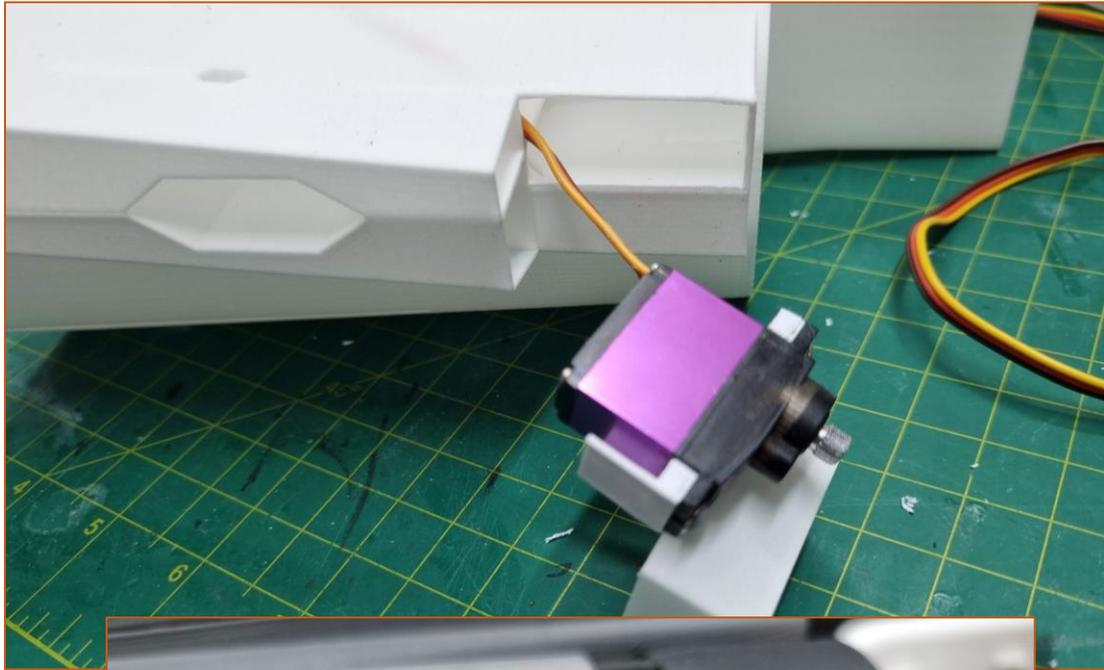
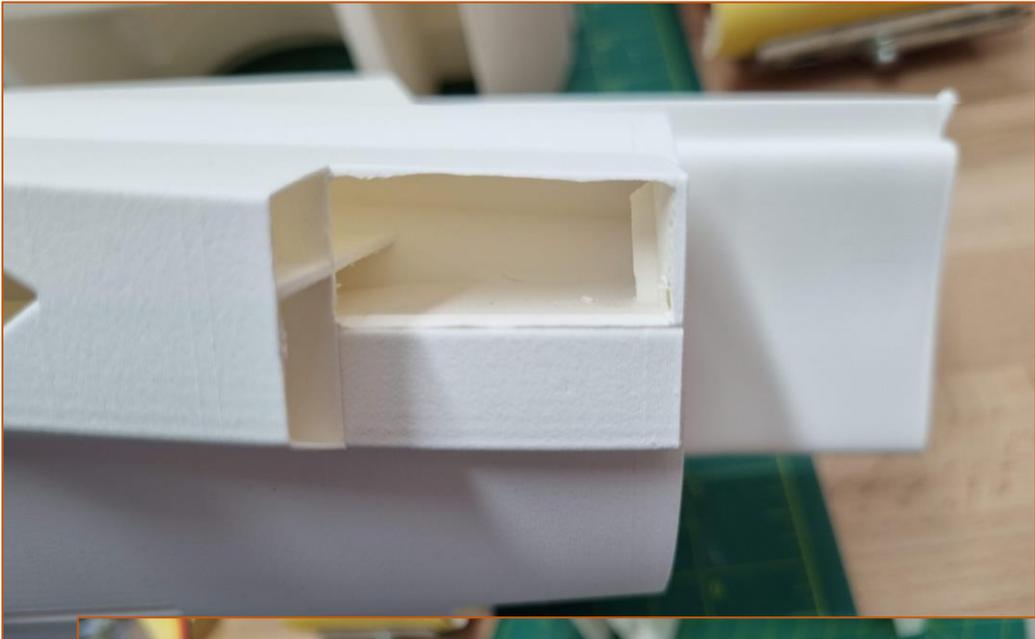


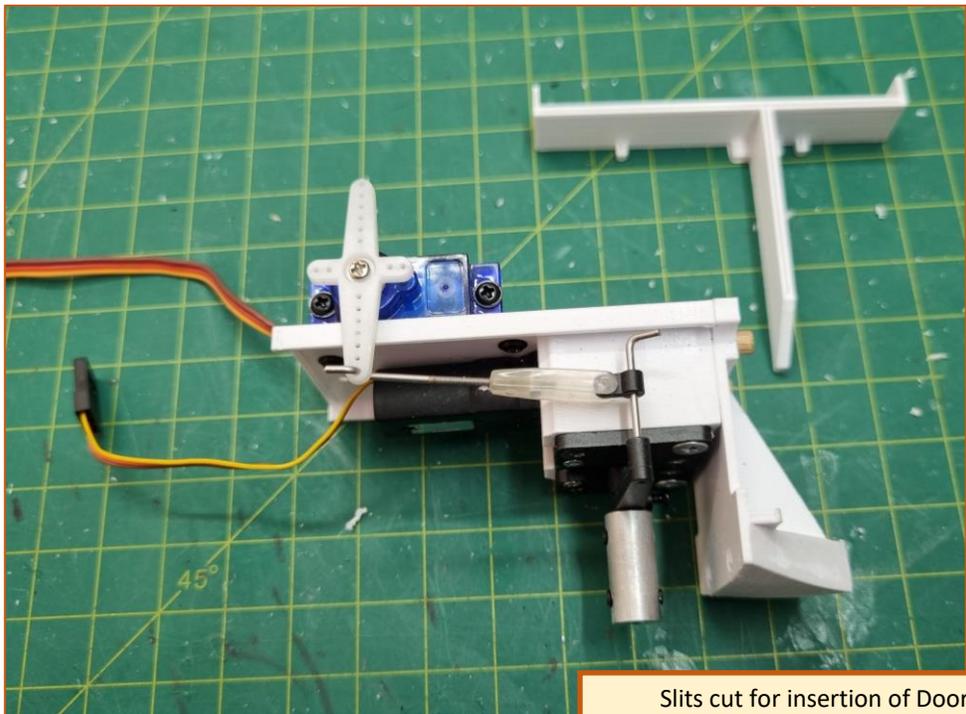
Using a soldering Iron, cut holes just rearward of the fan EDF structure, only just large enough to first Feed the motor leads, then hold the motor leads



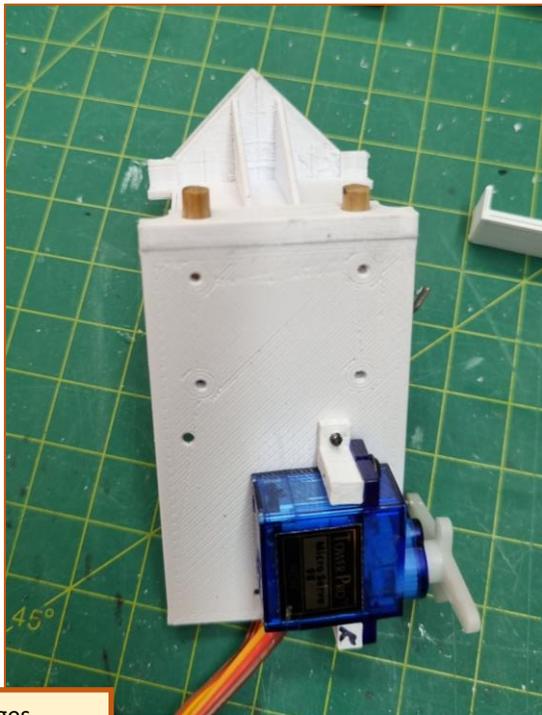
Mount Elevon servos, add extension leads and install EDF unit with motor leads before gluing Fuse6, Fuse5, Fuse4B & Fuse4A together







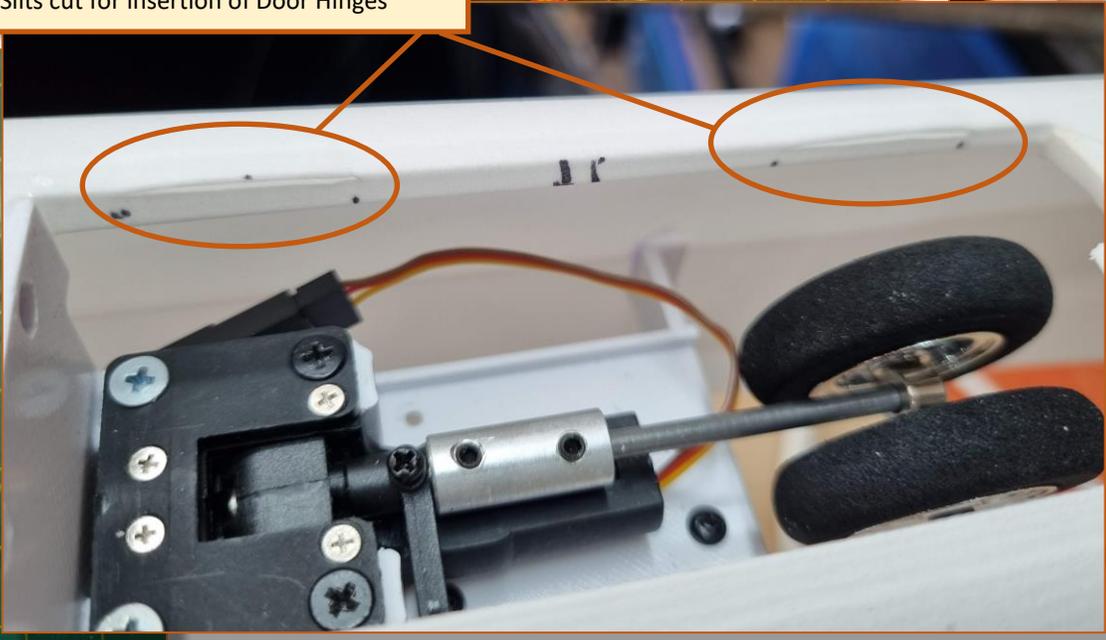
Slits cut for insertion of Door Hinges

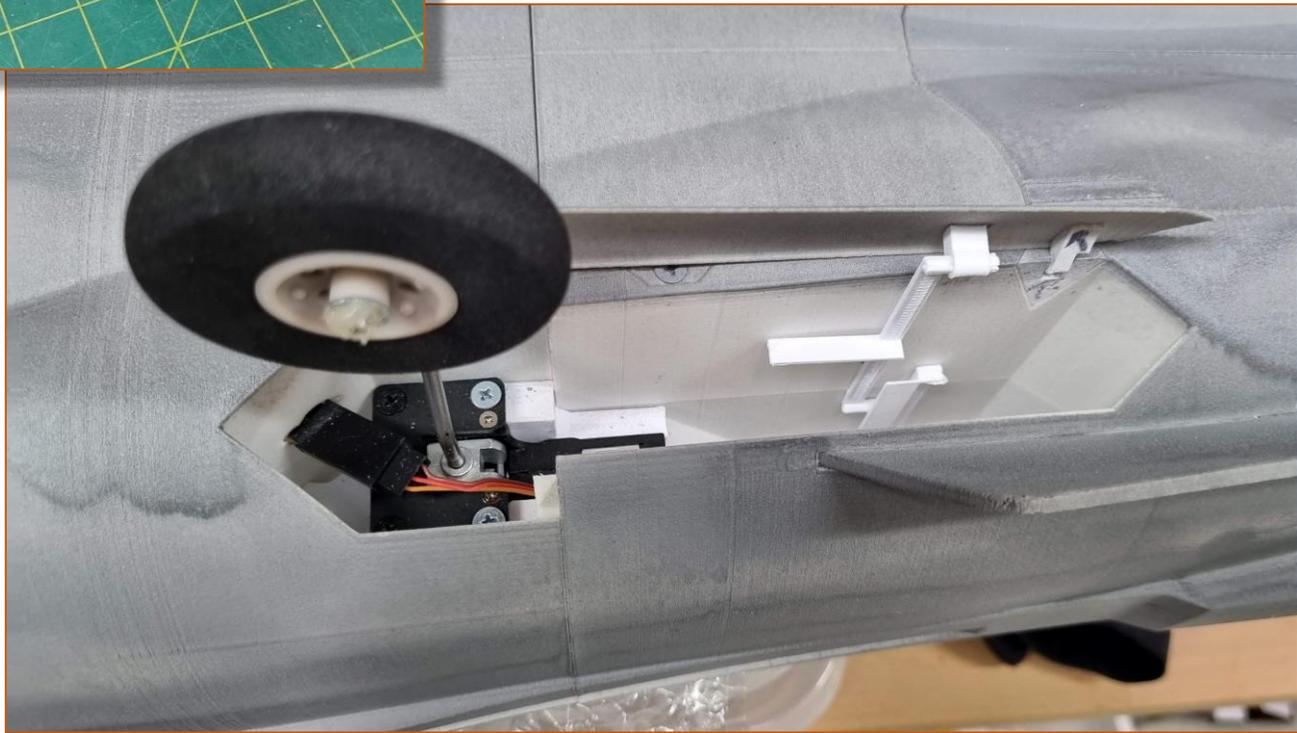
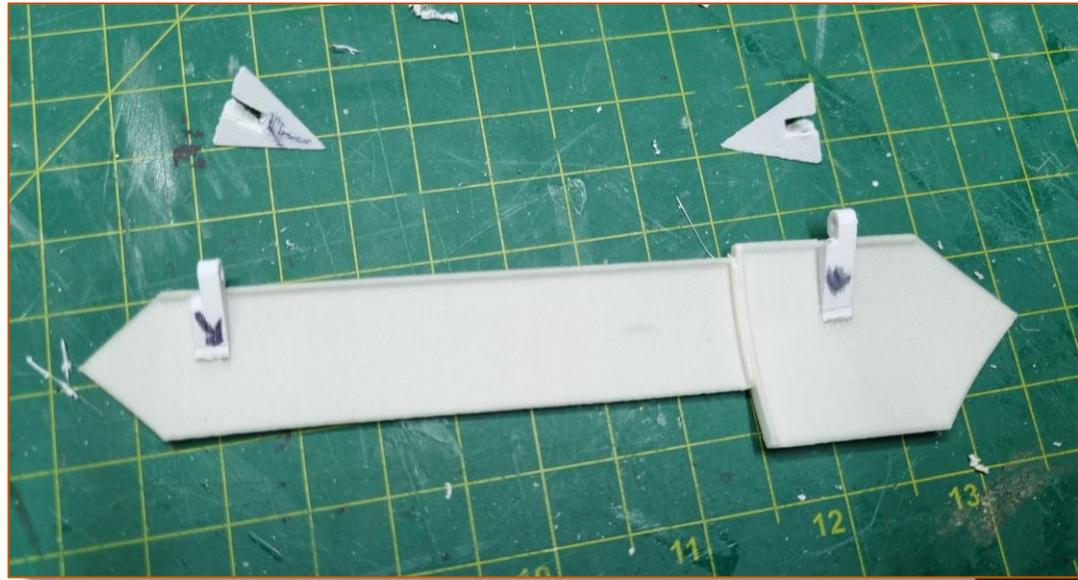
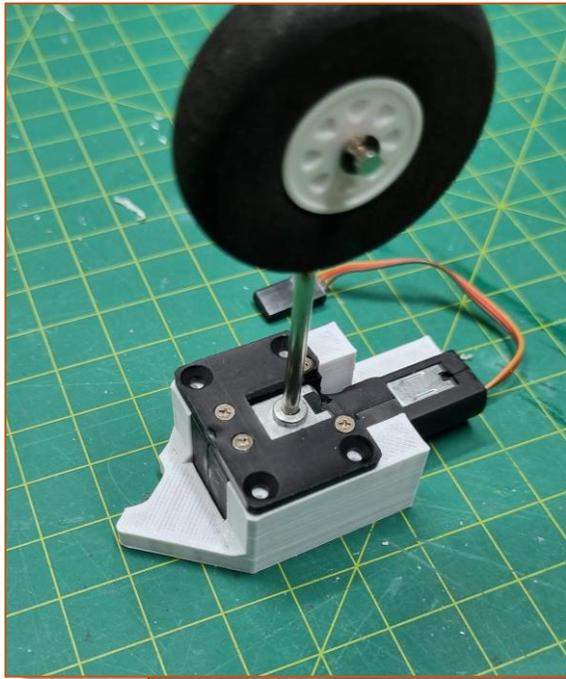


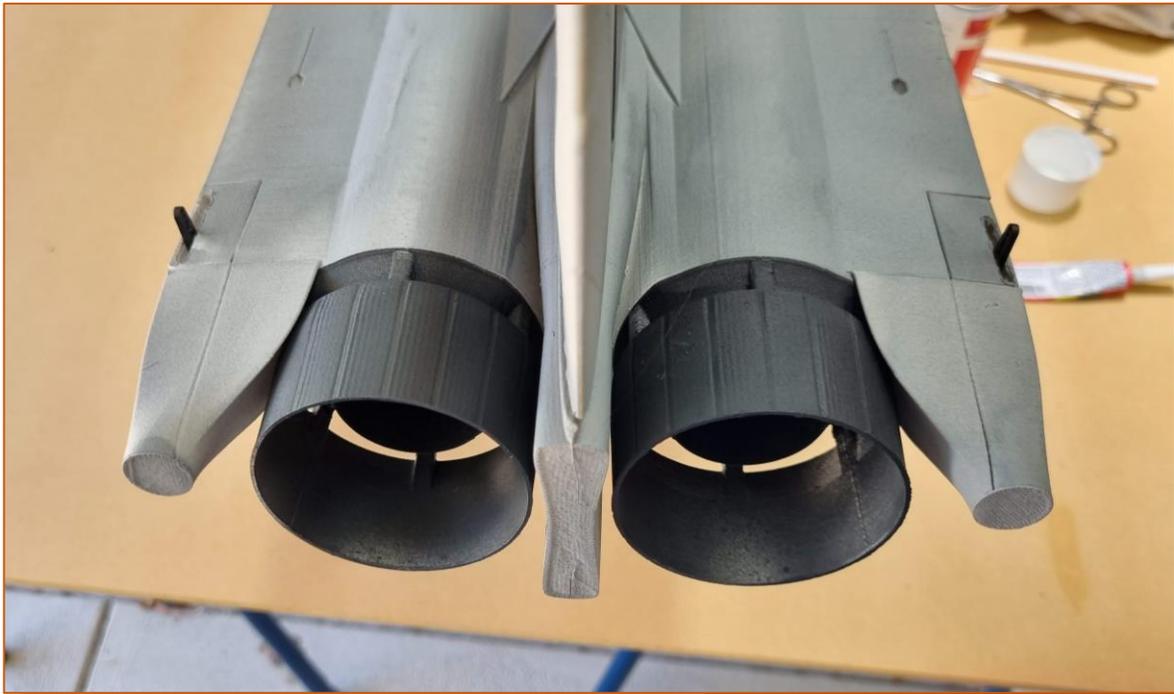
To hold Hinges in place:
Drill 1.5mm hole through Fuselage & plastic Hinge. Feed raw print filament through, glue, then snip off after dry. Do same for Doors



Double screwed Collar used to make nose wheel







MrWaz11 - YouTube

